

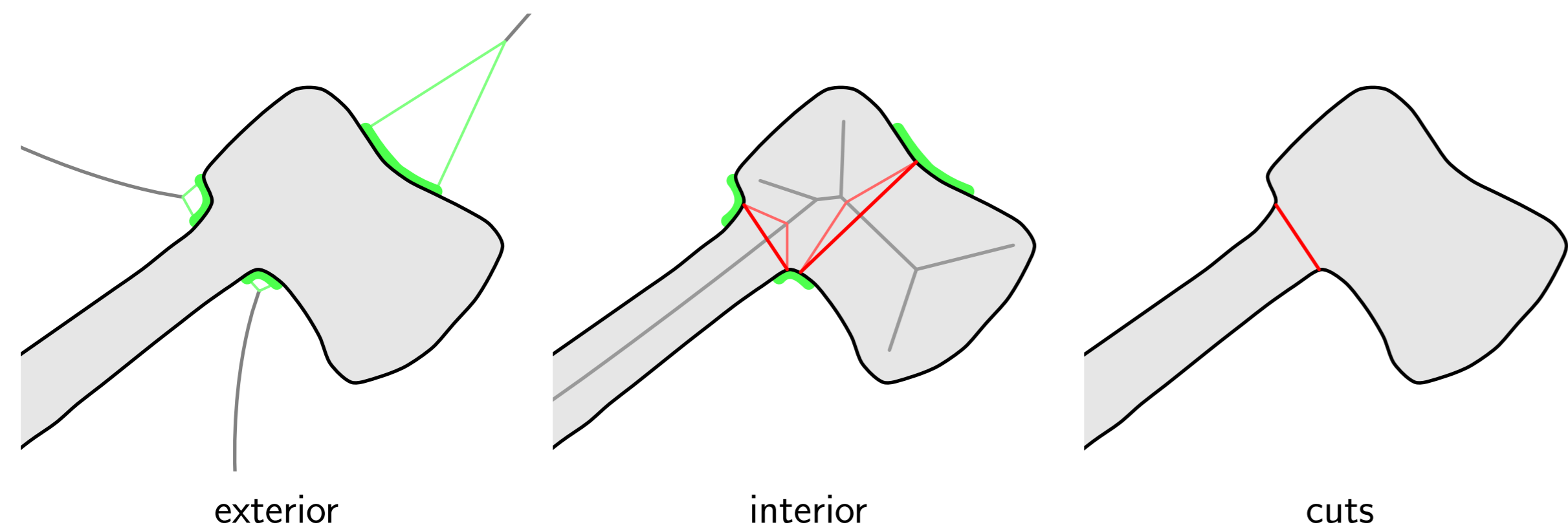
Planar Shape Decomposition Made Simple

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Motivation

- Planar shape decomposition without global optimization or differentiation
- All information available from (exterior and interior) medial axis representation
- Most rules and salience measure from psychophysical studies accommodated in a simple computational model



Shape Representation

- A planar shape is a set $X \subset \mathbb{R}^2$; its boundary ∂X is a finite union of mutually disjoint simple closed curves

Medial axis [1]

- The **distance map** $\mathcal{D}(X) : X \rightarrow \mathbb{R}$ is a function mapping each point $y \in X$ to

$$\mathcal{D}(X)(y) = \inf_{x \in \partial X} \|y - x\|$$

- For $y \in \mathbb{R}^2$, the **projection** or **contact set**

$$\pi(y) = \{x \in \partial X : \|y - x\| = \mathcal{D}(X)(y)\}$$

- is the set of points on the boundary at minimal distance to y ; each $x \in \pi(y)$ is a projection or contact point of y

- The (interior) **medial axis**

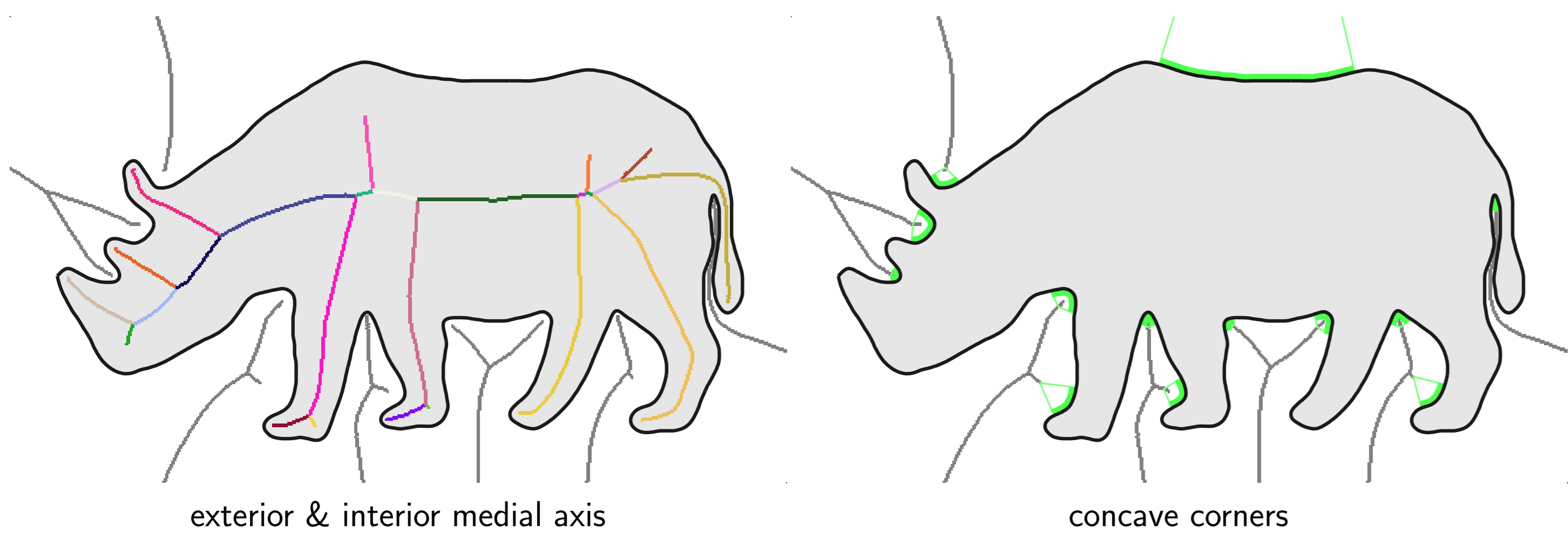
$$\mathcal{M}(X) = \{x \in \mathbb{R}^2 : |\pi(x)| > 1\}$$

- is the set of points with more than one projection points

- The **exterior** medial axis of X is the medial axis of its complement $\mathbb{R}^2 \setminus X$

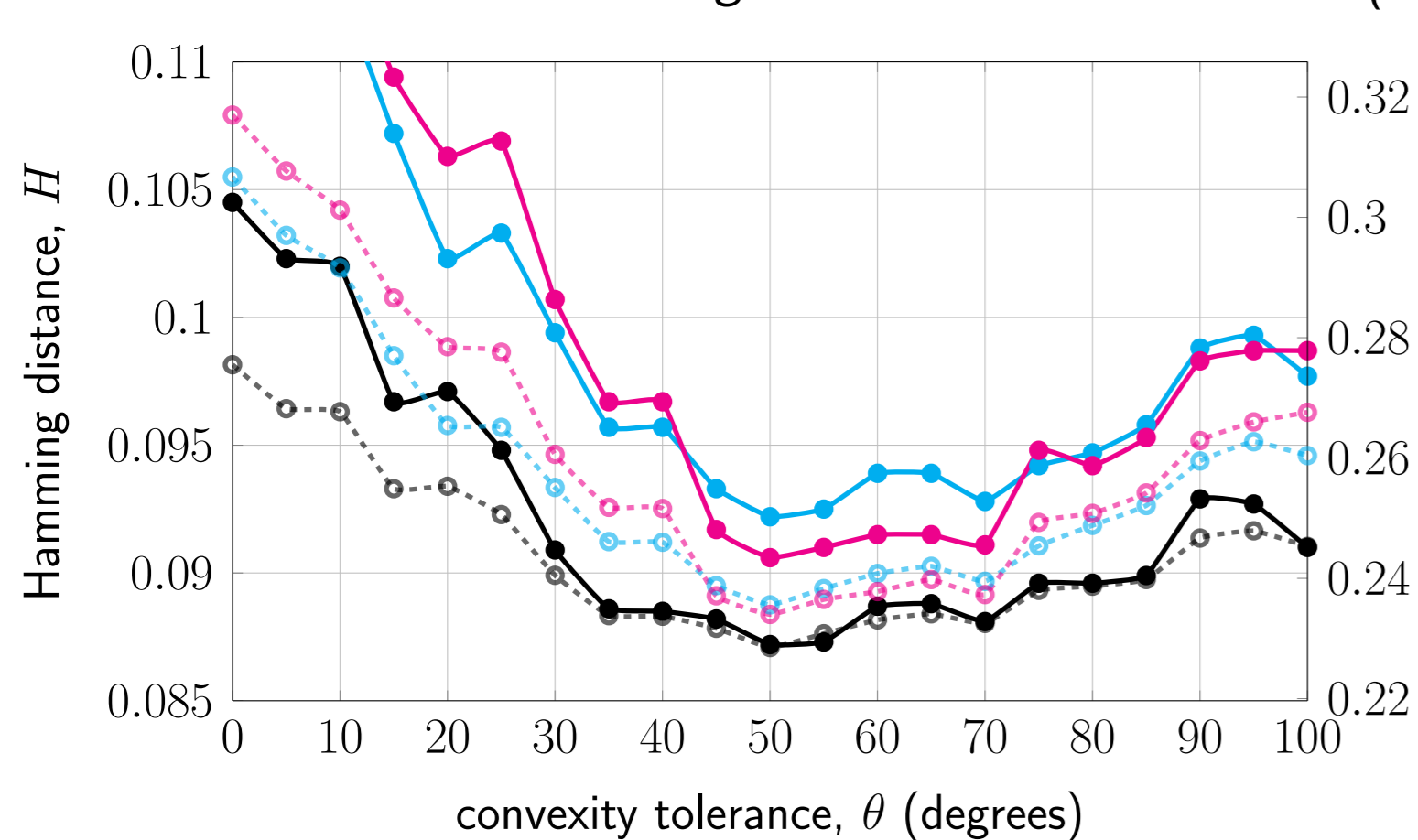
Construction [2]

- Given two points $x, y \in \partial X$, the **arc length** $\ell(x, y)$ is the length of the minimal arc of ∂X having x, y as endpoints or ∞ if no such arc exists
- Given a point z , its **chord residue** $r(z) = \sup_{x, y \in \pi(z)} \ell(x, y) - \|x - y\|$ is the maximal difference between arc length and chord length over all pairs of points in its projection
- Construction begins at local maxima of distance map and propagates as long as the residue is higher than a given threshold $\sigma > 0$



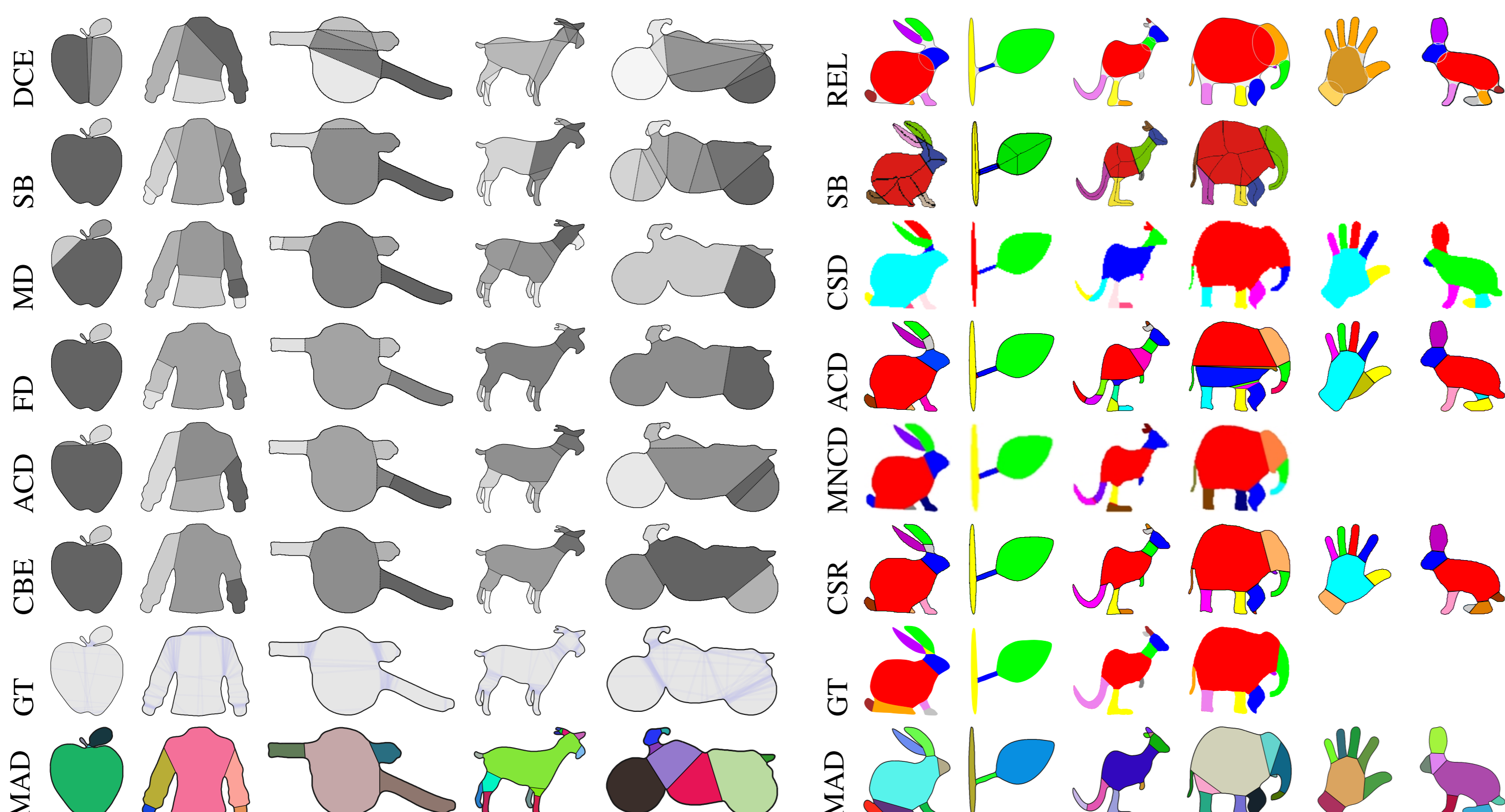
Quantitative Evaluation

- Evaluation measures: *Hamming distance* and *Rand Index (Jaccard distance)*



	average		majority	
	H	R	H	R
DCE	0.208	0.497	0.188	0.466
SB	0.163	0.402	0.131	0.335
MD	0.151	0.371	0.126	0.328
FD	0.145	0.350	0.112	0.267
ACD	0.128	0.323	0.092	0.251
MAD	0.126	0.317	0.096	0.247
MAD-opt	0.118	0.303	0.085	0.225
CBE	0.111	0.288	0.069	0.186
Human	0.128	0.312	0.093	0.245
Baseline	0.160	0.424	0.140	0.376

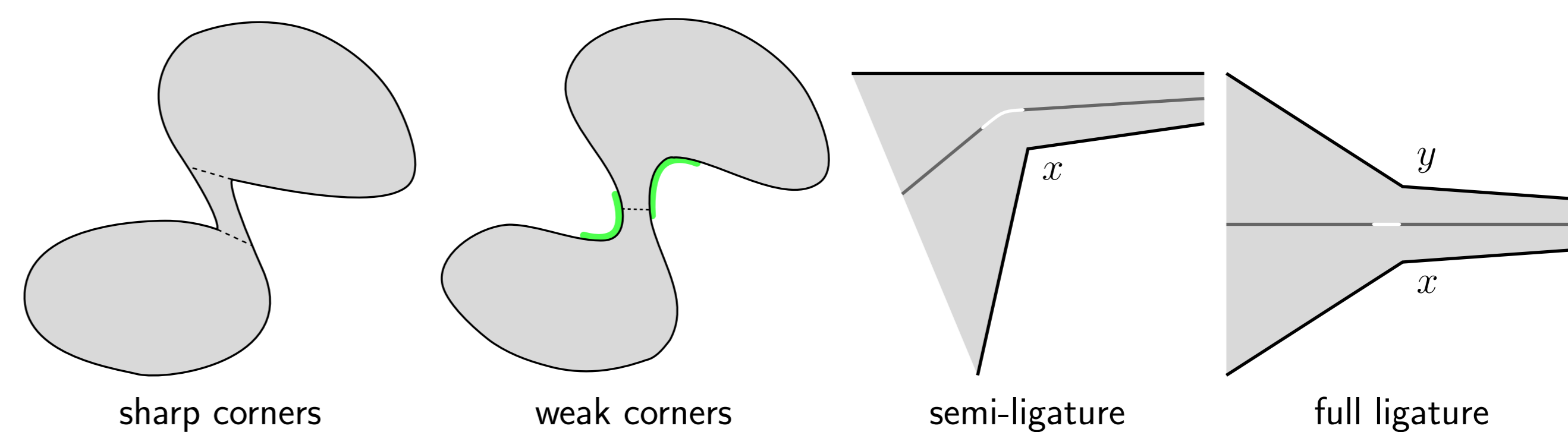
Qualitative Evaluation



Shape Decomposition

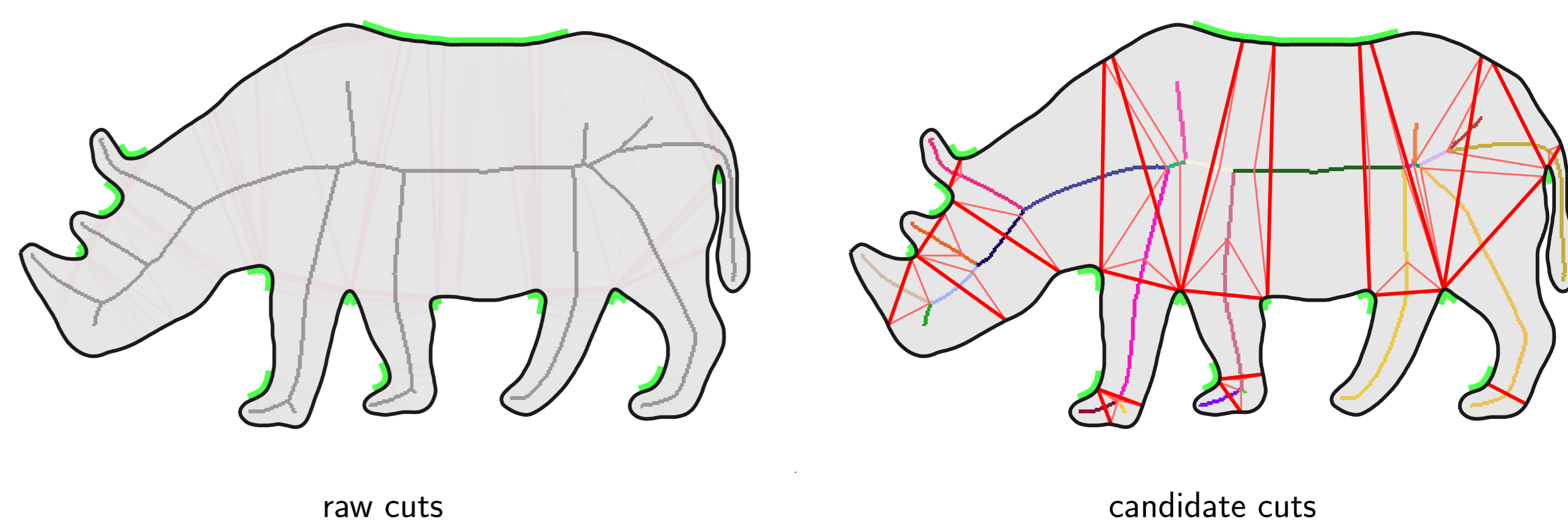
Minima rule

- A shape should be cut at points of **negative minima of curvature** [3]
- But these are exactly projection points of end vertices of the exterior medial axis [1]
- Moreover, one may get not just one boundary point but an entire arc, called a **(concave) corner**
- Without differentiation, an end-vertex with its two projection points determine the position, spatial extent, orientation and strength of each concavity



Symmetry

- A **cut** of a shape X is a line segment connecting two points of ∂X
- All prior work examines all possible pairs of points on ∂X as candidate cut endpoints; we only consider pairs of points that are projection points of the same point of the interior medial axis
- A cut may have one or two corner points as endpoints, called **single** or **double** cut respectively
- Raw cuts**: traverse interior medial axis collecting all pairs of projection points such that at least one lies on a corner; this is stronger than requiring cuts to cross an axis of **local symmetry** [3]

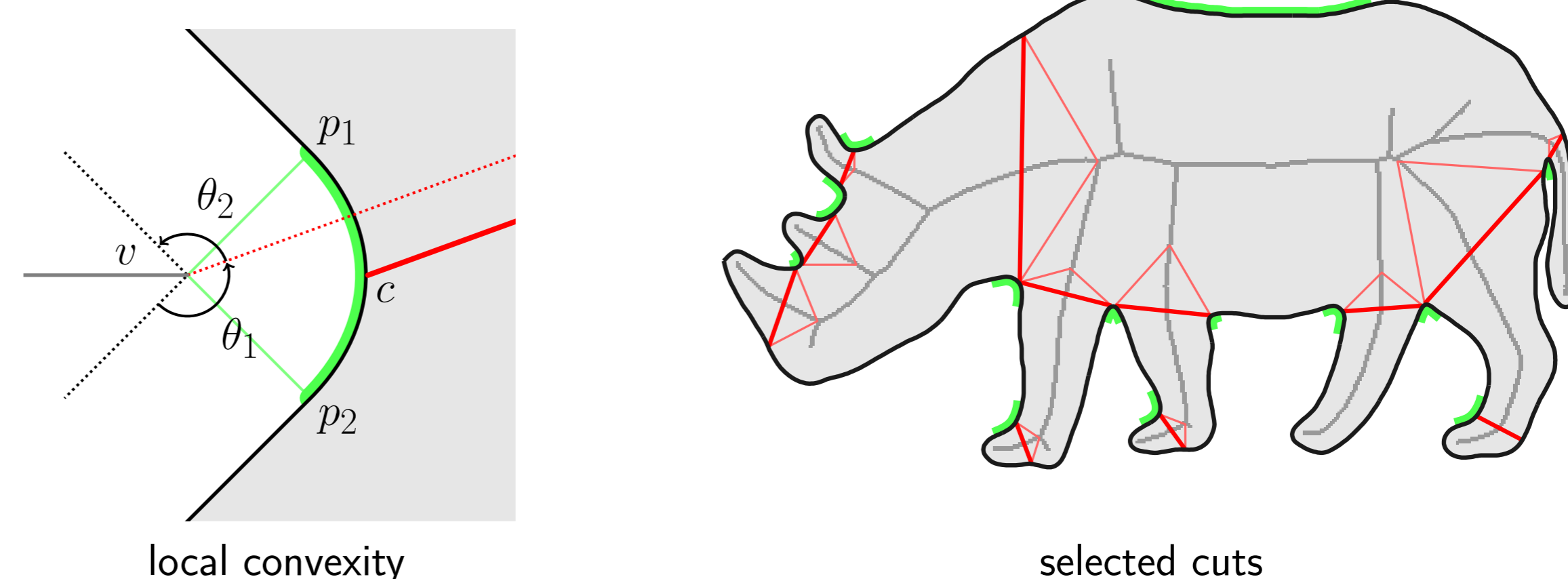


Equivalence

- Select **candidate cuts** by applying equivalence rules on raw cuts
- Branch equivalence**: two cuts on the same branch whose endpoints share at least one corner; double cuts have priority over single cuts
- Corner equivalence**: two (double) cuts whose endpoints lie on the same pair of corners; the cut with the maximal protrusion strength is selected

Salience measures

- Protrusion strength**: ratio of cut length to arc length; select cuts with protrusion less than p



Local convexity & short-cut rule

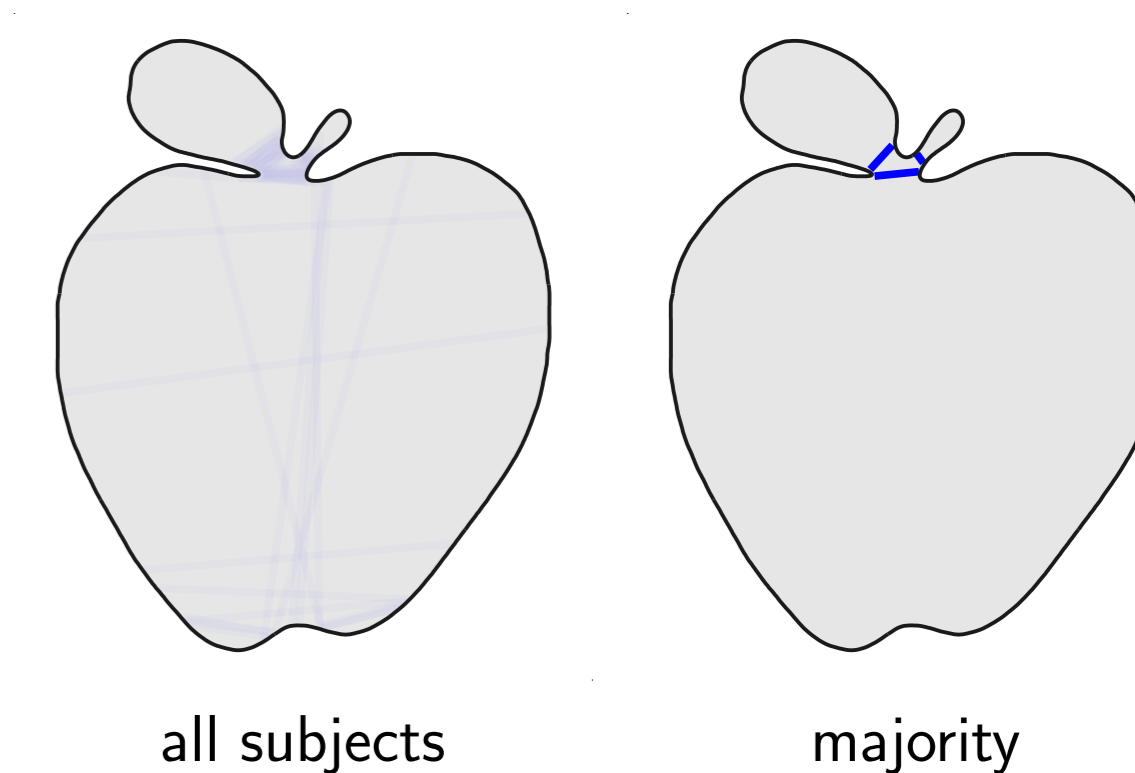
- Most approaches seek the minimal number of cuts such that each shape part is approximately convex
- But negative minima of curvature are exactly points where the shape is locally maximally concave
- For each corner, we select independently the minimal number of cuts such that the interior angle of each part is less than $\pi + \theta$, where θ is a tolerance
- Priority given according to **short-cut rule** [4], but arbitrary salience measures apply

Dataset

- Snodgrass and Vanderwart (S&V) everyday object dataset contains 260 line drawings
- De Winter and Wagemans dataset [5] evaluates exactly segmentation of 88 object outlines
- The subset has been converted to smooth outlines and each segmented by 39.5 subjects on average
- For each shape there are 122.4 part-cuts, that is 3.1 cuts per subject on average

Majority Voting

- Part-cuts of human subjects are typically inconsistent: evaluate on **majority** cuts
- Apply agglomerative clustering on all human cuts according to arc distance
- Select cluster representatives by averaging endpoints on the parametrization of the boundary curve
- Discard cluster with less than t votes



References

- Choi *et al.* Mathematical theory of medial axis transform. *Pacific Journal of Mathematics*, 1997.
- Avrithis & Rapantzikos. The medial feature detector: stable regions from image boundaries. *ICCV*, 2011.
- Hoffman & Richards. Parts of recognition. *Cognition*, 1984.
- Singh *et al.* Parsing silhouettes: the short-cut rule. *Perception and Psychophysics*, 1999.
- De Winter & Wagemans. Segmentation of object outlines into parts. *Cognition*, 2006.