

# Geometry in feature detection, matching, search, and clustering

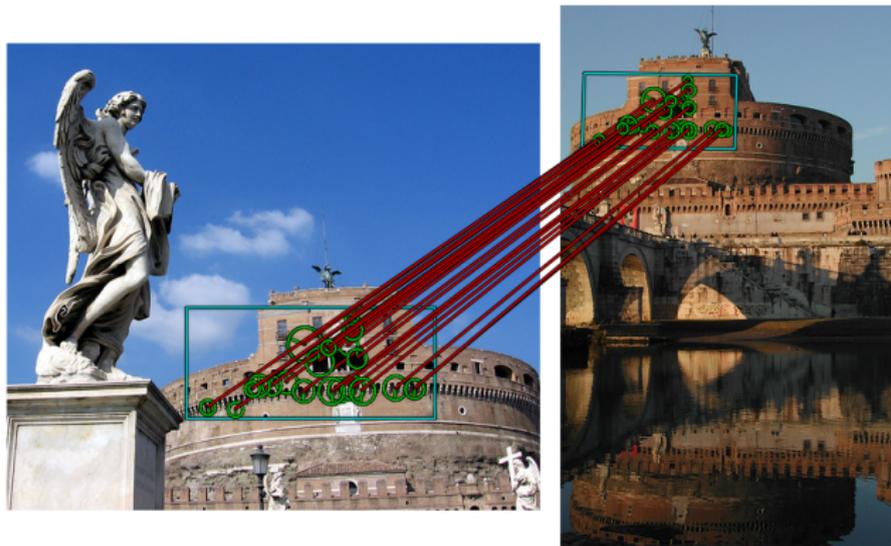
Yannis Avrithis

Philadelphia, June 2015

# motivation: visual search



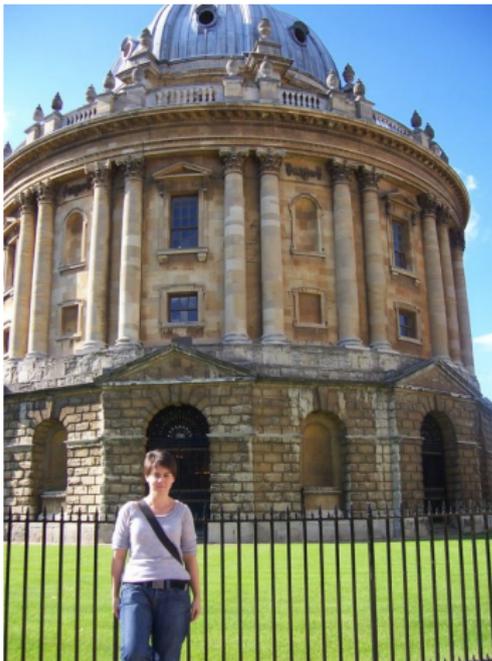
# challenges



- viewpoint
- lighting
- occlusion
- large scale

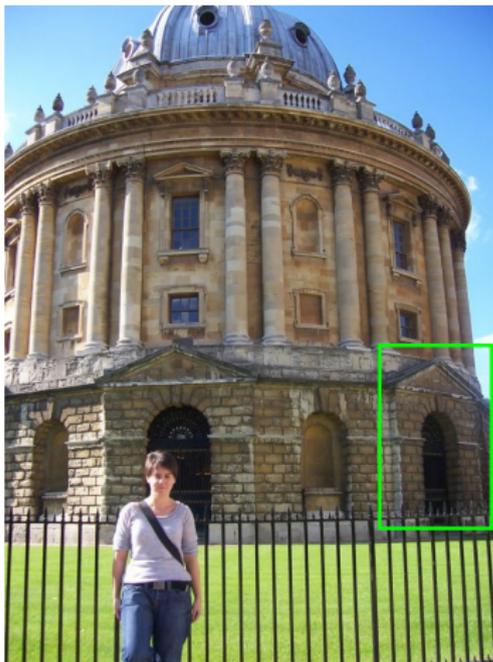
# discriminative local features

[Lowe, ICCV 1999]

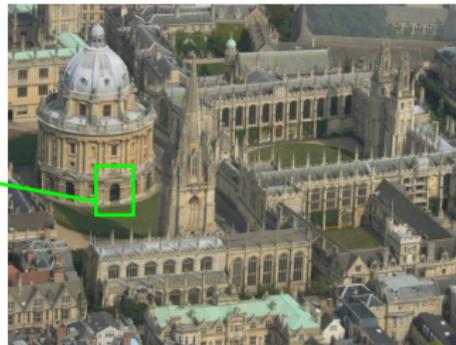


# discriminative local features

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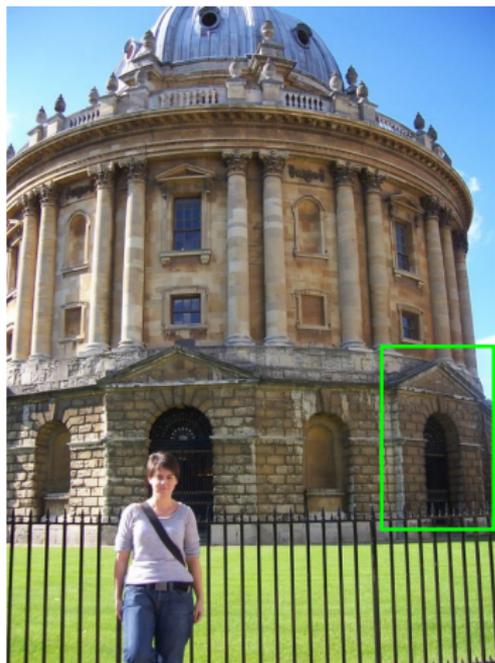


features

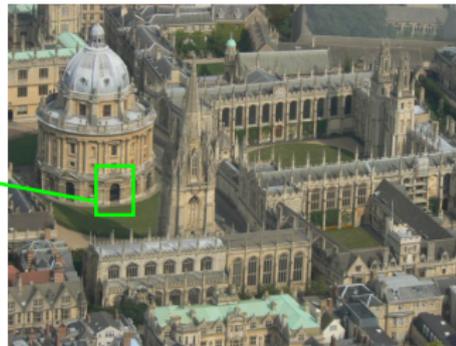
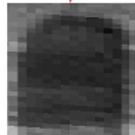
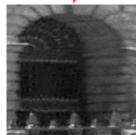


# discriminative local features

[Lowe, ICCV 1999]

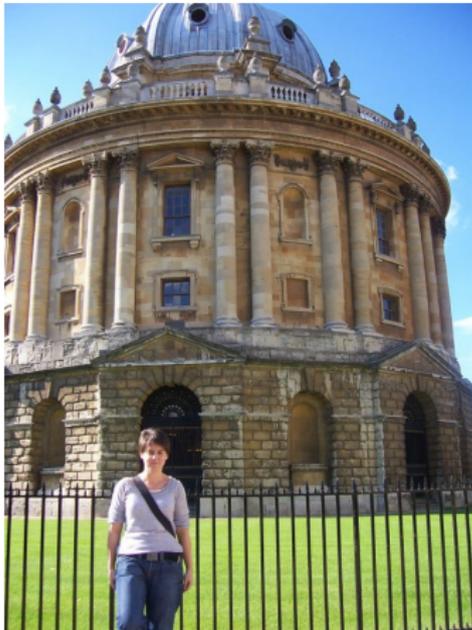


features



normalized features

# descriptor matching

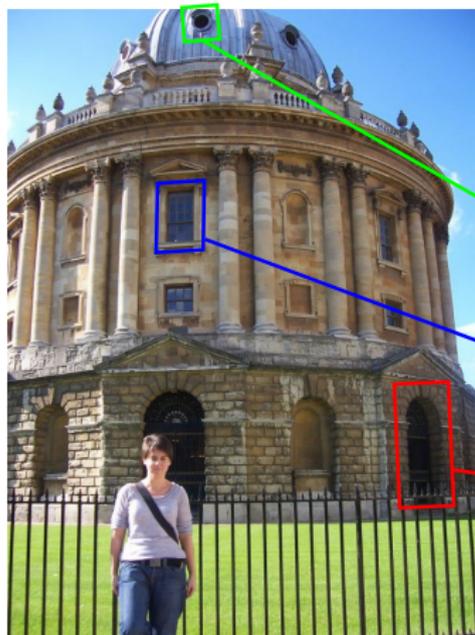


query

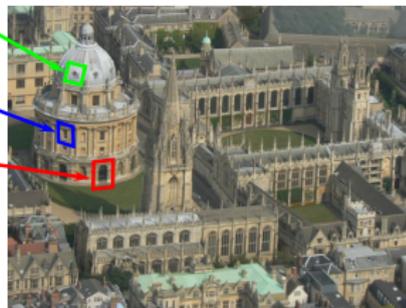


15

# descriptor matching

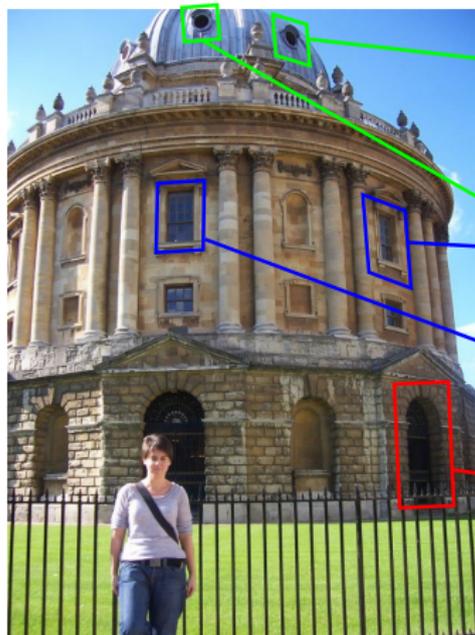


query



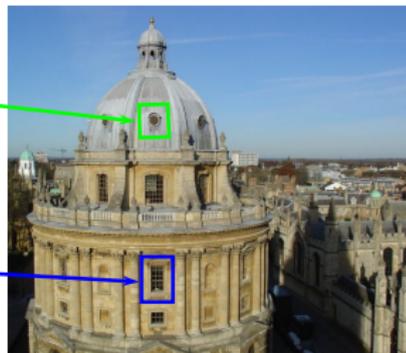
15

# descriptor matching

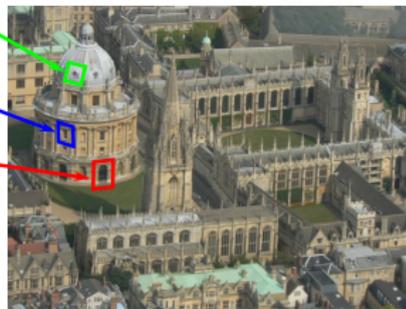


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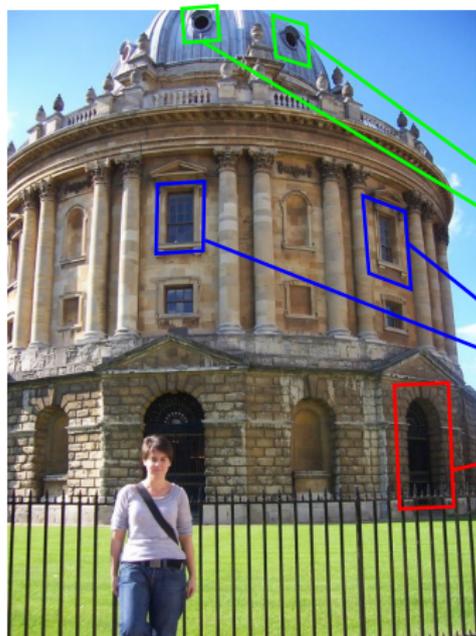
19



15

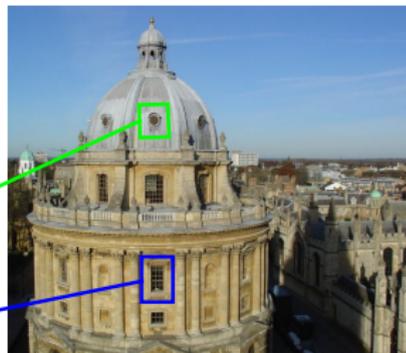


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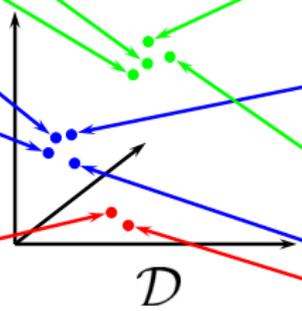
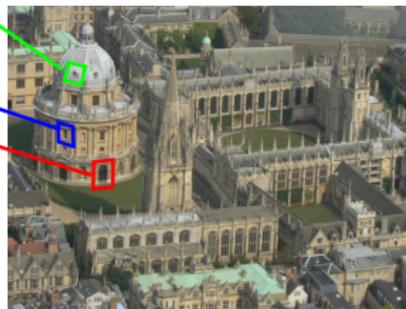


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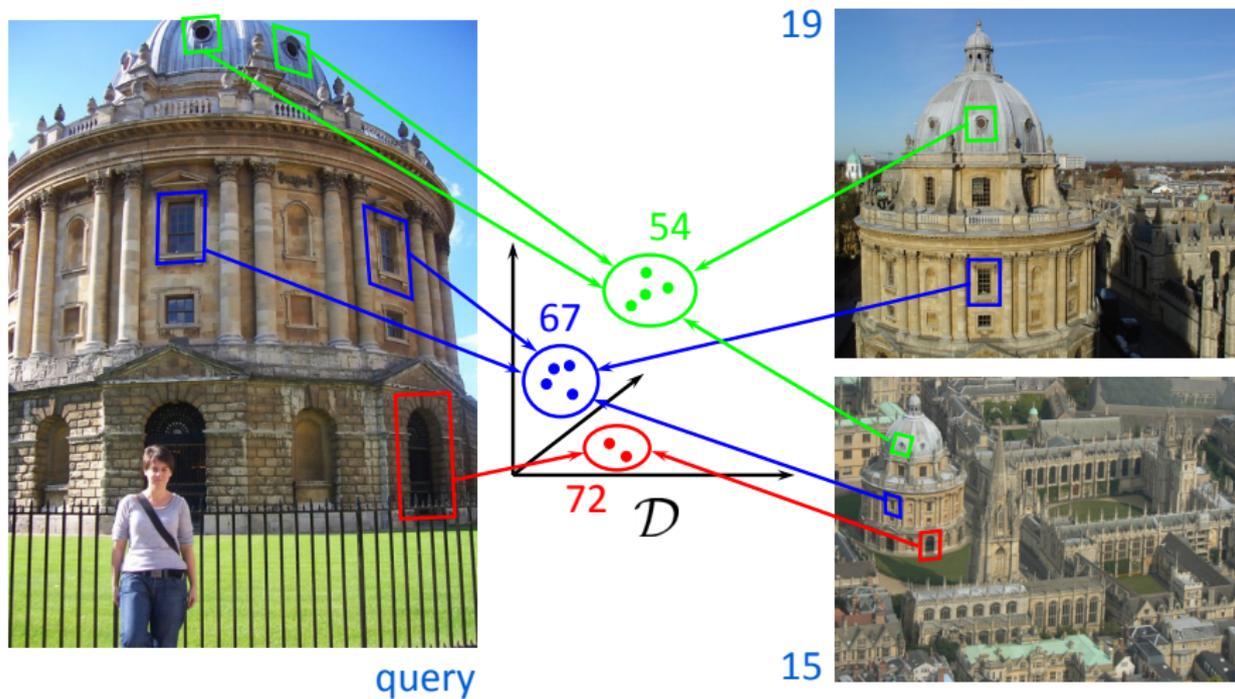


15



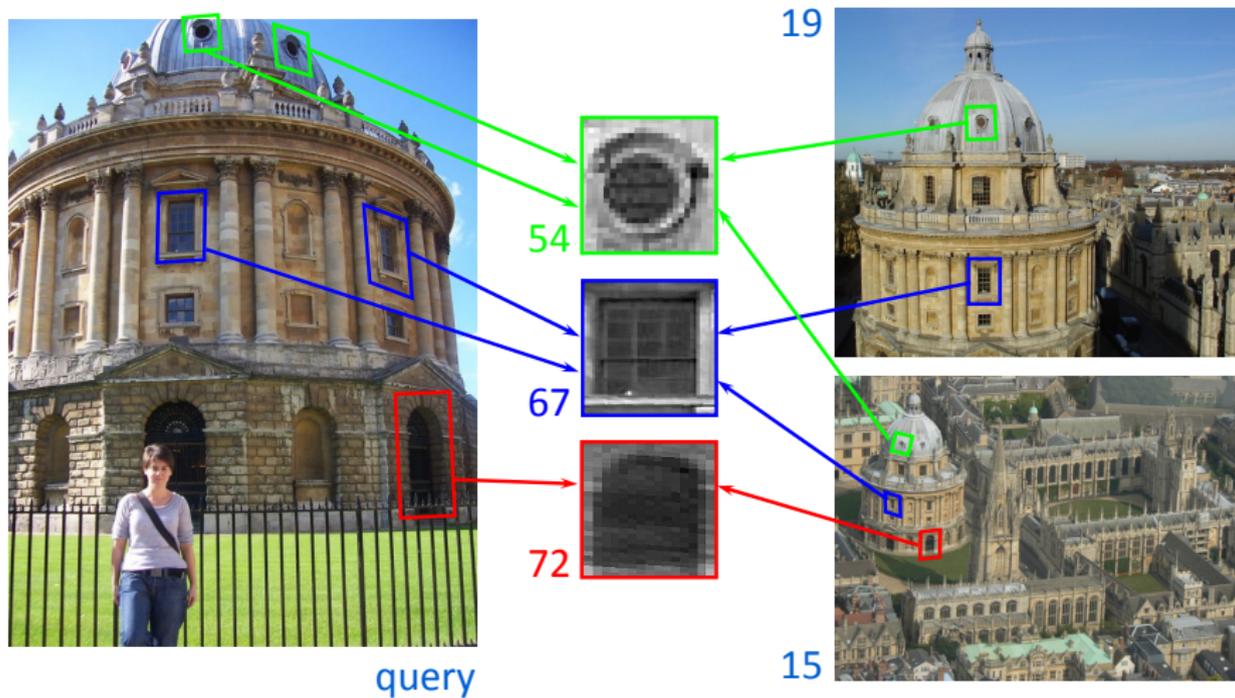
# vector quantization $\rightarrow$ visual words

[Sivic and Zisserman, ICCV 2003]



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[Sivic and Zisserman, ICCV 2003]

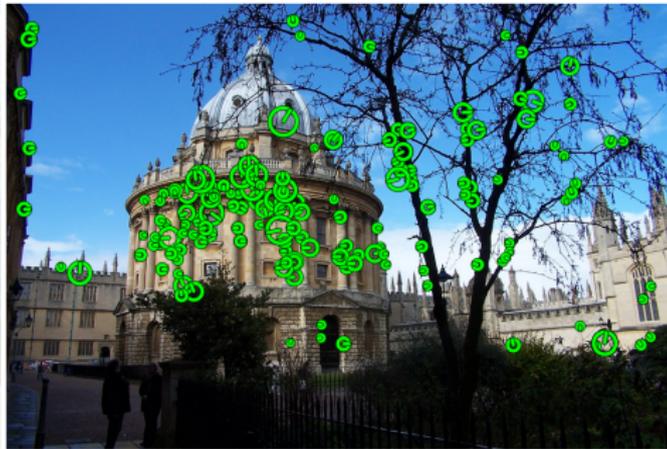
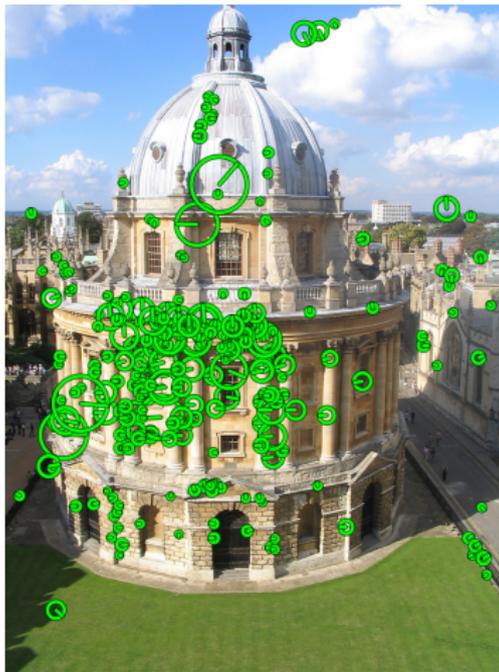


# spatial matching



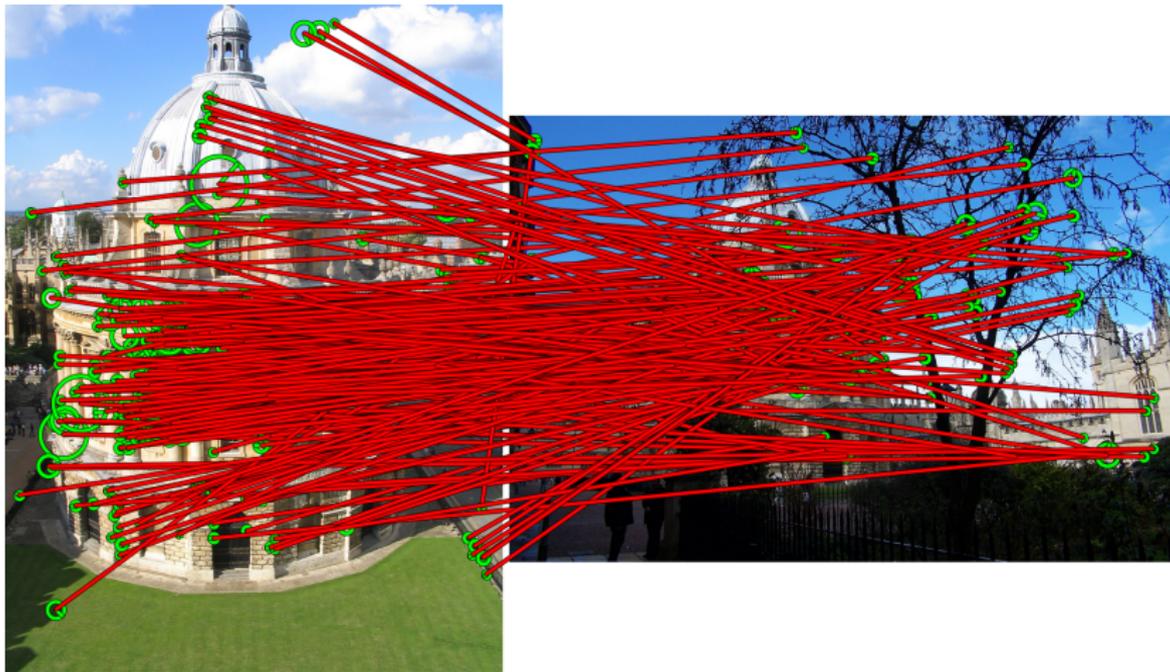
original images

# spatial matching



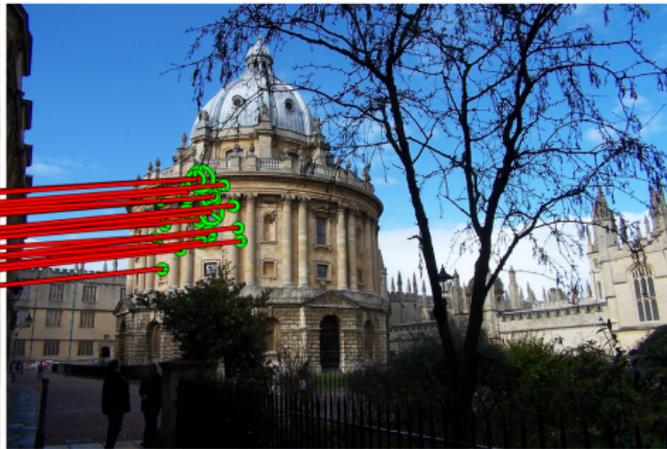
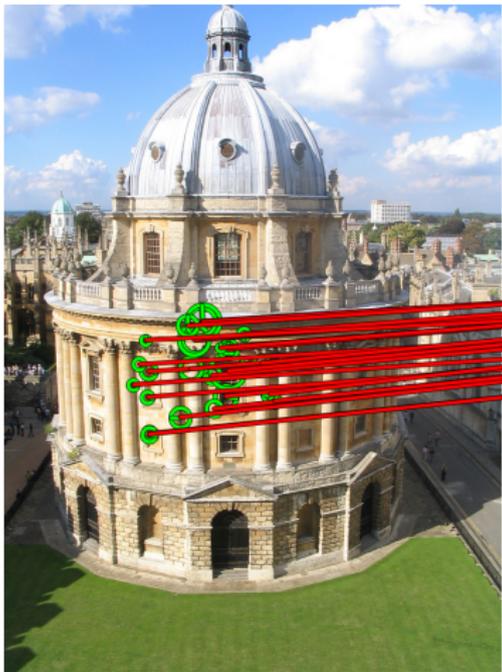
local features

# spatial matching



tentative correspondences

# spatial matching



inliers

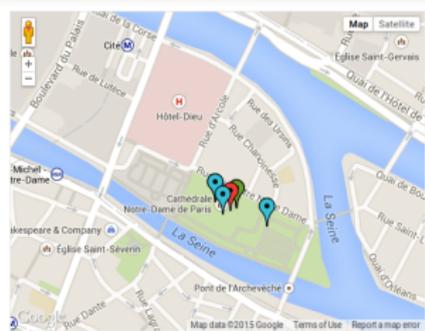
# applications

instance recognition [Kalantidis et al. 2011]

viralImage.ntua.gr/?query&id=1025986

## Visual Image Retrieval and Localization

Home Cities Upload Explore Routes Mobile About Search...



Estimated Location, Similar Image, Incorrectly geo-tagged, Unavailable



**Suggested tags:** Point Notre-Dame, Paris  
**Frequent user tags:** eiffel tower, louvre paris, notre dame, eiffel

### Similar Images



# applications

class recognition [Boiman et al. 2008]

query  
image  
 $Q$



$$KL(p_Q | p_C) = 8.35$$



$$KL(p_Q | p_1) = 17.54$$



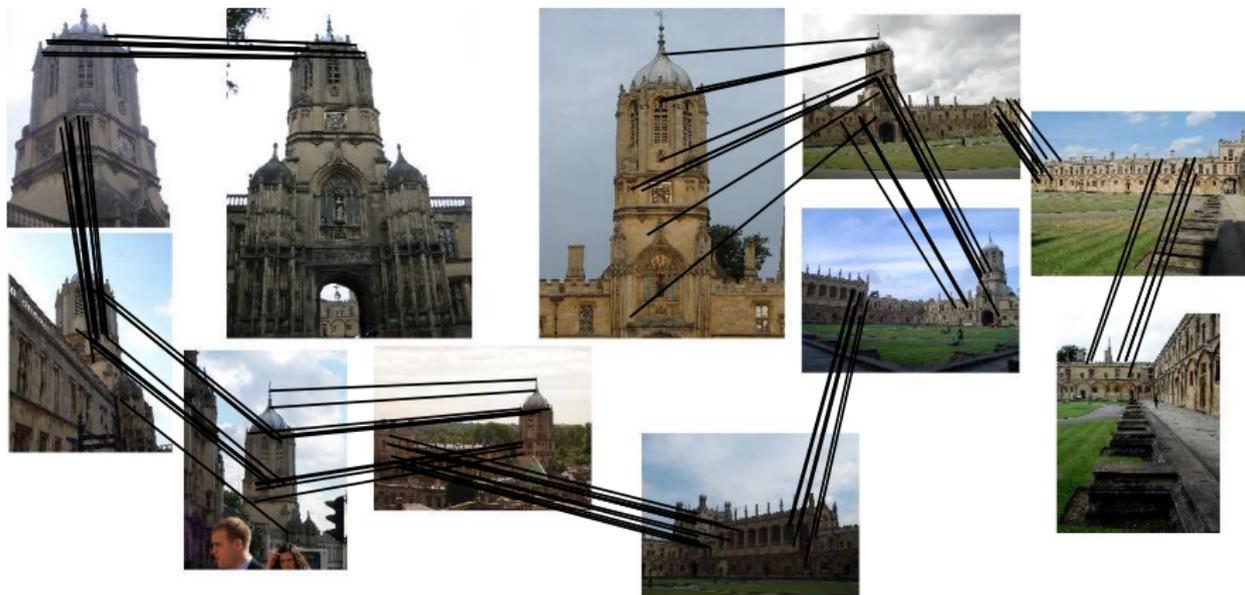
$$KL(p_Q | p_2) = 18.20$$



$$KL(p_Q | p_3) = 14.56$$

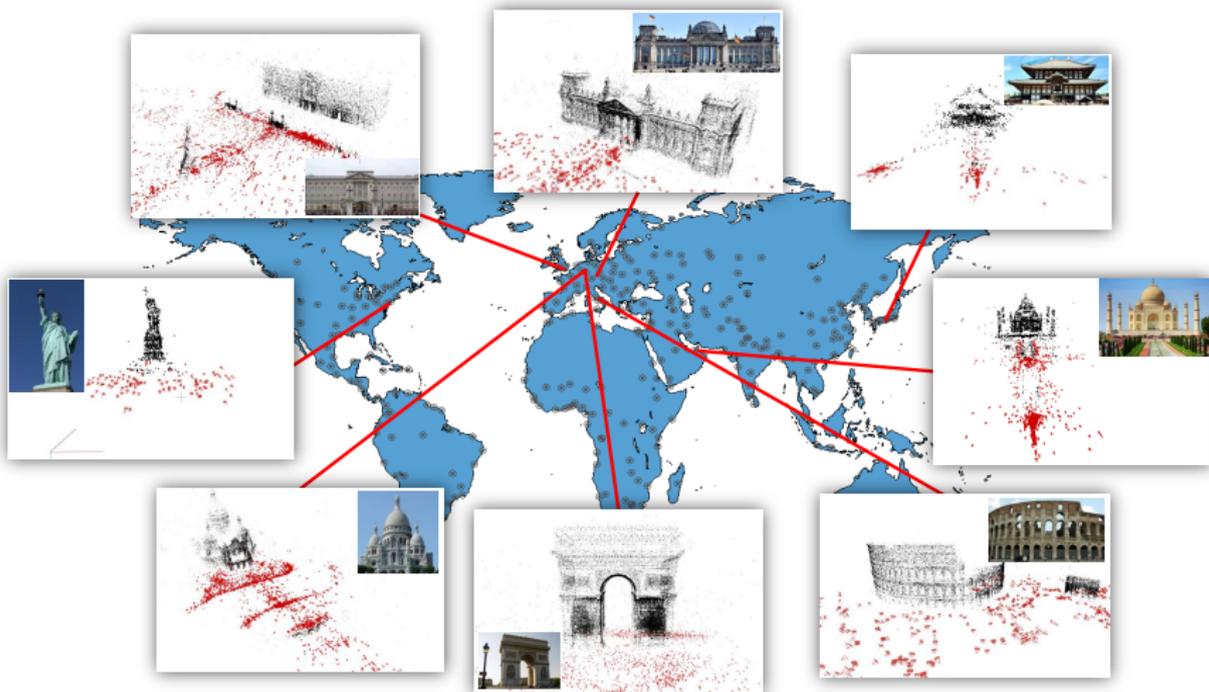
# applications

object mining [Chum & Matas 2008]



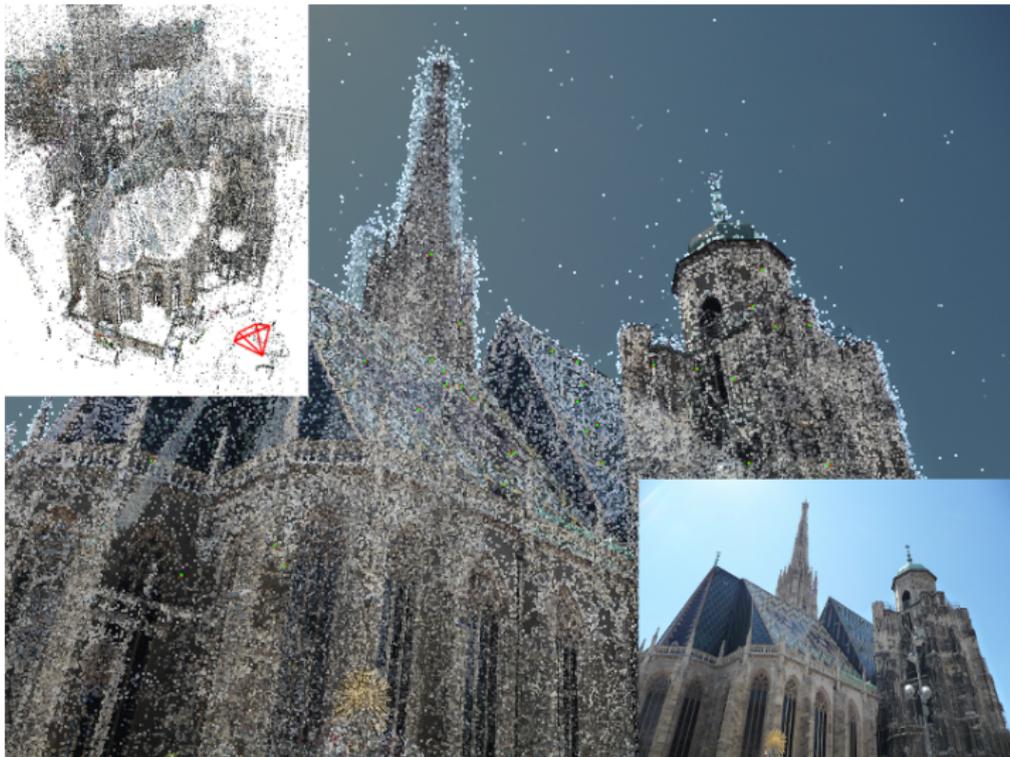
# applications

reconstruction [Heinly et al. 2015]



# applications

pose estimation [Sattler et al. 2012]

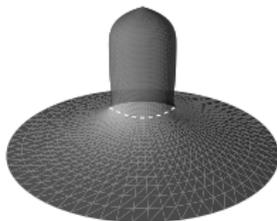
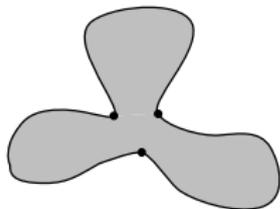


# overview

- planar shape decomposition
- local feature detection
- feature geometry & spatial matching
- descriptors, kernels & embeddings
- nearest neighbor search
- clustering
- mining, location & instance recognition



# psychophysical studies

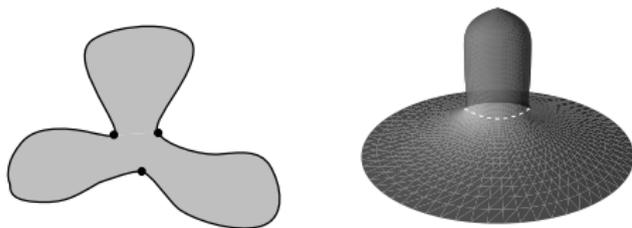


## minima rule

[Hoffman & Richards 1983]

“divide a silhouette into parts at concave cusps and negative minima of curvature”

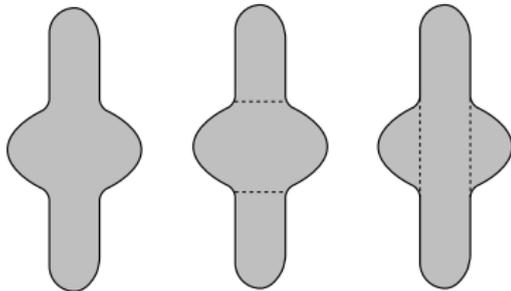
# psychophysical studies



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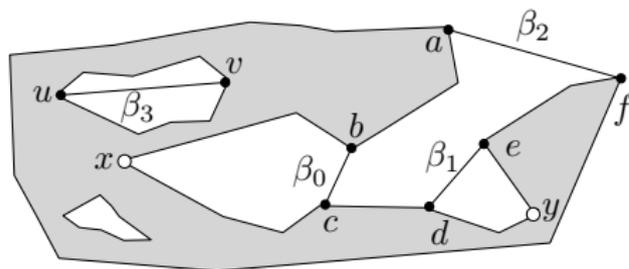


## short-cut rule

[Singh *et al.* 1999]

“divide a silhouette into parts using the shortest possible cuts”

# computational models



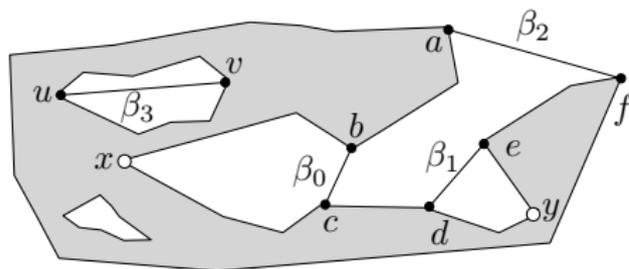
## current work

e.g. dual space decomposition

[Liu *et al.* 2014]

- mostly based on convexity
- requires optimization
- rules applied indirectly

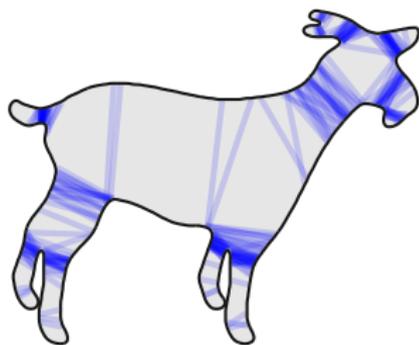
# computational models



## current work

e.g. dual space decomposition  
[Liu *et al.* 2014]

- mostly based on convexity
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## quantitative evaluation

practically non-existent until  
[De Winter & Wagemans 2006]

# medial axis

## planar shape

- a set  $X \subset \mathbb{R}^2$  whose boundary  $\partial X$  is a finite union of disjoint simple closed curves, such that for each curve there is a parametrization  $\alpha : [0, 1] \rightarrow \partial X$  by arc length that is piecewise smooth

## distance map

- maps each point  $x \in X$  to its minimal distance to boundary  $\partial X$

$$\mathcal{D}(X)(x) = \inf_{y \in \partial X} d(x, y)$$

## projection

- the set of points on  $\partial X$  at minimal distance to  $x$

$$\pi(x) = \{y \in \partial X : d(x, y) = \mathcal{D}(X)(x)\}$$

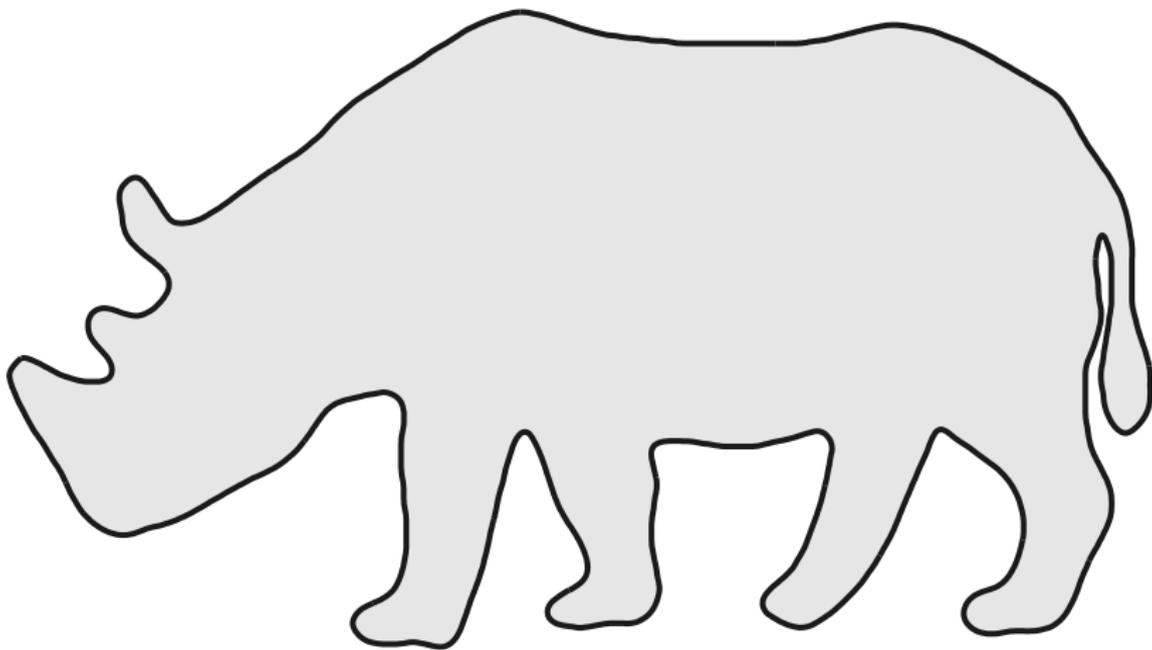
## medial axis

- the set of points with more than one projection points

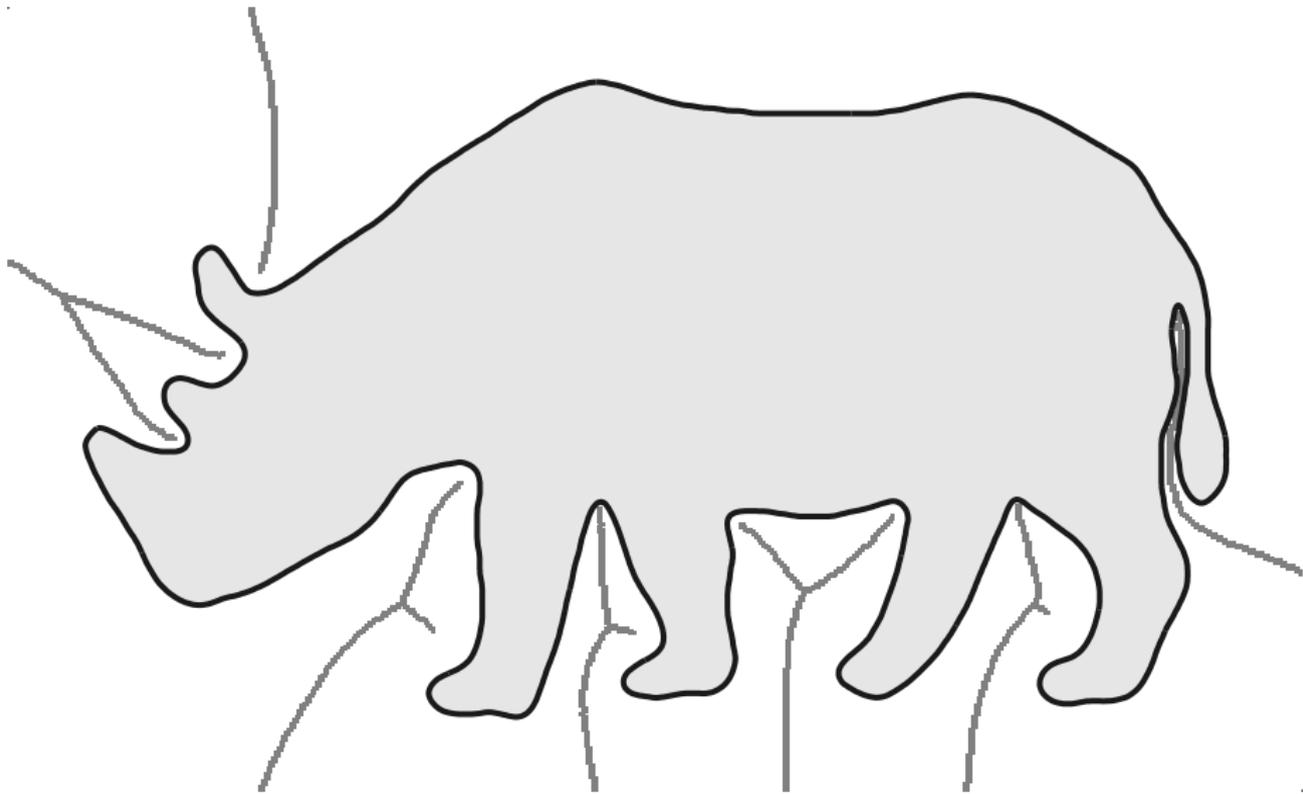
$$\mathcal{M}(X) = \{x \in \mathbb{R}^2 : |\pi(x)| > 1\}$$

# medial axis decomposition

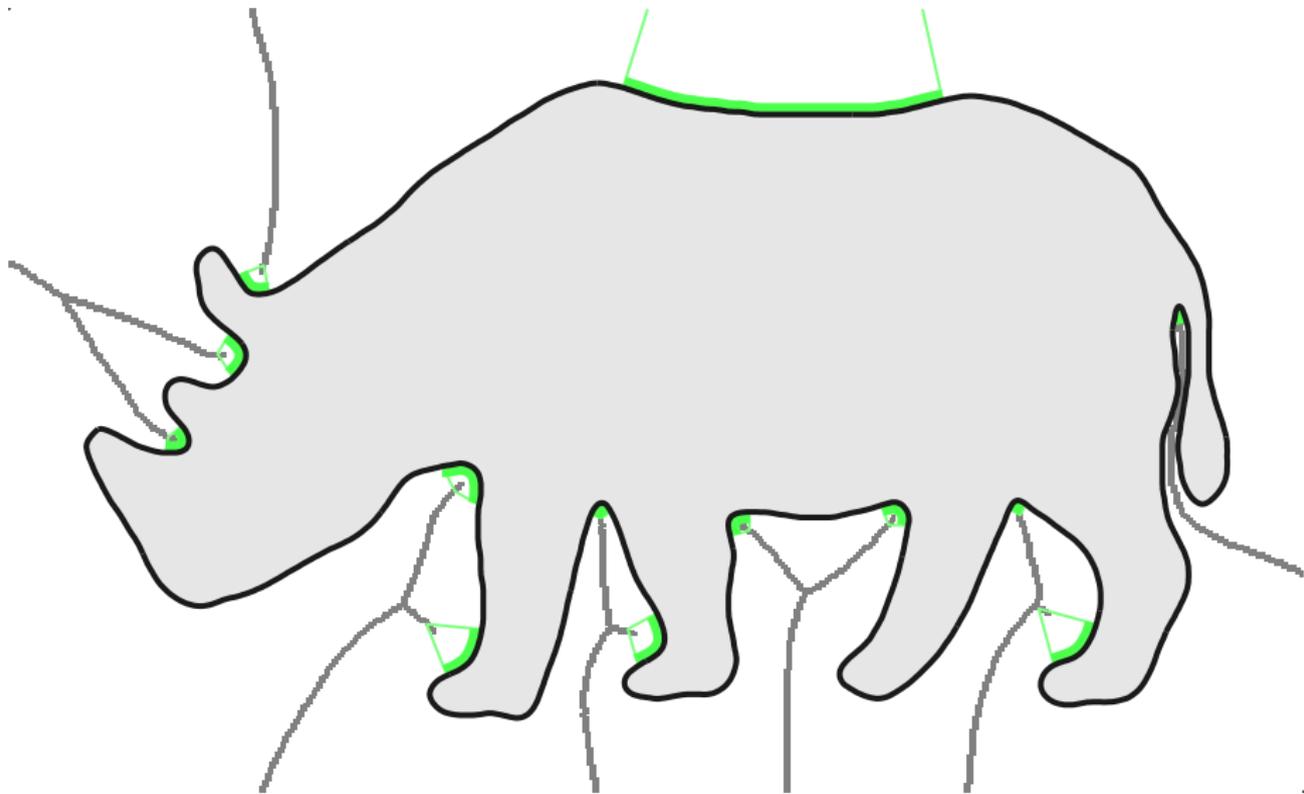
[Papanelopoulos & Avrithis, ongoing]



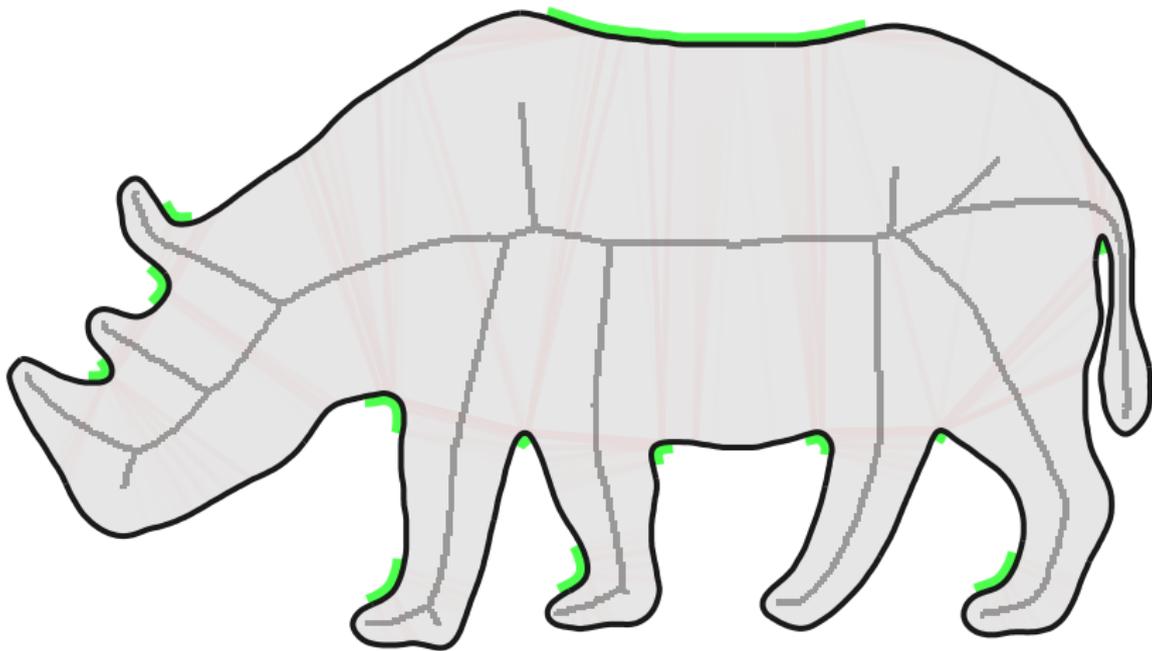
# exterior medial axis



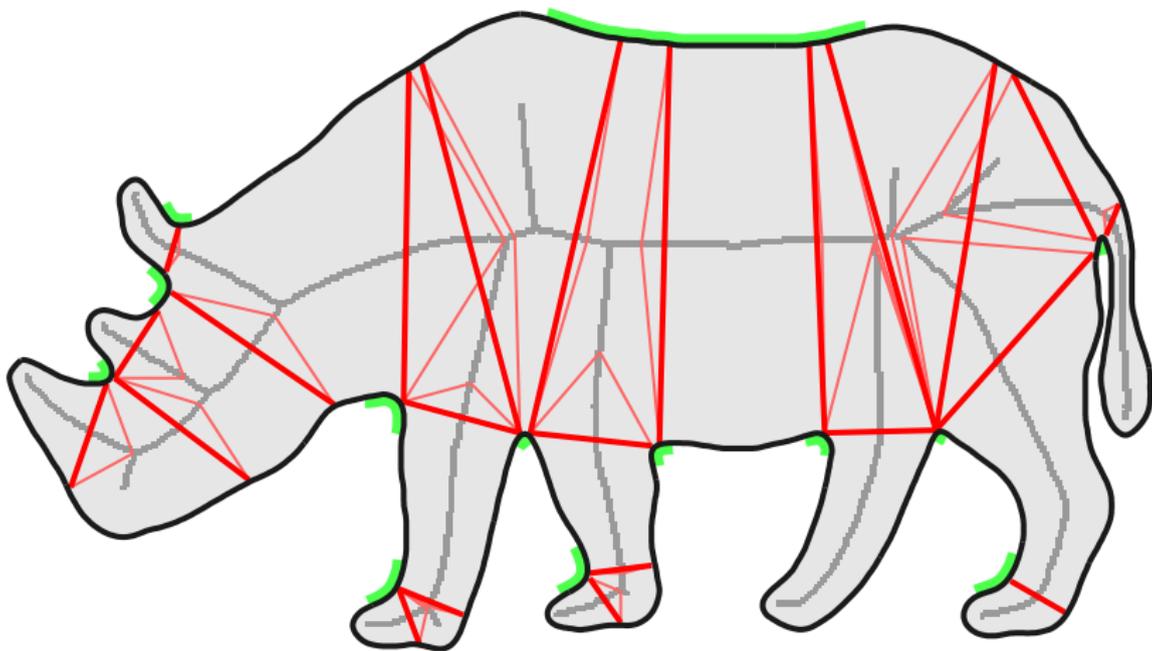
# concave corners and "locale"



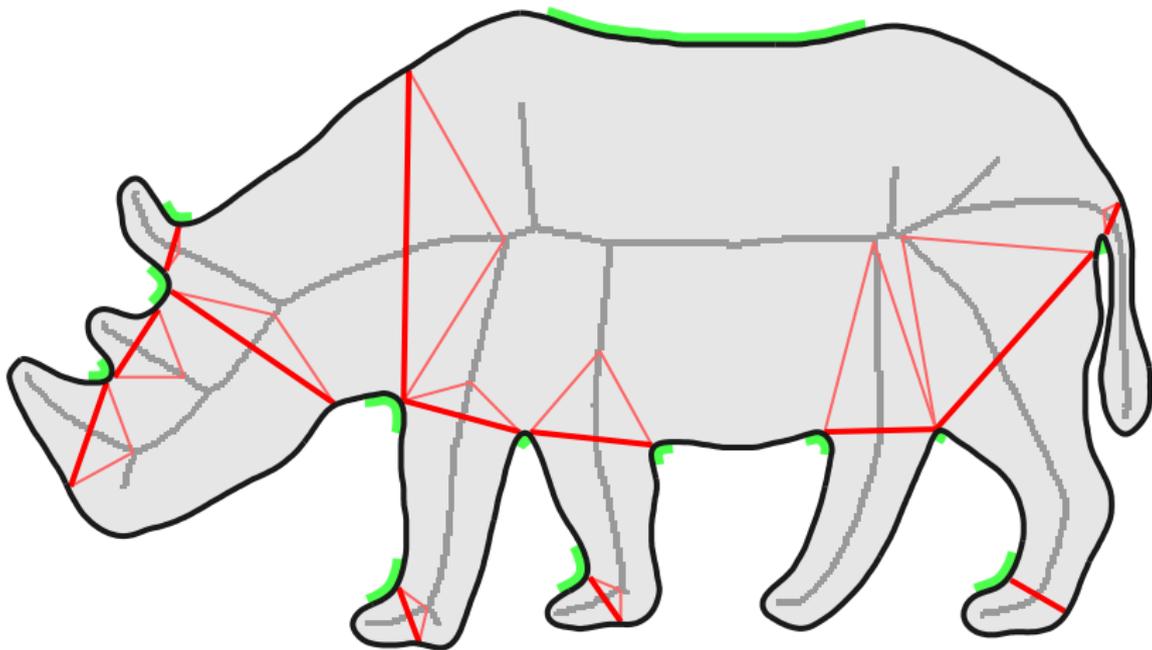
## interior medial axis and raw cuts



# cut equivalence on corners and branches



## local convexity and short-cut rule



## quantitative evaluation

	average		majority	
	$H$	$R$	$H$	$R$
DCE	0.208	0.497	0.188	0.466
SB	0.163	0.402	0.131	0.335
MD	0.151	0.371	0.126	0.328
FD	0.145	0.350	0.112	0.267
ACD	0.128	0.323	0.092	0.251
MAD	0.157	<b>0.193</b>	0.118	<b>0.154</b>
CBE	<b>0.111</b>	0.288	<b>0.069</b>	0.186
Human	–	–	0.104	0.137

$H$  = Hamming distance;  $R$  = Rand index

## medial axis decomposition...

- practically “reads off” all information from the medial axis
- requires no differentiation
- requires no optimization
- is based on local decisions only
- can use arbitrary salience measures



# feature detectors



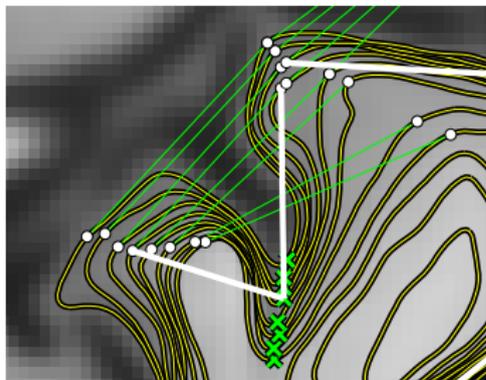
## Hessian affine

[Mikolajczyk & Schmid 2004]

- de facto standard in visual search
- too many responses



# feature detectors

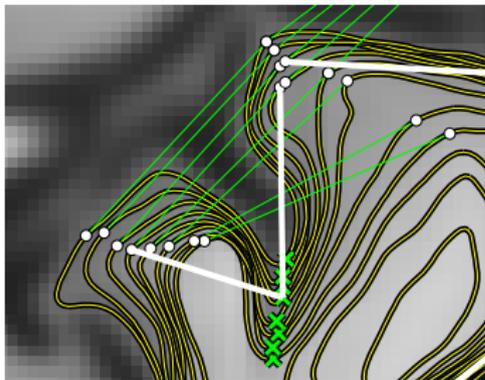


## affine frames on isophotes

[Perdoch *et al.* 2007]

- only local stability
- based on bitangents

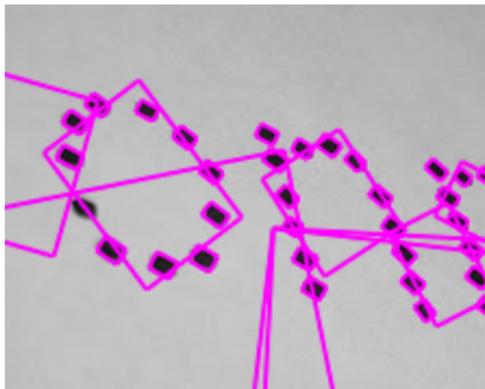
# feature detectors



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## medial features

[Avrithis & Rapantzikos 2011]

# medial features

[Avrithis & Rapantzikos, ICCV 2011]

## additively weighted distance map

- given a non-increasing function  $f : X \rightarrow \mathbb{R}$  of gradient strength, where  $X$  is the image plane,

$$\mathcal{D}(f)(x) = \min_{y \in X} \{d(x, y) + f(y)\}$$

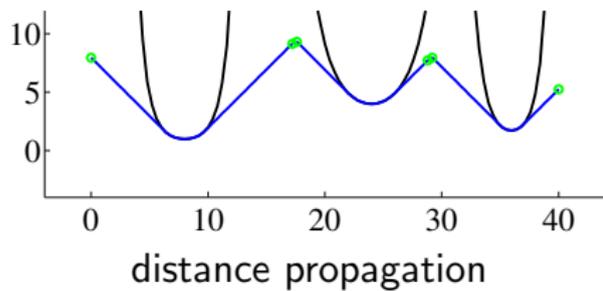
for  $x \in X$

## weighted medial

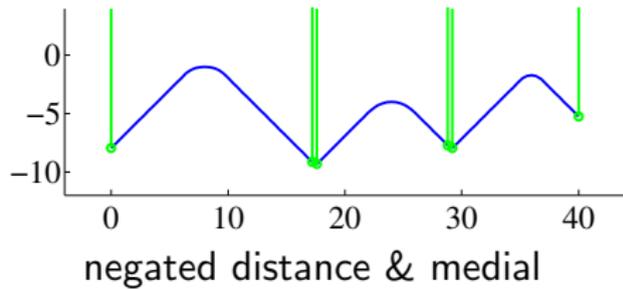
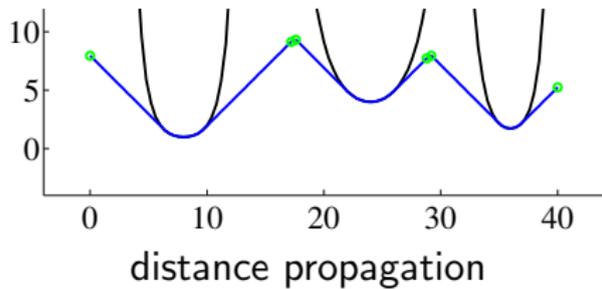
- similarly to unweighted case

$$\mathcal{M}(f) = \{x \in \mathbb{R}^2 : |\pi(x)| > 1\}$$

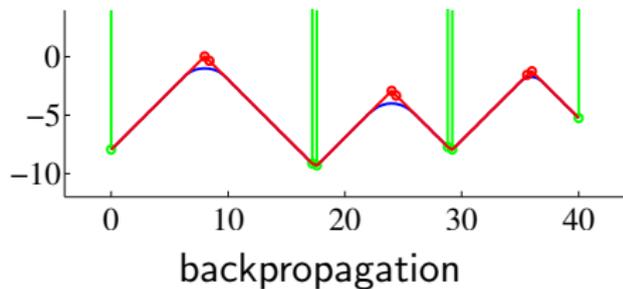
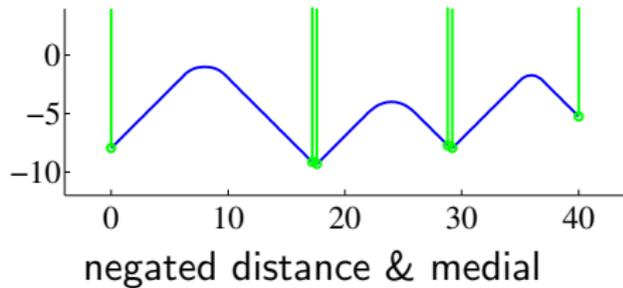
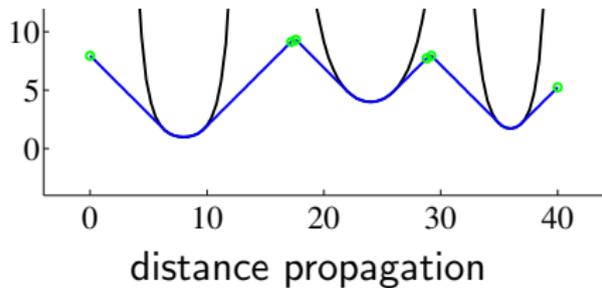
## region/boundary duality



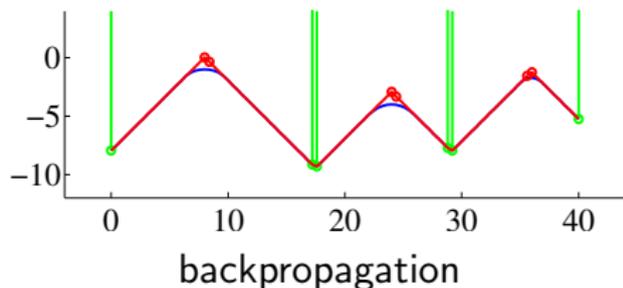
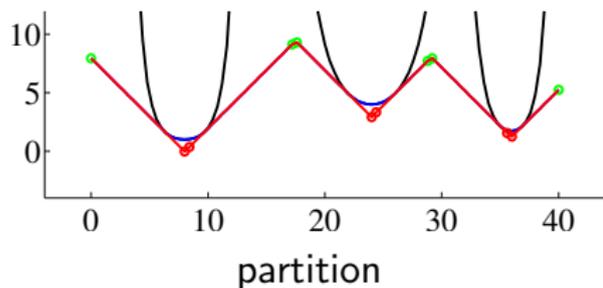
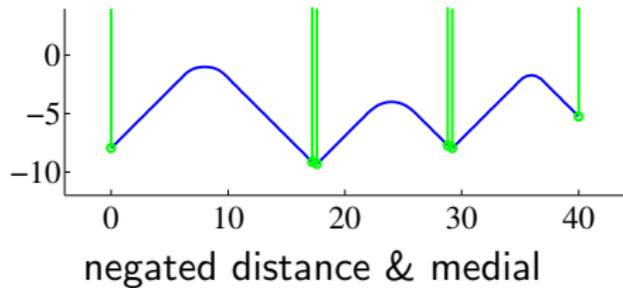
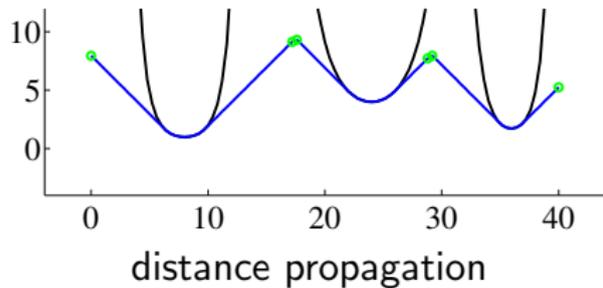
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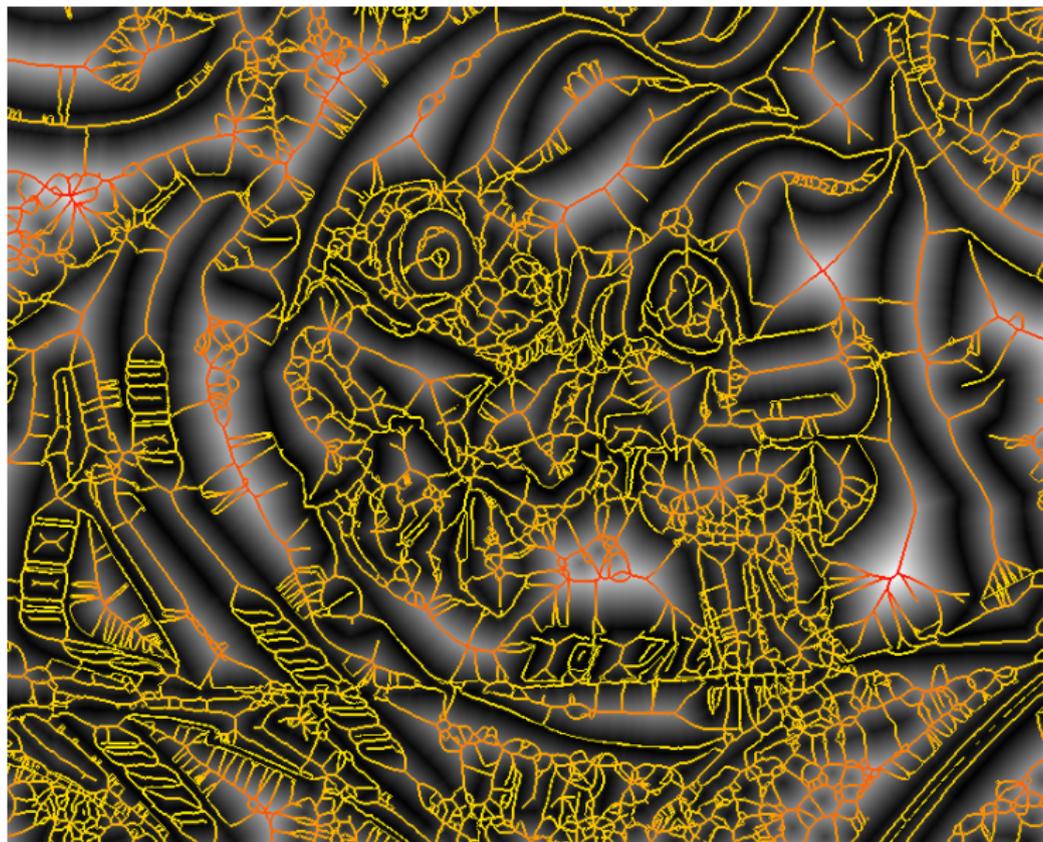
# region/boundary duality



## original image



## weighted distance map + medial



## original image + weighted medial



## region/boundary duality & partition



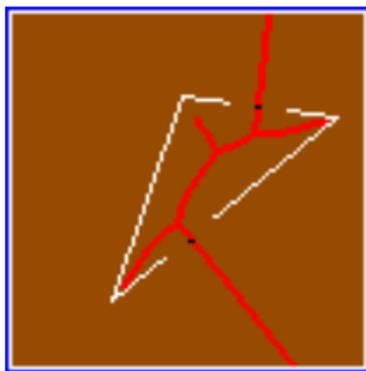
## original image + features



# fragmentation factor



binary input



point labels

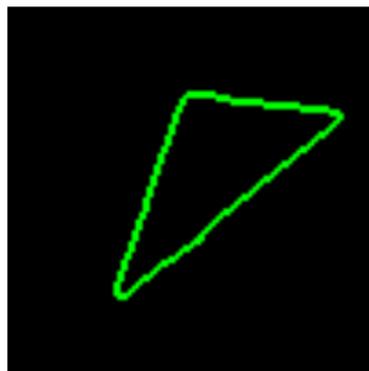
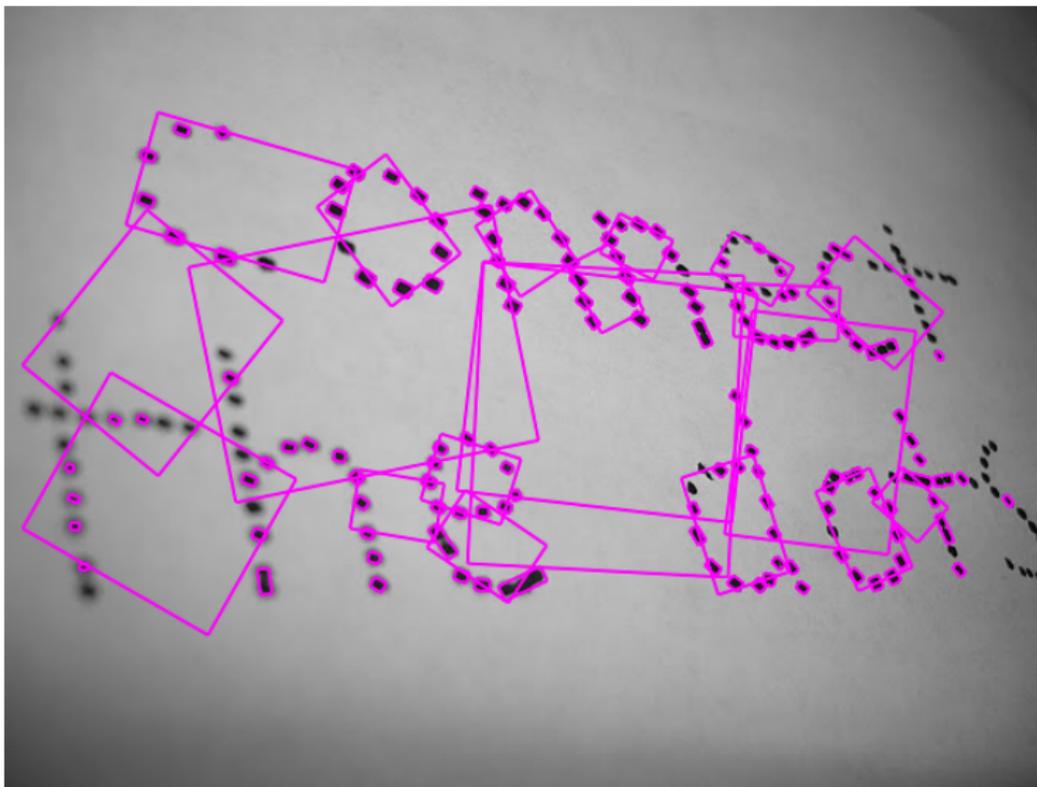


image partition

$$\phi(\kappa) = \frac{1}{a(\kappa)} \sum_{e \in E(\kappa)} w^2(x(e))$$

- selection criterion: is a region **well-enclosed by boundaries**?

# law of closure & perceptual grouping



# image search experiment

mAP on Oxford 5k

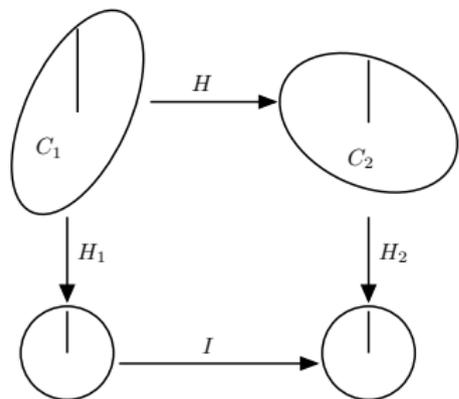
mAP	Inv. index		Re-ranking	
Detector	50k	200k	50k	200k
MFD	<b>0.515</b>	<b>0.580</b>	<b>0.568</b>	<b>0.617</b>
Hessian-affine	0.488	0.573	0.537	0.614
MSER	0.473	0.544	0.537	0.589
SURF	0.488	0.531	0.497	0.536
SIFT	0.395	0.457	0.434	0.495

## medial features...

- have arbitrary scale and shape
- are not constrained to extremal regions
- decompose shapes into parts
- capture law of closure



# spatial matching for instance recognition

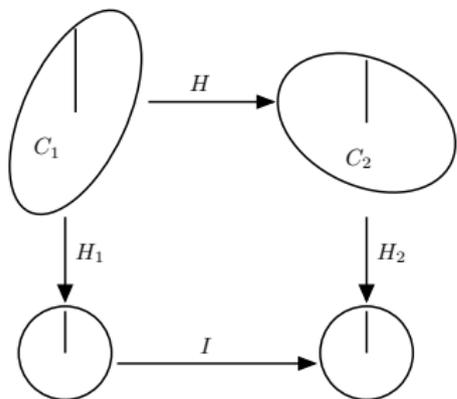


## fast spatial matching

[Philbin *et al.* 2007]

- RANSAC variant
- single-correspondence hypotheses
- enumerate them all— $O(n^2)$

# spatial matching for instance recognition



## fast spatial matching

[Philbin *et al.* 2007]

- RANSAC variant
- single-correspondence hypotheses
- enumerate them all— $O(n^2)$



## scale-invariant features

[Lowe 1999]

- Hough voting in 4d transformation space
- verification needed—still  $O(n^2)$

# spatial matching for class recognition

$$x^* = \arg \max_{x \in \{0,1\}^n} x^\top Ax$$

## spectral matching

[Leordeanu & Hebert *et al.* 2005]

- based on pairwise affinity
- mapping constraints
- relaxed to an eigenvalue problem

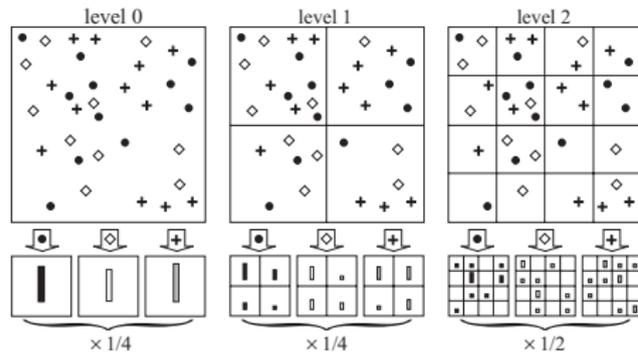
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[Leordeanu & Hebert *et al.* 2005]

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- mapping constraints
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## spatial pyramid matching

[Lazebnik *et al.* 2006]

- flexible matching
- non-invariant

# Hough pyramid matching

[Tolias & Avrithis, ICCV 2011]

- do not seek for inliers
- rather, look for hypotheses that agree with each other
- Hough voting in the 4d transformation space

$$F(c) = F(q)F(p)^{-1} = \begin{bmatrix} M(c) & \mathbf{t}(c) \\ \mathbf{0}^\top & 1 \end{bmatrix}$$

$$f(c) = (x(c), y(c), \sigma(c), \theta(c))$$

- pyramid matching in the transformation space

$$s(c) = g(b_0) + \sum_{k=1}^{L-1} 2^{-k} \{g(b_k) - g(b_{k-1})\}$$

$$s(C) = \sum_{c \in C \setminus X} w(c)s(c)$$

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$$F(c) = F(q)F(p)^{-1} = \begin{bmatrix} M(c) & \mathbf{t}(c) \\ \mathbf{0}^\top & 1 \end{bmatrix}$$

$$f(c) = (x(c), y(c), \sigma(c), \theta(c))$$

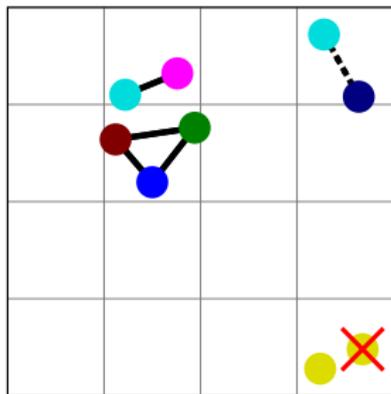
- pyramid matching in the transformation space

$$s(c) = g(b_0) + \sum_{k=1}^{L-1} 2^{-k} \{g(b_k) - g(b_{k-1})\}$$

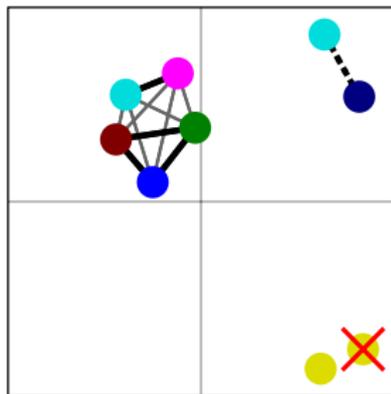
$$s(C) = \sum_{c \in C \setminus X} w(c)s(c)$$

# toy example

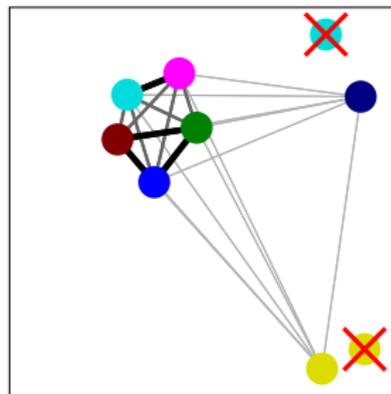
## Hough pyramid



Level 0



Level 1



Level 2

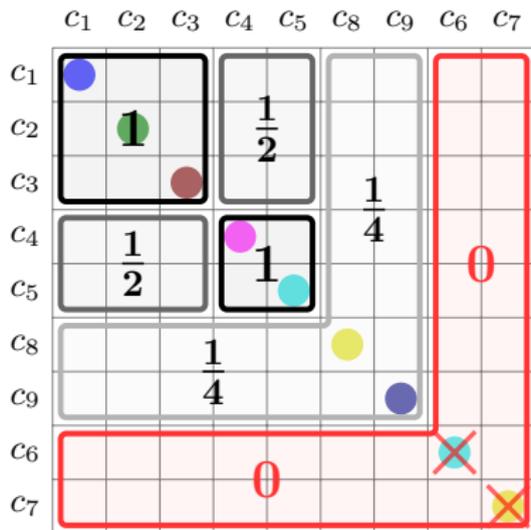
# toy example

## correspondences, strengths

	$p$	$q$	strength
$c_1$			$(2 + \frac{1}{2}2 + \frac{1}{4}2)w(c_1)$
$c_2$			$(2 + \frac{1}{2}2 + \frac{1}{4}2)w(c_2)$
$c_3$			$(2 + \frac{1}{2}2 + \frac{1}{4}2)w(c_3)$
$c_4$			$(1 + \frac{1}{2}3 + \frac{1}{4}2)w(c_4)$
$c_5$			$(1 + \frac{1}{2}3 + \frac{1}{4}2)w(c_5)$
$c_6$			0
$c_7$			0
$c_8$			$\frac{1}{4}6w(c_8)$
$c_9$			$\frac{1}{4}6w(c_9)$

# toy example

## affinity matrix

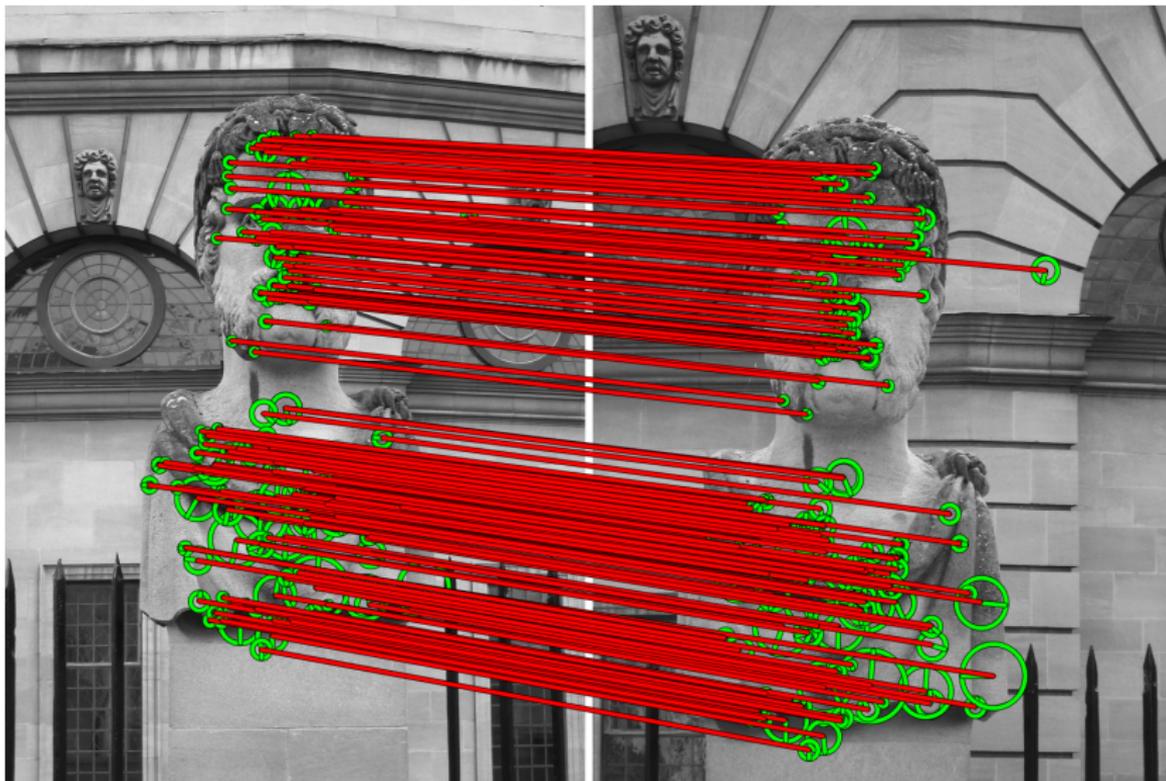


# Hough pyramid matching ...

- is **invariant** to similarity transformations
- is **flexible**, allowing non-rigid motion and multiple matching surfaces or objects
- imposes **one-to-one** mapping

# examples

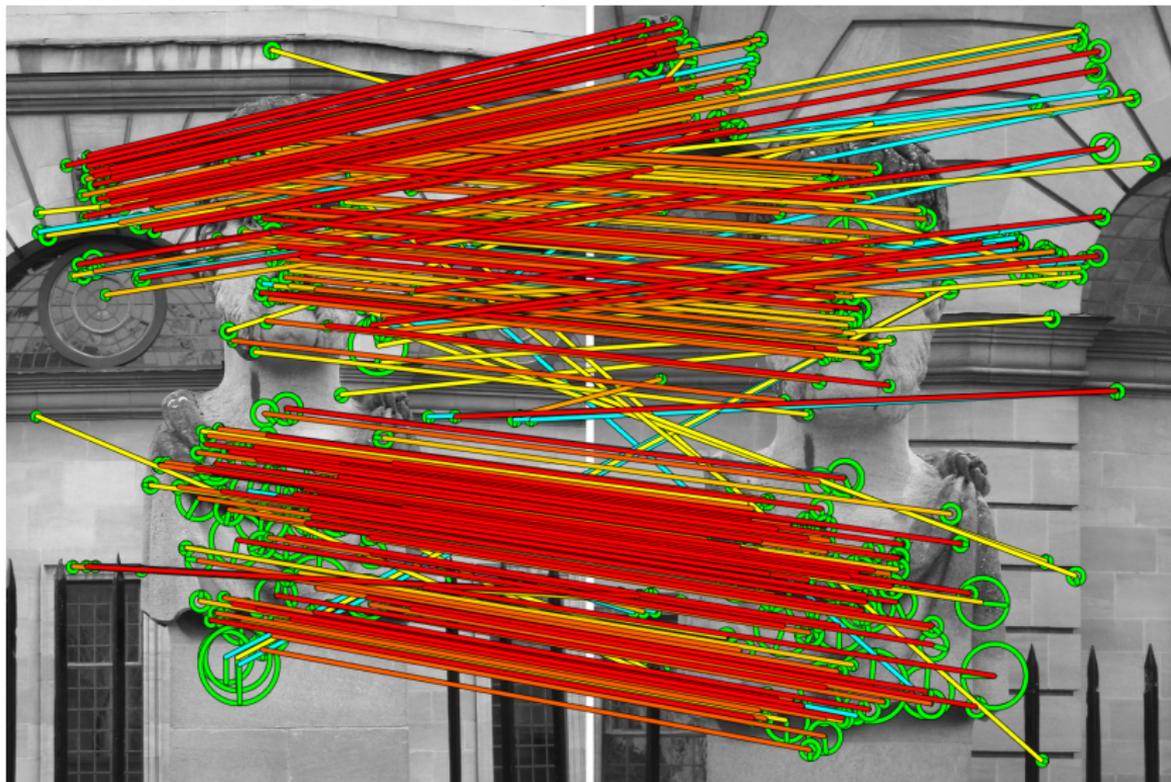
HPM vs FSM [Philbin et al. 2007]



fast spatial matching

# examples

HPM vs FSM [Philbin et al. 2007]



Hough pyramid matching

# examples

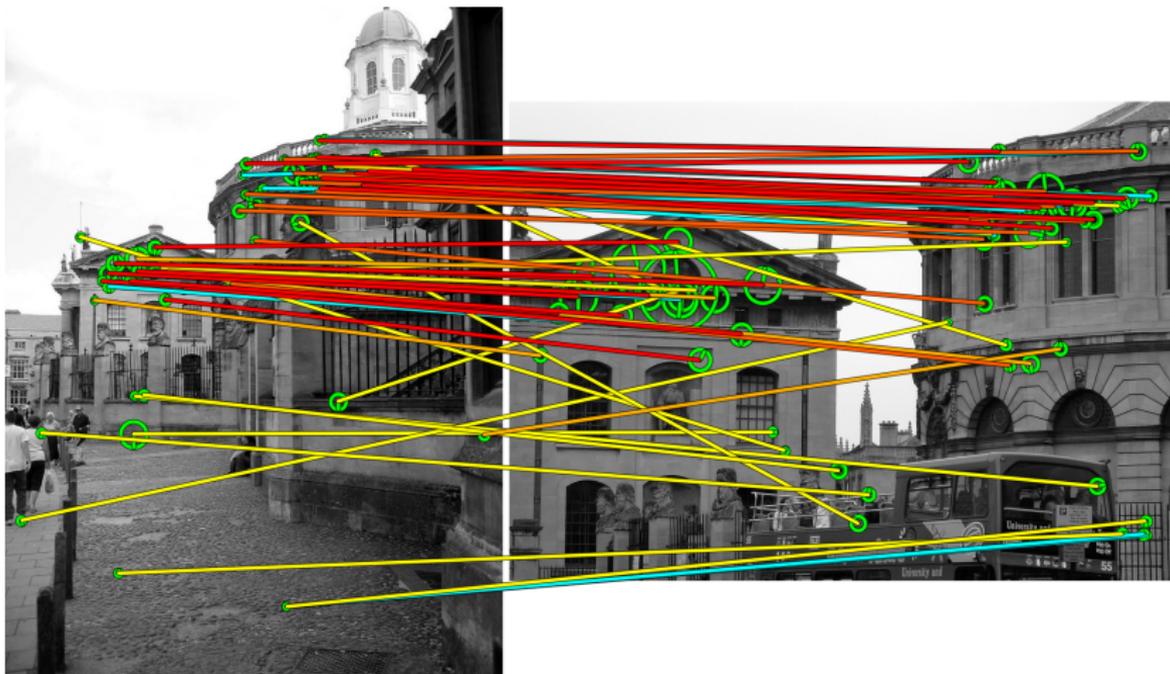
HPM vs FSM [Philbin et al. 2007]



fast spatial matching

# examples

HPM vs FSM [Philbin et al. 2007]



Hough pyramid matching

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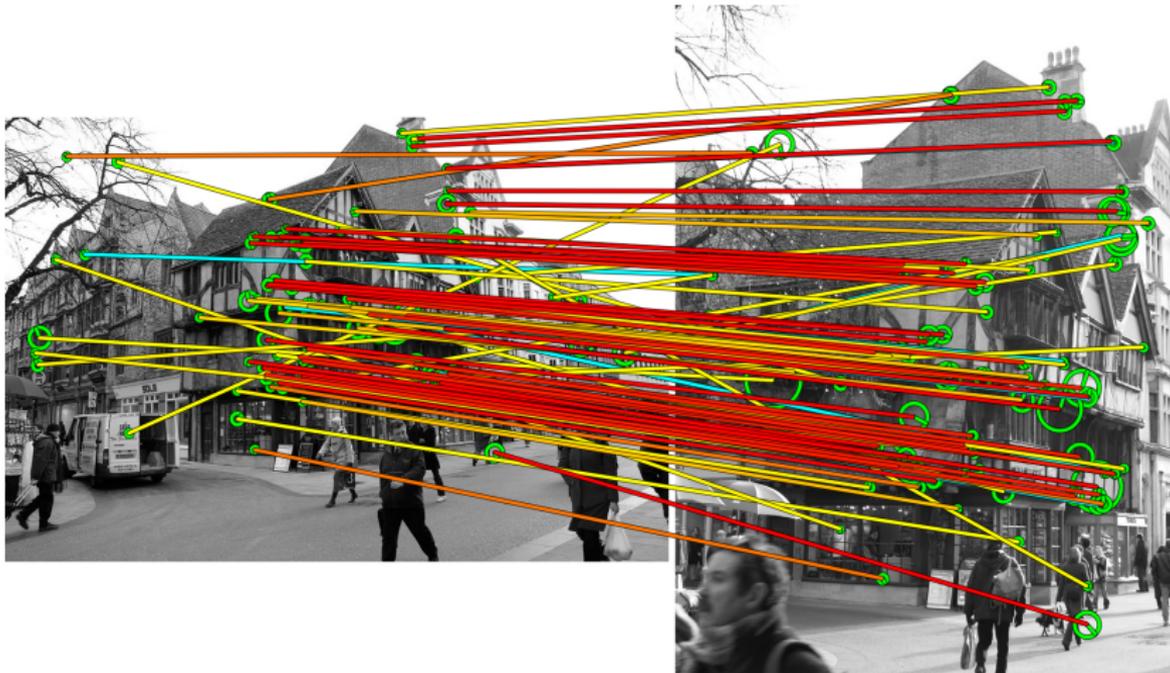
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fast spatial matching

# examples

HPM vs FSM [Philbin et al. 2007]



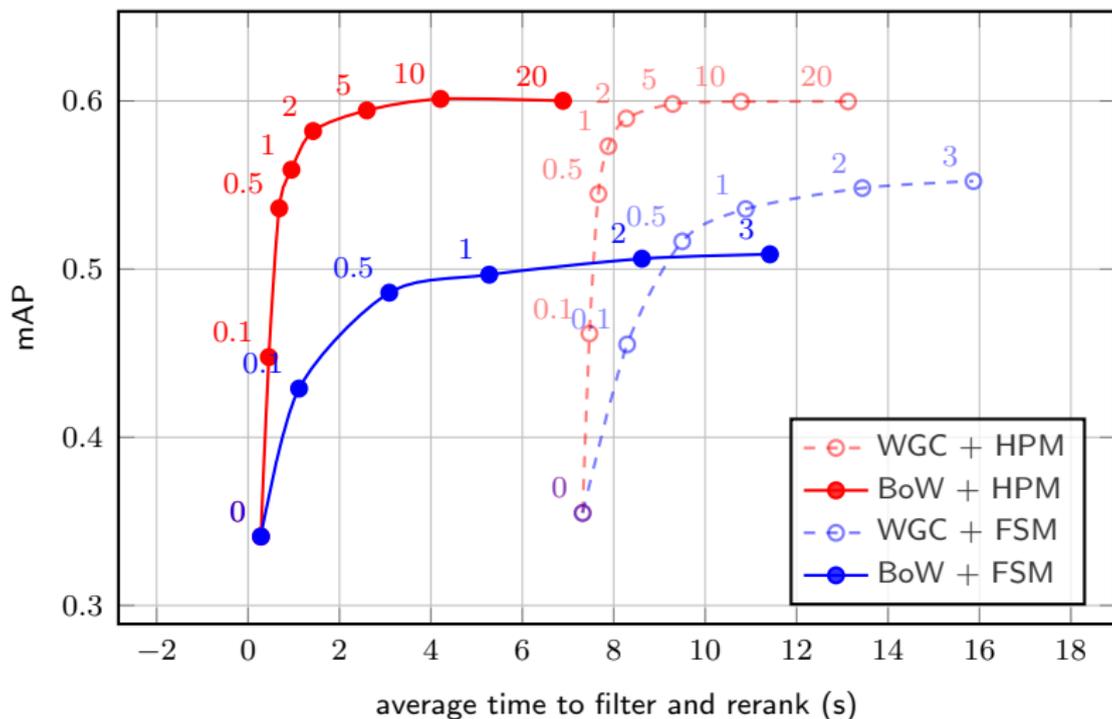
Hough pyramid matching

# Hough pyramid matching ...

- is non-iterative, and **linear** in the number of correspondences
- in a given query time, can re-rank **one order of magnitude** more images than the state of the art
- typically needs **less than one millisecond** to match a pair of images, on average

# performance vs time

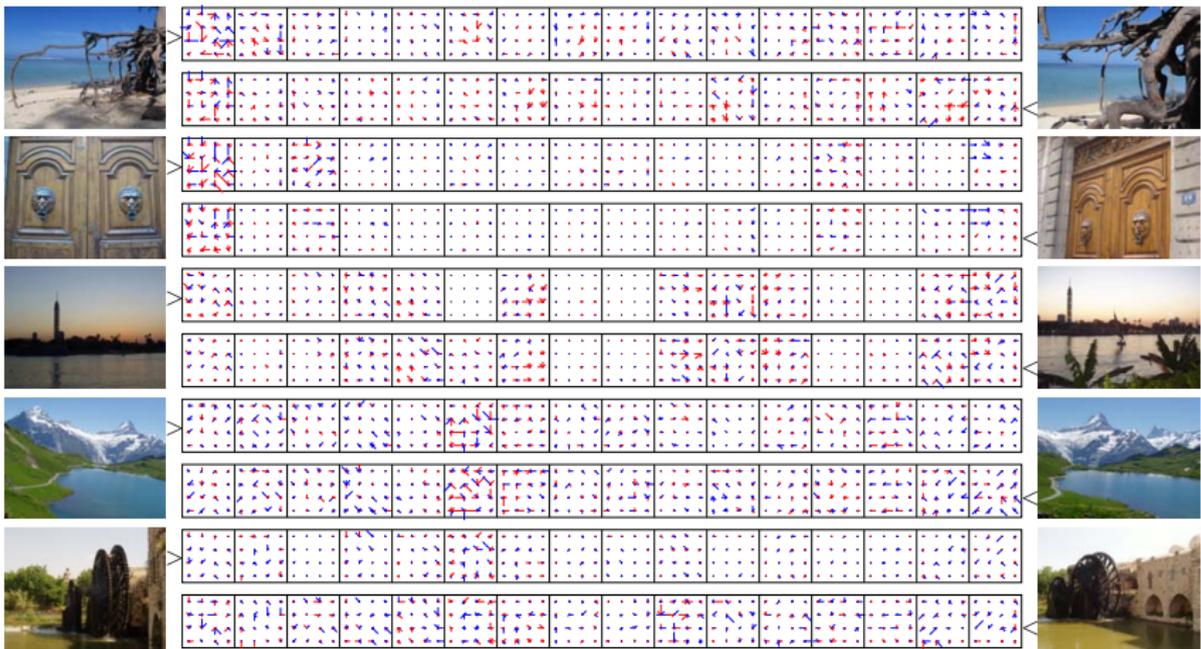
on World Cities 2M



# comparison to state of the art

[Avrithis & Tolias, IJCV 2014]

method	Ox5K	Ox105K	Paris	Holidays
HPM (this work)	<b>0.789</b>	<b>0.730</b>	0.725	<b>0.790</b>
[Shen <i>et al.</i> 2012]	0.752	0.729	<b>0.741</b>	0.762
GVP [Zhang <i>et al.</i> 2011]	0.696	-	-	-
SBoF [Cao <i>et al.</i> 2010]	0.656	-	0.632	-
[Perdoch <i>et al.</i> 2009]	<b>0.789</b>	0.726	-	0.715
FSM [Philbin <i>et al.</i> 2007]	0.647	0.541	-	-



# descriptors, kernels & embeddings

# set kernels & embeddings

## normalized sum set kernel [Bo & Sminchisescu 2009]

- given kernel function  $k$ , define (finite) set kernel

$$K(X, Y) = \frac{1}{|X||Y|} \sum_{x \in X} \sum_{y \in Y} k(x, y)$$

## example: Gaussian mixtures [Liu & Perronnin 2008]

- model set  $X$  by finite mixture distribution

$$f_X(z) = \frac{1}{|X|} \sum_{x \in X} \mathcal{N}(z|x, \Sigma), \quad z \in \mathbb{R}^d$$

- then,

$$\langle f_X, f_Y \rangle = \frac{1}{|X||Y|} \sum_{x \in X} \sum_{y \in Y} \mathcal{N}(x|y, 2\Sigma)$$

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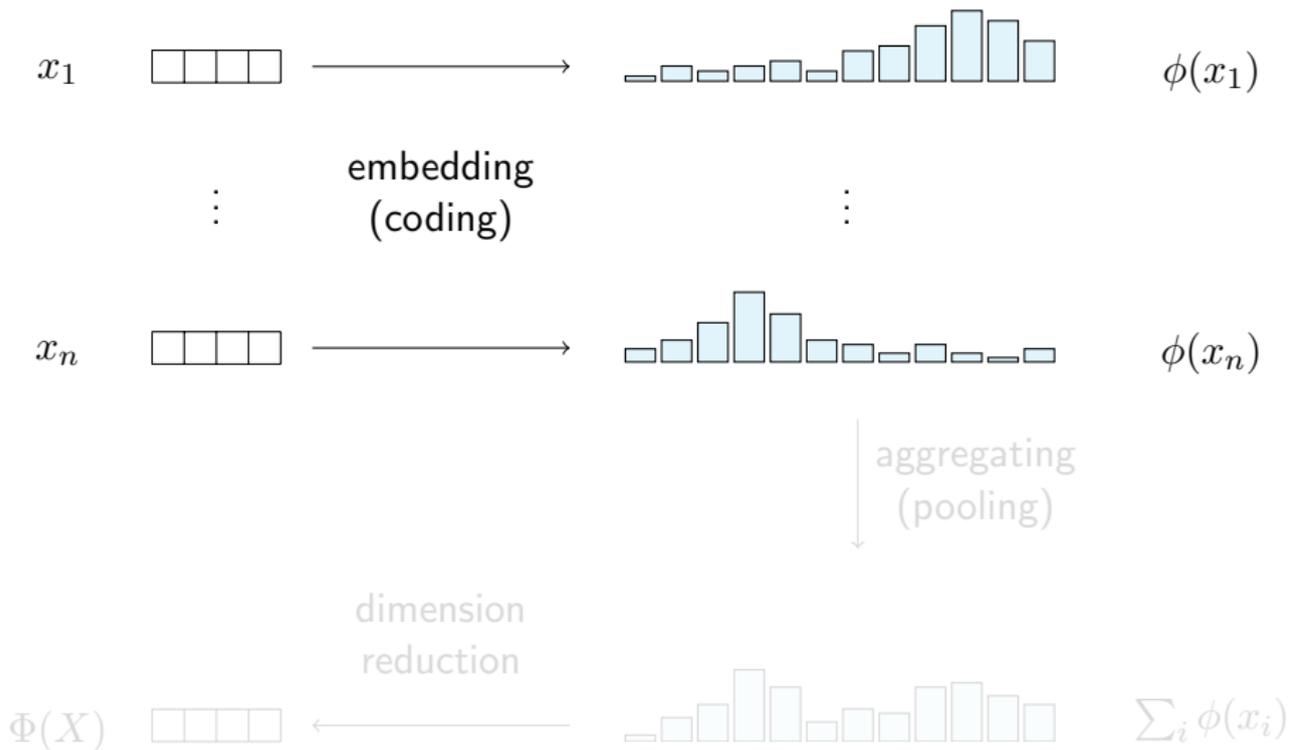
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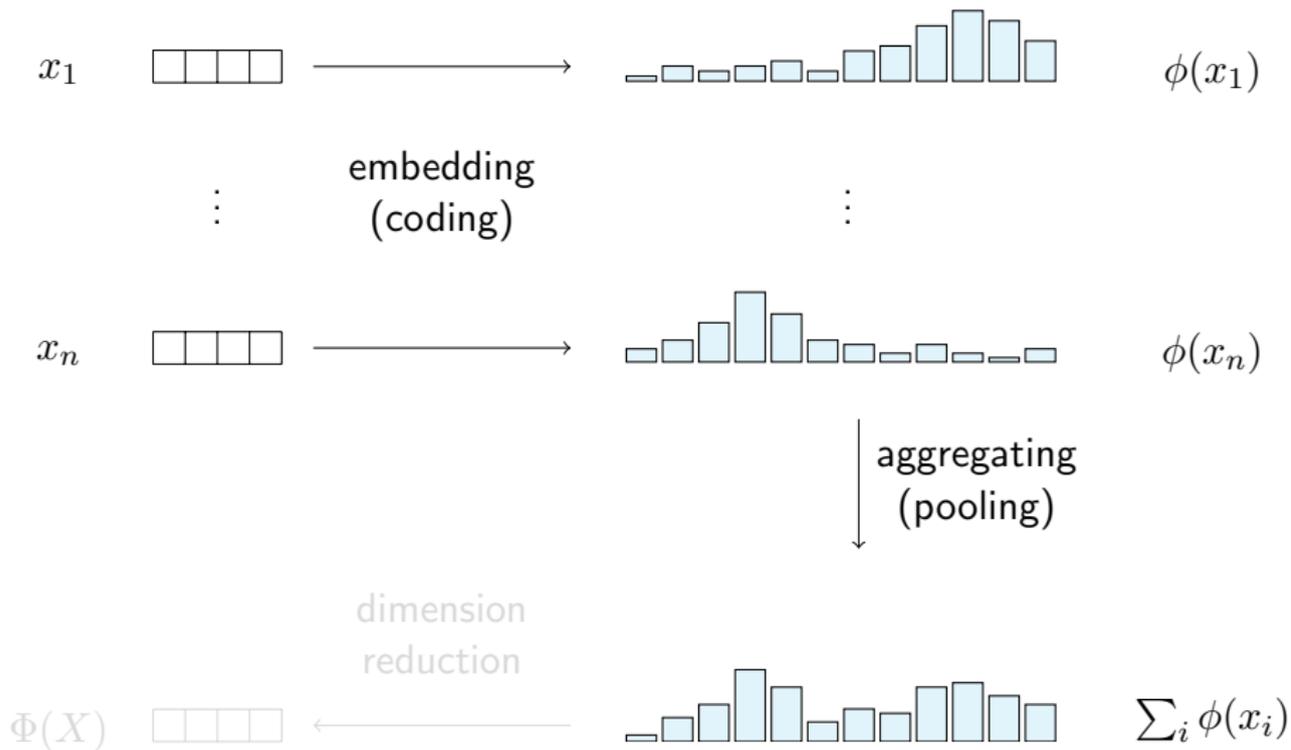
# explicit feature maps



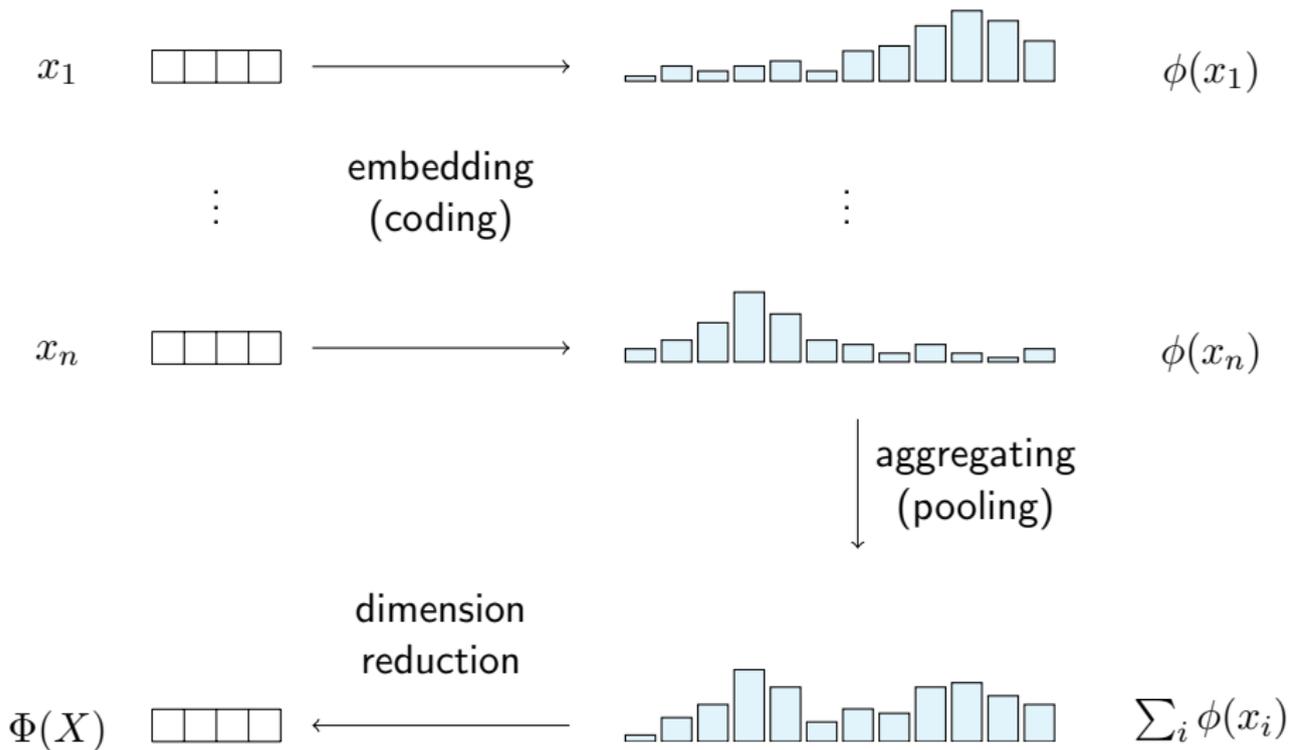
# explicit feature maps



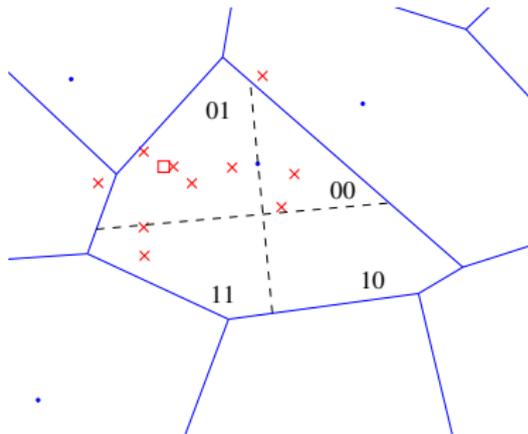
# explicit feature maps



# explicit feature maps



## two different perspectives



### Hamming embedding

[Jégou *et al.* 2008]

- large vocabulary
- binary signature & descriptor voting
- not aggregated
- selective: discard weak votes

$$V(X_c) = \sum_{x \in X_c} x - q(x)$$

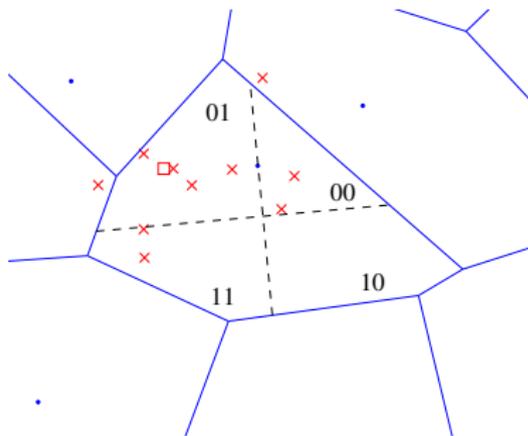
$$X_c = \{x \in X : q(x) = c\}$$

### VLAD

[Jégou *et al.* 2010]

- small vocabulary
- one aggregated vector per cell
- linear operation
- not selective

## two different perspectives



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$$V(X_c) = \sum_{x \in X_c} x - q(x)$$

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## common model: image similarity

$$K(X, Y) = \gamma(X) \gamma(Y) \sum_{c \in C} w_c \kappa(X_c, Y_c)$$

normalization factor

cell weighting

cell similarity

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$$K(X, Y) = \gamma(X) \gamma(Y) \sum_{c \in C} w_c \kappa(X_c, Y_c)$$

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cell similarity

# common model: cell similarity

## non aggregated

$$\kappa_n(X_c, Y_c) = \sum_{x \in X_c} \sum_{y \in Y_c} \sigma \left( \phi(x)^\top \phi(y) \right)$$

selectivity function

descriptor representation (residual, binary, scalar)

## aggregated

$$\kappa_a(X_c, Y_c) = \sigma \left\{ \psi \left( \sum_{x \in X_c} \phi(x) \right)^\top \psi \left( \sum_{y \in Y_c} \phi(y) \right) \right\} = \sigma \left( \Phi(X_c)^\top \Phi(Y_c) \right)$$

normalization ( $\ell_2$ , power-law)

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# BoW, HE and VLAD in the common model

model	$\kappa(X_c, Y_c)$	$\phi(x)$	$\sigma(u)$	$\psi(z)$	$\Phi(X_c)$
BoW	$\kappa_n$ or $\kappa_a$	1	$u$	$z$	$ X_c $
HE	$\kappa_n$ only	$\hat{b}_x$	$w \left( \frac{B}{2}(1-u) \right)$	—	—
VLAD	$\kappa_n$ or $\kappa_a$	$r(x)$	$u$	$z$	$V(X_c)$

BoW  $\kappa(X_c, Y_c) = \sum_{x \in X_c} \sum_{y \in Y_c} 1 = |X_c| \times |Y_c|$

HE  $\kappa(X_c, Y_c) = \sum_{x \in X_c} \sum_{y \in Y_c} w(h(b_x, b_y))$

VLAD  $\kappa(X_c, Y_c) = \sum_{x \in X_c} \sum_{y \in Y_c} r(x)^\top r(y) = V(X_c)^\top V(Y_c)$

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# aggregated selective match kernel

[Tolias et al. ICCV 2013]

- cell similarity

$$\text{ASMK}(X_c, Y_c) = \sigma_\alpha \left( \hat{V}(X_c)^\top \hat{V}(Y_c) \right)$$

- cell representation:  $\ell_2$ -normalized aggregated residual

$$\Phi(X_c) = \hat{V}(X_c) = V(X_c) / \|V(X_c)\|$$

- selectivity function

$$\sigma_\alpha(u) = \begin{cases} \text{sgn}(u)|u|^\alpha, & u > \tau \\ 0, & \text{otherwise} \end{cases}$$

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# impact of selectivity

$$\alpha = 1, \tau = 0.0$$



$$\alpha = 1, \tau = 0.25$$



thresholding removes false correspondences

# impact of selectivity

$$\alpha = 3, \tau = 0.0$$



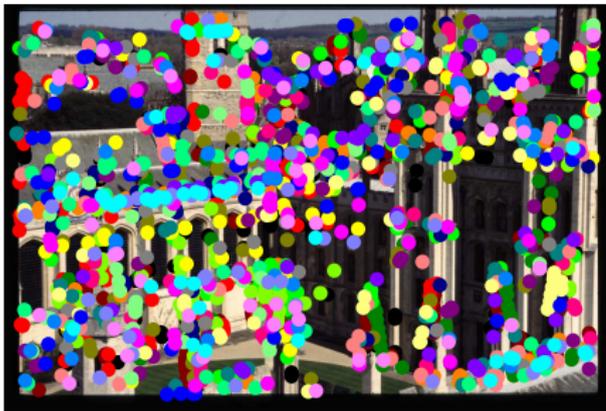
$$\alpha = 3, \tau = 0.25$$



correspondences weighed based on confidence

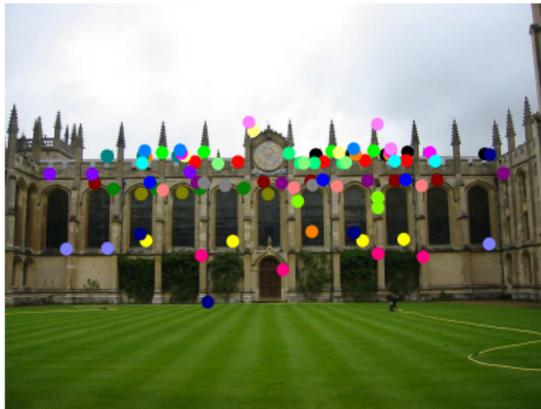
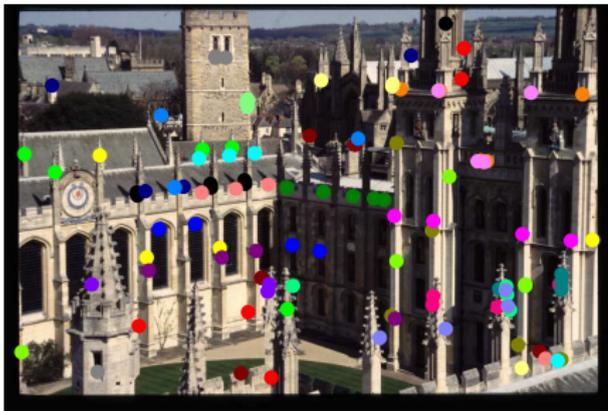
# impact of aggregation & burstiness

$k = 128$  as in VLAD



# impact of aggregation & burstiness

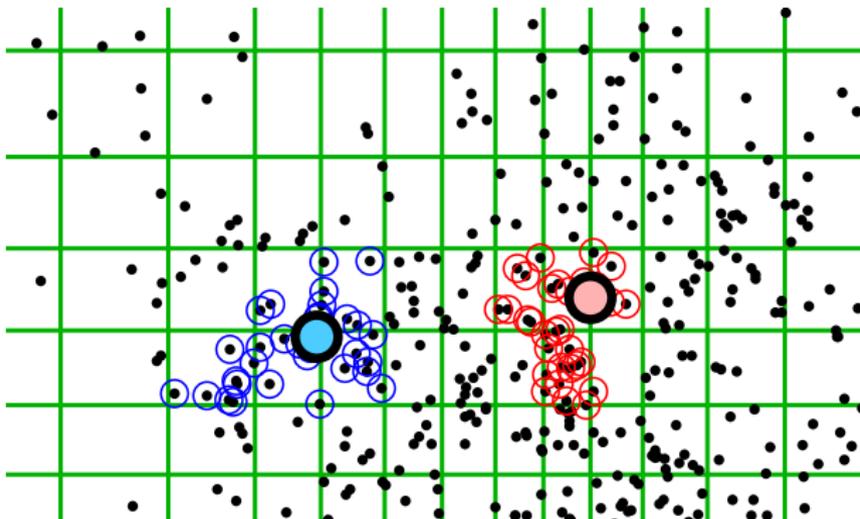
$k = 65k$  as in HE



# comparison to state of the art

[Tolias et al. IJCV 2015]

Dataset	MA	Oxf5k	Oxf105k	Par6k	Holiday
ASMK*		76.4	69.2	74.4	80.0
ASMK*	×	80.4	75.0	77.0	81.0
ASMK		78.1	-	76.0	81.2
ASMK	×	81.7	-	78.2	82.2
HE [Jégou et al. '10]		51.7	-	-	74.5
HE [Jégou et al. '10]	×	56.1	-	-	77.5
HE-BURST [Jain et al. '10]		64.5	-	-	78.0
HE-BURST [Jain et al. '10]	×	67.4	-	-	79.6
Fine vocab. [Mikulík et al. '10]	×	74.2	67.4	74.9	74.9
AHE-BURST [Jain et al. '10]		66.6	-	-	79.4
AHE-BURST [Jain et al. '10]	×	69.8	-	-	81.9
Rep. structures [Torri et al. '13]	×	65.6	-	-	74.9
Locality [Tao et al. '14]	×	77.0	-	-	78.7

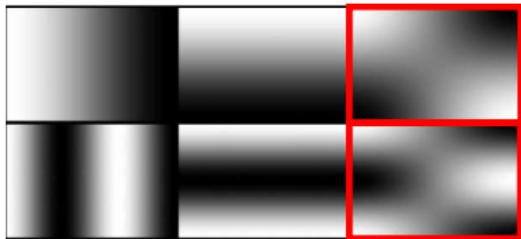


nearest neighbor search

# binary codes

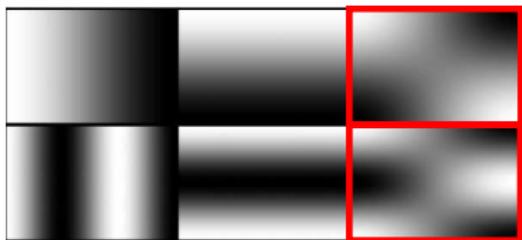
## spectral hashing

[Weiss *et al.* 2008]



- similarity preserving, balanced, uncorrelated
- spectral relaxation
- out of sample extension: uniform assumption

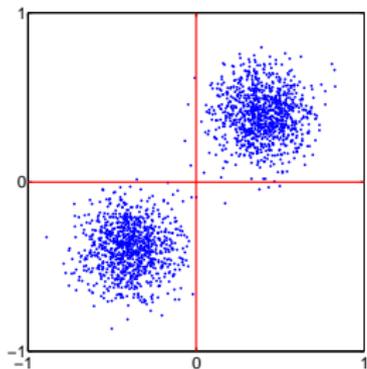
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## spectral hashing

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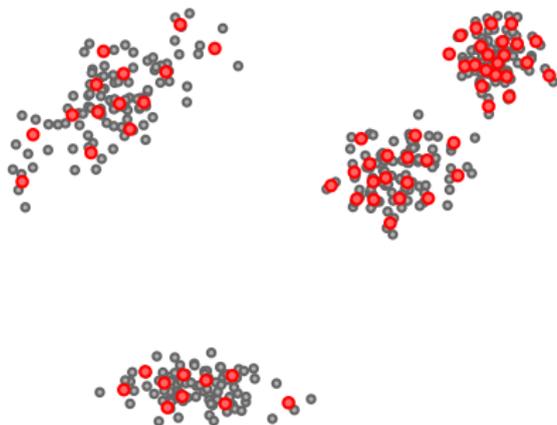
## iterative quantization

[Gong & Lazebnik 2011]

- quantize to closest vertex of binary cube
- PCA followed by interleaved rotation and quantization

# vector quantization

[Gray 1984]



$$\text{minimize } E(C) = \sum_{\mathbf{x} \in X} \min_{\mathbf{c} \in C} \|\mathbf{x} - \mathbf{c}\|^2 = \sum_{\mathbf{x} \in X} \|\mathbf{x} - q(\mathbf{x})\|^2$$

distortion

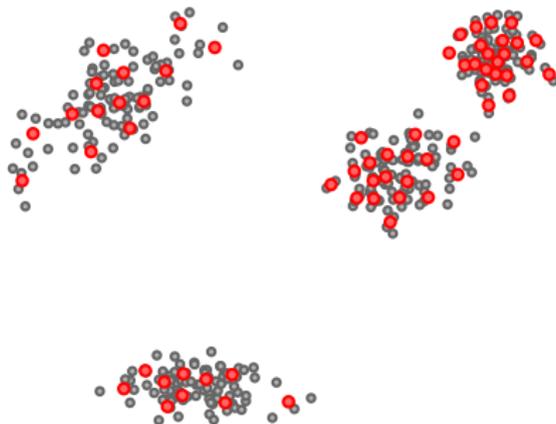
dataset

codebook

quantizer

# vector quantization

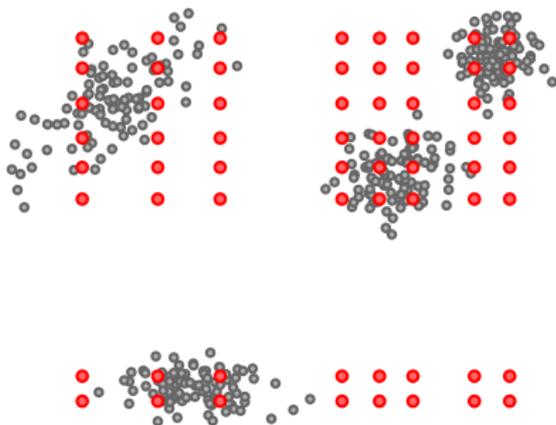
[Gray 1984]



- For small distortion  $\rightarrow$  large  $k = |C|$ :
  - hard to train
  - too large to store
  - too slow to search

# product quantization

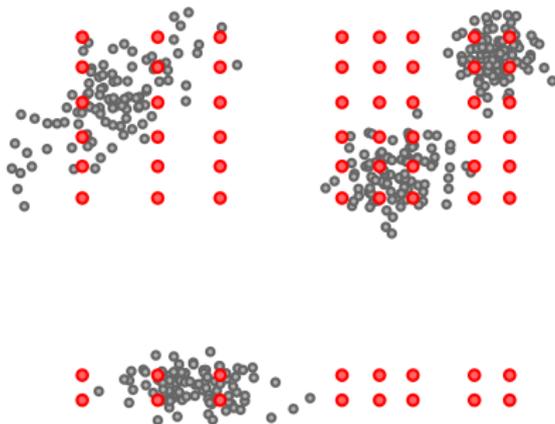
[Jégou et al. 2011]



$$\begin{aligned} & \text{minimize} && \sum_{\mathbf{x} \in X} \min_{\mathbf{c} \in C} \|\mathbf{x} - \mathbf{c}\|^2 \\ & \text{subject to} && C = C^1 \times \dots \times C^m \end{aligned}$$

# product quantization

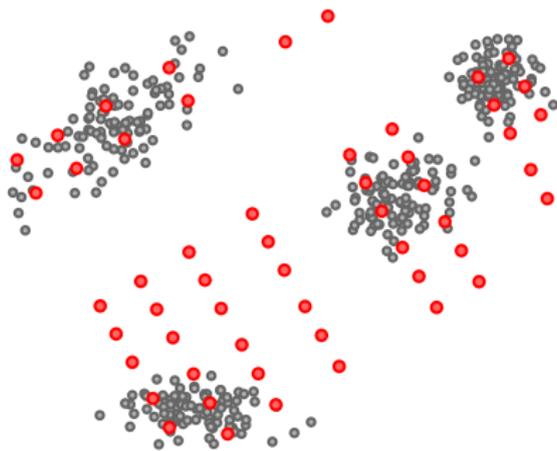
[Jégou et al. 2011]



- train:  $q = (q^1, \dots, q^m)$  where  $q^1, \dots, q^m$  obtained by VQ
- store:  $|C| = k^m$  with  $|C^1| = \dots = |C^m| = k$
- search:  $\|\mathbf{y} - q(\mathbf{x})\|^2 = \sum_{j=1}^m \|\mathbf{y}^j - q^j(\mathbf{x}^j)\|^2$  where  $q^j(\mathbf{x}^j) \in C^j$

# optimized product quantization

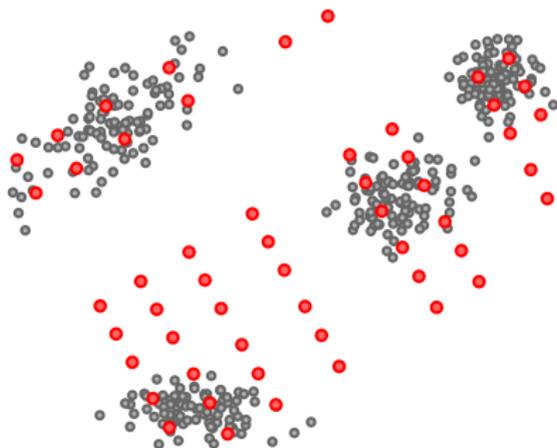
[Ge et al. 2013]



$$\begin{aligned} & \text{minimize} && \sum_{\mathbf{x} \in X} \min_{\hat{\mathbf{c}} \in \hat{C}} \|\mathbf{x} - R^T \hat{\mathbf{c}}\|^2 \\ & \text{subject to} && \hat{C} = C^1 \times \dots \times C^m \\ & && R^T R = I \end{aligned}$$

# optimized product quantization

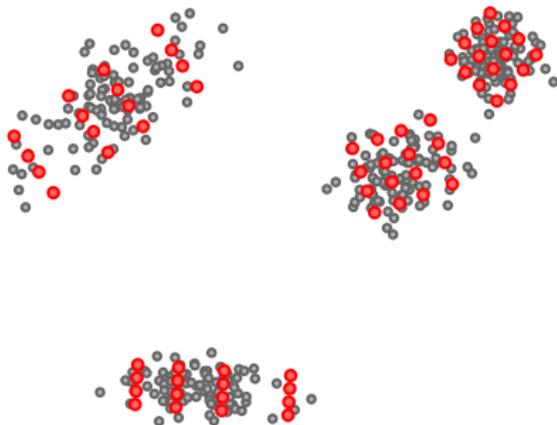
Parametric solution for  $x \sim \mathcal{N}(0, \Sigma)$



- **independence**: PCA-align by diagonalizing  $\Sigma$  as  $U\Lambda U^\top$
- **balanced variance**: permute  $\Lambda$  by  $\pi$  such that  $\prod_i \lambda_i$  is constant in each subspace;  $R \leftarrow UP_\pi^\top$
- find  $\hat{C}$  by PQ on rotated data  $\hat{X} = RX$

# locally optimized product quantization

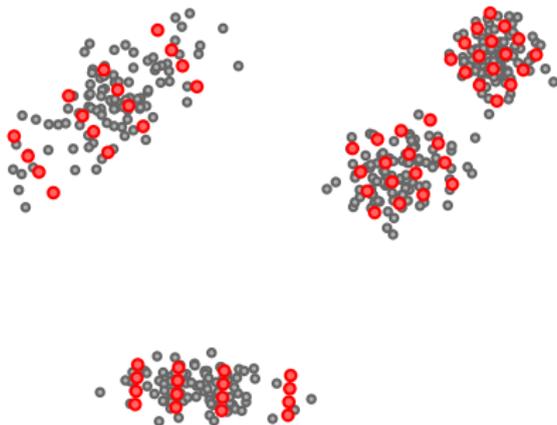
[Kalantidis & Avrithis, CVPR 2014]



- compute residuals  $r(\mathbf{x}) = \mathbf{x} - q(\mathbf{x})$  on coarse quantizer  $q$
- collect residuals  $Z_{\mathbf{c}} = \{r(\mathbf{x}) : q(\mathbf{x}) = \mathbf{c}\}$  per cell
- train  $(R_{\mathbf{c}}, q_{\mathbf{c}}) \leftarrow \text{OPQ}(Z_{\mathbf{c}})$  per cell

# locally optimized product quantization

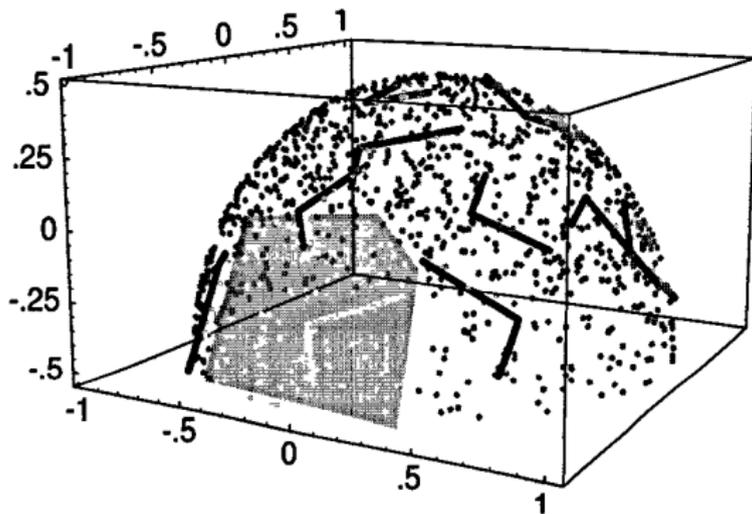
[Kalantidis & Avrithis, CVPR 2014]



- residual distributions closer to Gaussian assumption
- better captures the support of data distribution, like local PCA
  - multimodal (e.g. mixture) distributions
  - distributions on nonlinear manifolds

# local principal component analysis

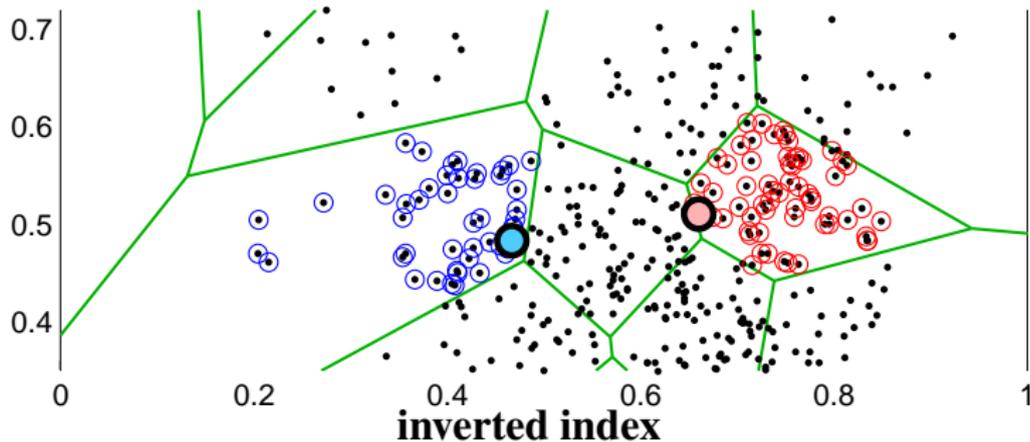
[Kambhatla & Leen 1997]



but, we are not doing dimensionality reduction!

# inverted multi-index

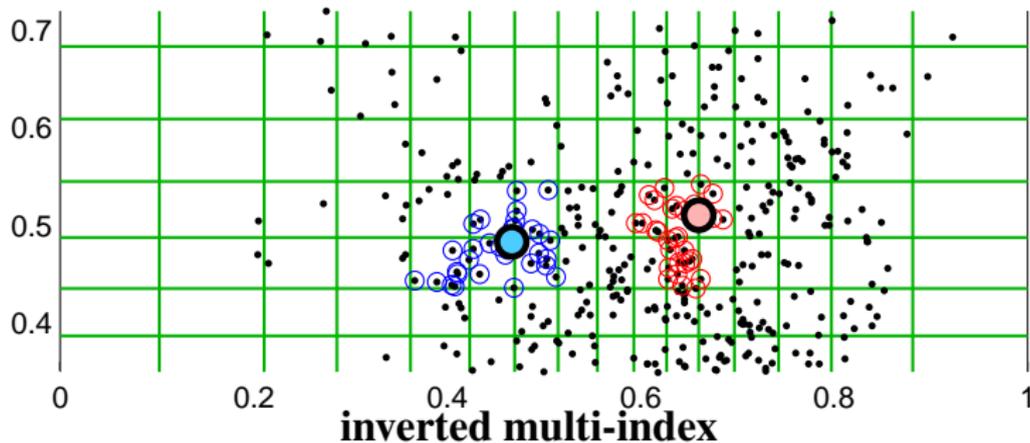
[Babenko & Lempitsky 2012]



- train codebook  $C$  from dataset  $\{\mathbf{x}_n\}$
- this codebook provides a **coarse** partition of the space

# inverted multi-index

[Babenko & Lempitsky 2012]

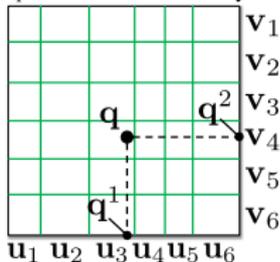


- decompose vectors as  $\mathbf{x} = (\mathbf{x}^1, \mathbf{x}^2)$
- train codebooks  $C^1, C^2$  from datasets  $\{\mathbf{x}_n^1\}, \{\mathbf{x}_n^2\}$
- induced codebook  $C^1 \times C^2$  gives a finer partition
- given query  $\mathbf{q}$ , visit cells  $(\mathbf{c}^1, \mathbf{c}^2) \in C^1 \times C^2$  in ascending order of distance to  $\mathbf{q}$ , by first computing distances to  $\mathbf{q}^1, \mathbf{q}^2$

# inverted multi-index

## multi-sequence algorithm

space subdivision via PQ



product  
quantization

$q^1$  vs.  $\mathcal{U}$

$i$	$u_{\alpha(i)}$	$r$
1	$u_3$	0.5
2	$u_4$	0.7
3	$u_5$	4
4	$u_2$	6
5	$u_1$	8
6	$u_6$	9

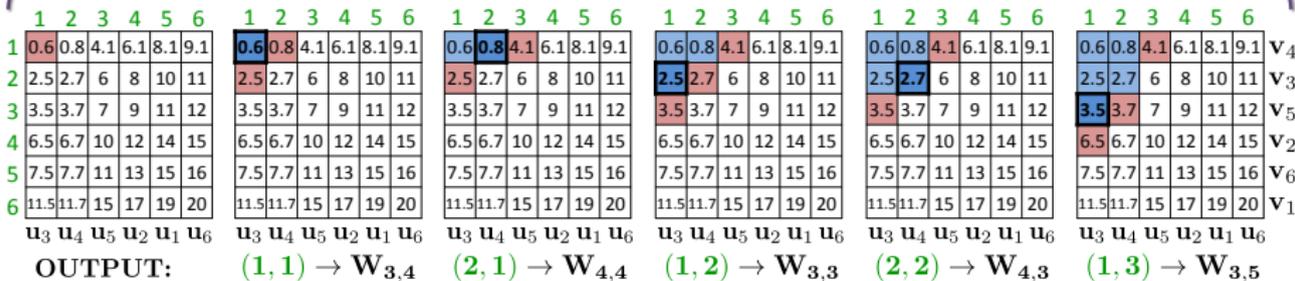
$q^2$  vs.  $\mathcal{V}$

$j$	$v_{\beta(j)}$	$s$
1	$v_4$	0.1
2	$v_3$	2
3	$v_5$	3
4	$v_2$	6
5	$v_6$	7
6	$v_1$	11



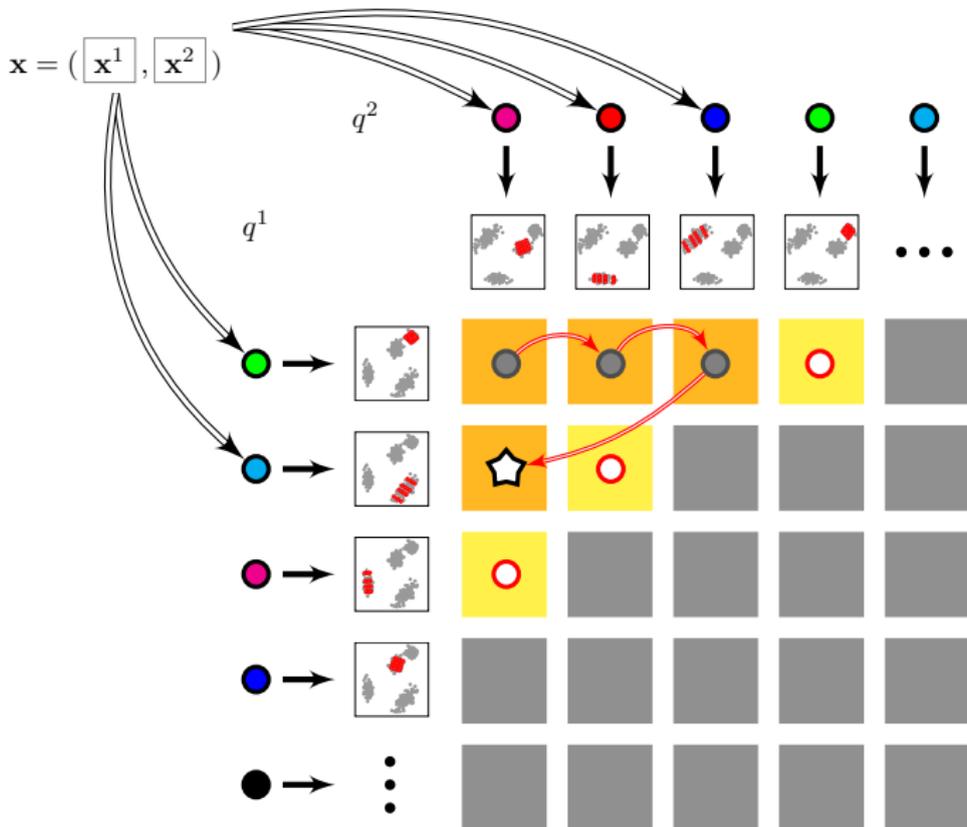
multi-  
sequence  
algorithm

$[u_{\alpha(i)} \ v_{\beta(j)}]$	$(i, j)$	$r(i) + s(j)$
$u_3 \ v_4$	(1,1)	0.6 (0.5+0.1)
$u_4 \ v_4$	(2,1)	0.8 (0.7+0.1)
$u_3 \ v_3$	(1,2)	2.5 (0.5+2)
$u_4 \ v_3$	(2,2)	2.7 (0.7+2)
$u_3 \ v_5$	(1,3)	3.5 (0.5+3)
$u_4 \ v_5$	(2,3)	3.7 (0.7+3)
$u_5 \ v_4$	(3,1)	4.1 (4+0.1)
$u_5 \ v_3$	(3,2)	6 (4+2)
$u_3 \ v_2$	(1,4)	6.5 (0.5+6)
...		



# Multi-LOPQ

[Kalantidis & Avrithis, CVPR 2014]



# comparison to state of the art

on SIFT1B, 128-bit codes

$T$	Method	$R = 1$	10	100
20K	IVFADC+R [Jégou <i>et al.</i> '11]	0.262	0.701	0.962
	LOPQ+R [Kalantidis & Avrithis '14]	<b>0.350</b>	<b>0.820</b>	<b>0.978</b>
10K	Multi-D-ADC [Babenko & Lempitsky '12]	0.304	0.665	0.740
	OMulti-D-OADC [Ge <i>et al.</i> '13]	0.345	0.725	<b>0.794</b>
	Multi-LOPQ [Kalantidis & Avrithis '14]	<b>0.430</b>	<b>0.761</b>	0.782
30K	Multi-D-ADC [Babenko & Lempitsky '12]	0.328	0.757	0.885
	OMulti-D-OADC [Ge <i>et al.</i> '13]	0.366	0.807	<b>0.913</b>
	Multi-LOPQ [Kalantidis & Avrithis '14]	<b>0.463</b>	<b>0.865</b>	0.905
100K	Multi-D-ADC [Babenko & Lempitsky '12]	0.334	0.793	0.959
	OMulti-D-OADC [Ge <i>et al.</i> '13]	0.373	0.841	<b>0.973</b>
	Multi-LOPQ [Kalantidis & Avrithis '14]	<b>0.476</b>	<b>0.919</b>	<b>0.973</b>

# image query on Flickr 100M

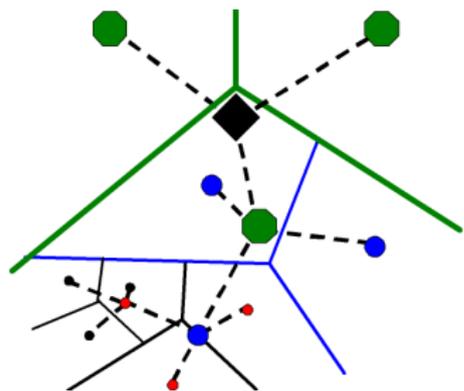
deep learned features, 4k  $\rightarrow$  128 dimensions



credit: Y. Kalantidis



# ANN search - clustering connection

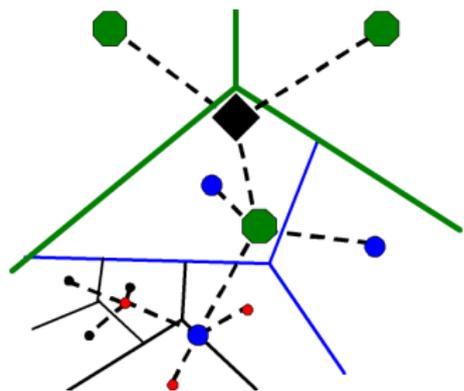


## hierarchical $k$ -means

[Nister & Stewenius 2006]

use  $k$ -means tree for ANN search

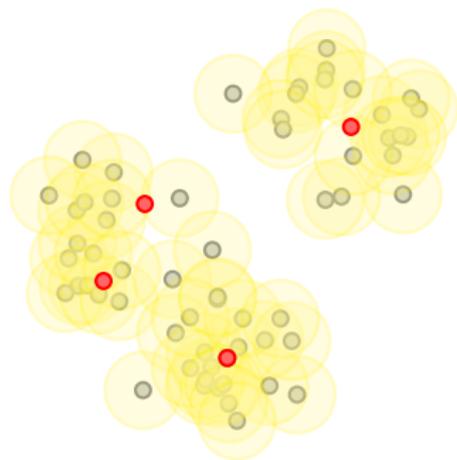
# ANN search - clustering connection



## hierarchical $k$ -means

[Nister & Stewenius 2006]

use  $k$ -means tree for ANN search

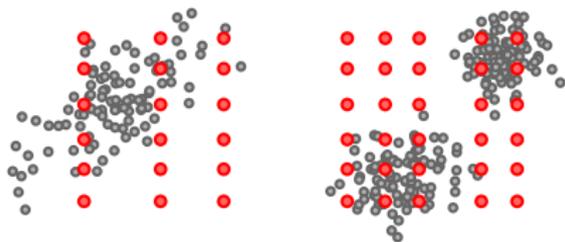


## approximate $k$ -means

[Philbin *et al.* 2007]

use ANN search to accelerate assignment step

# ANN search - clustering connection



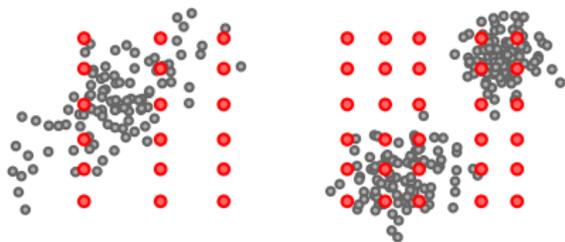
## product quantization

[Jégou *et al.* 2010]

use  $k$ -means on subspaces to  
accelerate ANN search



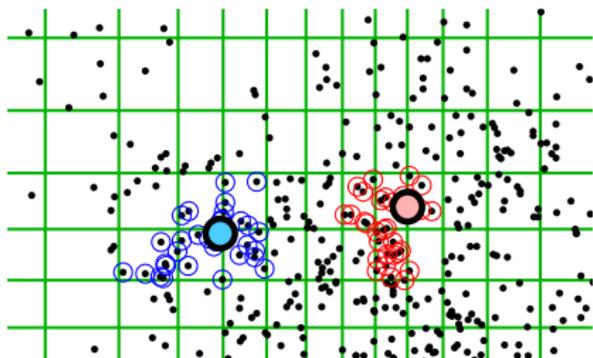
# ANN search - clustering connection



## product quantization

[Jégou *et al.* 2010]

use  $k$ -means on subspaces to  
accelerate ANN search



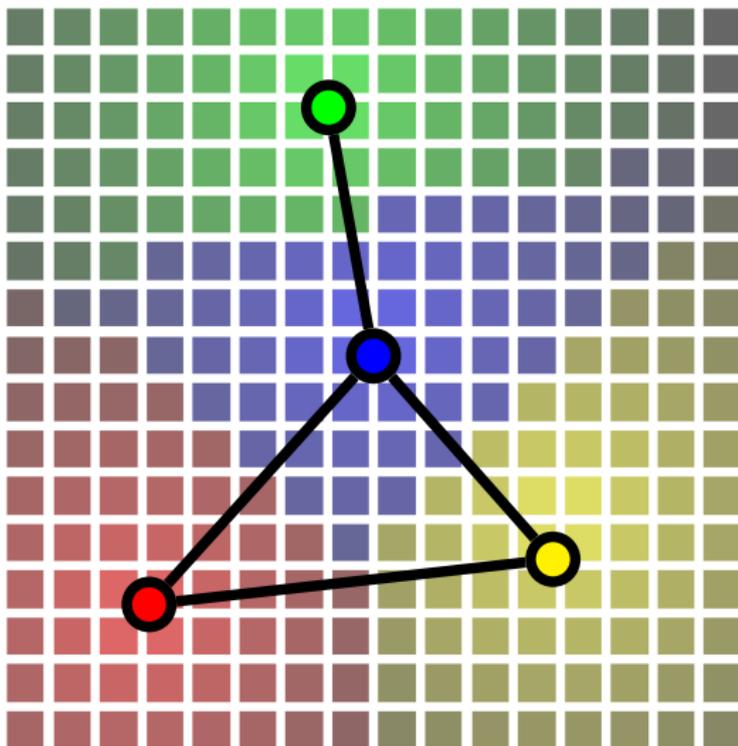
## inverted multi-index

[Babenko & Lempitsky 2012]

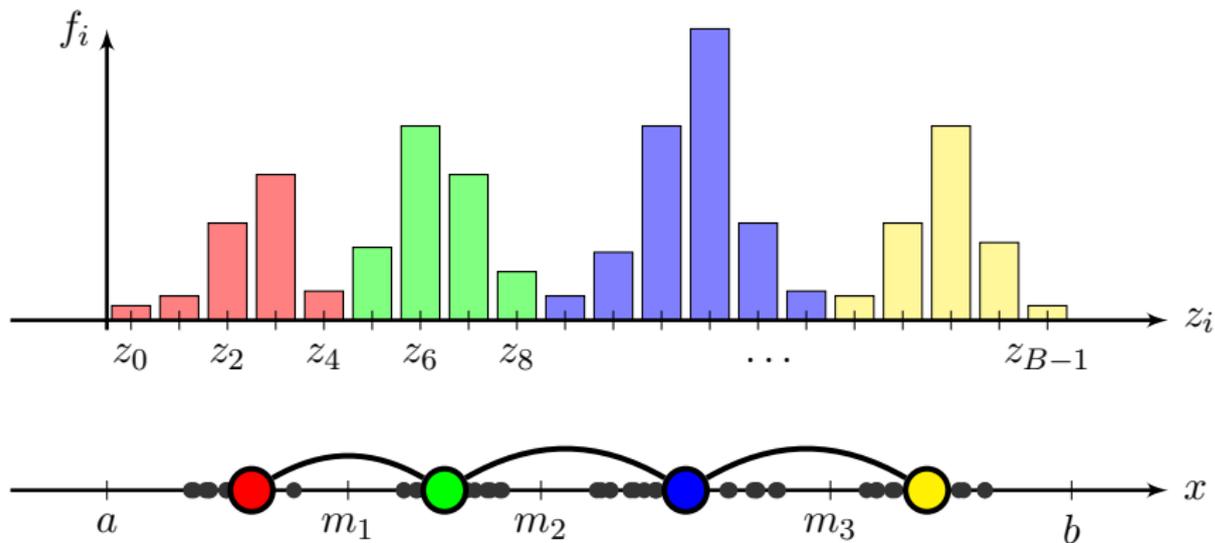
exhaustively search on subspaces  
before searching on entire space

# dimensionality-recursive vector quantization

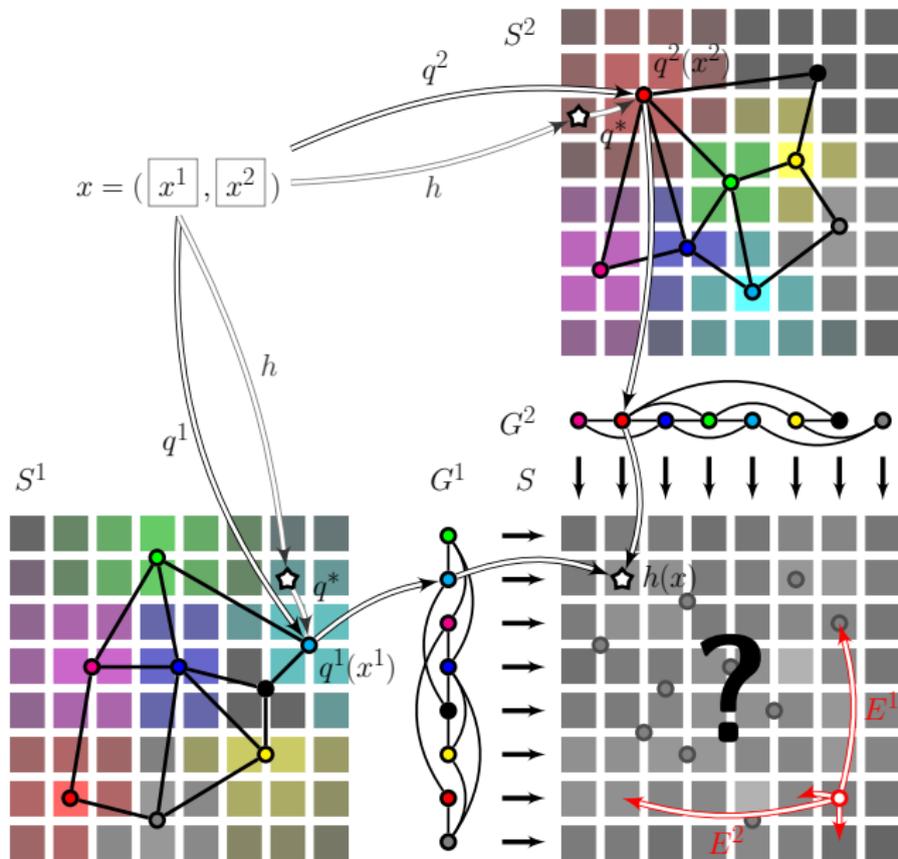
[Avrithis, ICCV 2013]



# DRVQ base case: $d = 1$



# DRVQ recursion: $d \rightarrow 2d$



## DRVQ: vector quantization

$k$	16k	8k	4k	2k	1k	512
approximate ( $\mu\text{s}$ )	0.95	0.83	0.80	0.73	0.80	0.90
exact (ms)	1.19	0.79	0.51	0.26	0.21	0.11

averaged over the  $n = 75\text{k}$  SIFT descriptors of the 55 cropped query images of *Oxford 5k*

## DRVQ: clustering

$k$	$\log k_p (d = 2^p)$						time (m)
	1	2	4	8	16	32	
16k	6	7	8	9	11	14	129.96
8k	6	7	8	9	11	13	119.43
4k	6	7	8	9	10	12	20.07
2k	5	6	7	8	9	11	2.792
1k	5	6	7	8	9	10	2.608
512	4	5	6	7	8	9	0.866
4k	approximate $k$ -means						504.2

4 codebooks at  $d = 32$  dimensions each on  $n = 12.5\text{M}$  128-dimensional SIFT descriptors of *Oxford 5k*

## DRVQ: clustering

$k$	$\log k_p (d = 2^p)$						time (m)
	1	2	4	8	16	32	
16k	6	7	8	9	11	14	129.96
8k	6	7	8	9	11	13	119.43
4k	6	7	8	9	10	12	20.07
2k	5	6	7	8	9	11	2.792
1k	5	6	7	8	9	10	2.608
512	4	5	6	7	8	9	0.866
4k	approximate $k$ -means						504.2

4 codebooks at  $d = 32$  dimensions each on  $n = 12.5\text{M}$  128-dimensional SIFT descriptors of *Oxford 5k*

# inverted-quantized $k$ -means

[Avrithis et al. ongoing]

clustering of 100M images in less than one hour on a single core



<http://viral.image.ntua.gr>

# query



# result



📍 Estimated Location 📍 Similar Image, 📍 Incorrectly geo-tagged 📍 Unavailable



**Suggested tags:** [Buxton Memorial Fountain](#), [Victoria Tower Gardens](#), [London](#)  
**Frequent user tags:** [Victoria Tower Gardens](#), [Buxton Memorial Fountain](#), [Winchester Palace](#), [Architecture](#), [Victorian gothic](#)

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**Suggested tags:** Buxton Memorial Fountain, Victoria Tower Gardens, London

**Frequent user tags:** Victoria Tower Gardens, Buxton Memorial Fountain, Winchester Palace, Architecture, Victorian gothic

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## Buxton Memorial Fountain

From Wikipedia, the free encyclopedia

The **Buxton Memorial Fountain** is a memorial and [drinking fountain](#) in [London](#), the [United Kingdom](#), that commemorates the [emancipation of slaves](#) in the [British Empire](#) in 1834.

It was commissioned by [Charles Buxton](#) MP, and was dedicated to his father [Thomas Fowell Buxton](#) along with [William Wilberforce](#), [Thomas Clarkson](#), [Thomas Babington Macaulay](#), [Henry Brougham](#) and [Stephen Lushington](#), all of whom were involved in the abolition. It was designed by Gothic architect [Samuel Sanders Teulon](#) (1812–1873) in 1865 coincidentally with the passing of the [Thirteenth Amendment to the United States Constitution](#), which effectively ended the western slave-trade.<sup>[1]</sup>

It was originally constructed in [Parliament Square](#), erected at a cost of £1,200. As part of the postwar redesign of the square it was removed in 1949 and not reinstated in its present position in [Victoria Tower Gardens](#) until 1957.<sup>[2]</sup> There were eight decorative figures of British rulers on it, but four were stolen in 1960 and four in 1971. They were replaced by fibreglass figures in 1960. By 2005 these were missing, and the fountain was no longer working. Between autumn 2006 and February 2007 restoration works were carried out. The restored fountain was unveiled on 27 March 2007 as part of the commemoration of the 200th anniversary of the act to abolish the slave trade.<sup>[3]</sup>

A memorial plaque commemorating the 150th anniversary of the [Anti-Slavery Society](#) was added in 1989.

### Description

[\[edit\]](#)

The base is octagonal, about twelve feet in diameter, having open arches on the eight sides, supported on clustered shafts of polished Devonshire marble around a large central shaft, with four massive granite basins. Surmounting the pinnacles at the angles of the octagon are eight figures of bronze, representing the different rulers of England, the [Britons](#) represented by [Caractacus](#), the [Romans](#) by [Constantine](#), the [Danes](#) by [Canute](#), the [Saxons](#) by [Alfred](#), the [Normans](#) by [William the Conqueror](#), and so on, ending with [Queen Victoria](#). The fountain bears an inscription to the effect that it is "intended as a memorial of those members of Parliament who, with Mr. [Wilberforce](#), advocated the abolition of the British slave-trade, achieved in 1807, and of those members of Parliament who, with Sir T.



The Buxton Memorial Fountain, designed by [Samuel Sanders Teulon](#), celebrating the emancipation of slaves in the [British Empire](#) in 1834, in [Victoria Tower Gardens](#), [Millbank](#), [Westminster](#), [London](#).

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## Victoria Tower Gardens

From Wikipedia, the free encyclopedia

Coordinates: 51°29′49.0″N 0°7′30.0″W﻿ / ﻿

**Victoria Tower Gardens** is a public [park](#) along the north bank of the [River Thames](#) in [London](#). As its name suggests, it is adjacent to the [Victoria Tower](#), the south-western corner of the [Palace of Westminster](#). The park, which extends southwards from the Palace to [Lambeth Bridge](#), sandwiched between [Millbank](#) and the river, also forms part of the [Thames Embankment](#).

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- [2 Transport](#)
- [3 History](#)
- [4 External links](#)
- [5 References](#)

### Features

[\[edit\]](#)

The park features:

- A reproduction of the sculpture *The Burglers of Calais* by [Auguste Rodin](#), purchased by the [British](#) Government in 1911 and positioned in the Gardens in 1915.
- A 1930 statue of the suffragette [Emmeline Pankhurst](#), by A.G. Walker.
- The [Buxton Memorial Fountain](#) – originally constructed in [Parliament Square](#), this was removed in 1940 and placed in its present position in 1967. It was commissioned by [Charles Buxton](#) MP to commemorate the emancipation of slaves in 1834, dedicated to his father [Thomas Fowell Buxton](#), and designed by Gothic architect [Samuel Sanders Teulon](#) (1812–1873) in 1865.
- A stone wall with two modern-style goats with kids – situated at the southern end of the Gardens.

### Transport

[\[edit\]](#)



Victoria Tower Gardens, 2005, with the [Buxton Memorial Fountain](#) at the front and the [Palace of Westminster](#) in the background

# VIRaL explore

The screenshot displays the VIRaL explore interface, which features a map of Venice and a grid of image thumbnails. The map shows various landmarks and locations in Venice, including Murano, Cannaregio, San Marco, and the Venetian Arsenal. The grid of thumbnails shows a variety of images, including buildings, landscapes, and people. The interface includes a search bar, a map control, and a scale bar.

**Map Control:** Map Satellite

**Scale:** 500 m / 2000 ft

**Grid of Image Thumbnails:**

Chicago	Copenhagen	Delhi
Dortmund	Dubai	Dublin
Edinburgh	Florence	Havana
Helsinki	Hong Kong	Istanbul
Krakow	Lima	Lisbon
London	Los Angeles	Madrid
New York	Paris	Petersburgh

# VIRaL explore

The screenshot displays the VIRaL explore interface. The main area is a map of Venice, Italy, with numerous small thumbnail images overlaid on it, representing different scenes or landmarks. Key locations labeled on the map include Ca' d'Oro, Scuola Grande di San Marco, Palazzo Grimani di Santa Maria Formosa, Rialto Bridge, La Fenice, San Marco, Castello, Venice, San Giorio Maggiore, Santa Maria della Salute, and Accademia. The map also shows the Grand Canal and various streets.

On the right side, there is a sidebar titled "Map Satellite" with a dropdown menu. Below the menu is a grid of city thumbnails, each with a label: Chicago, Copenhagen, Delhi, Dortmund, Dubai, Dublin, Edinburgh, Florence, Havana, Helsinki, Hong Kong, Istanbul, Krakow, Lima, Lisbon, London, Los Angeles, Madrid, New York, Paris, and Petersburg. The thumbnails show various cityscapes, landmarks, and buildings.

At the bottom of the interface, there are navigation controls including a compass, a person icon, a zoom in (+) and zoom out (-) button, and a scale bar showing 200 meters and 500 feet. At the very bottom, there are several small icons for navigation and search.

# VIRaL routes

Map Satellite

**Identified landmarks**

Ca' Pesaro

**Frequent user tags**

palazzo, italia - venecia, grand canal

**User images**

**Similar images**

Viewing Venice by ykaland

Change photo set

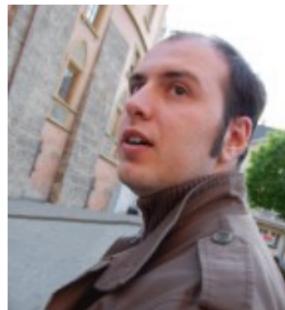
# credits



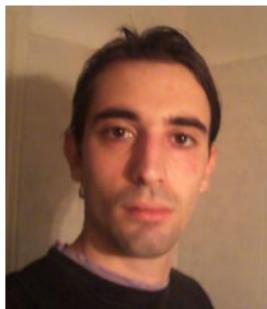
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Giorgos Tolias



Christos Varitimidis



Kimon Kontosis



Marios Phinikettos



Kostas Rapantzikos

<http://image.ntua.gr/iva/research/>

**thank you!**