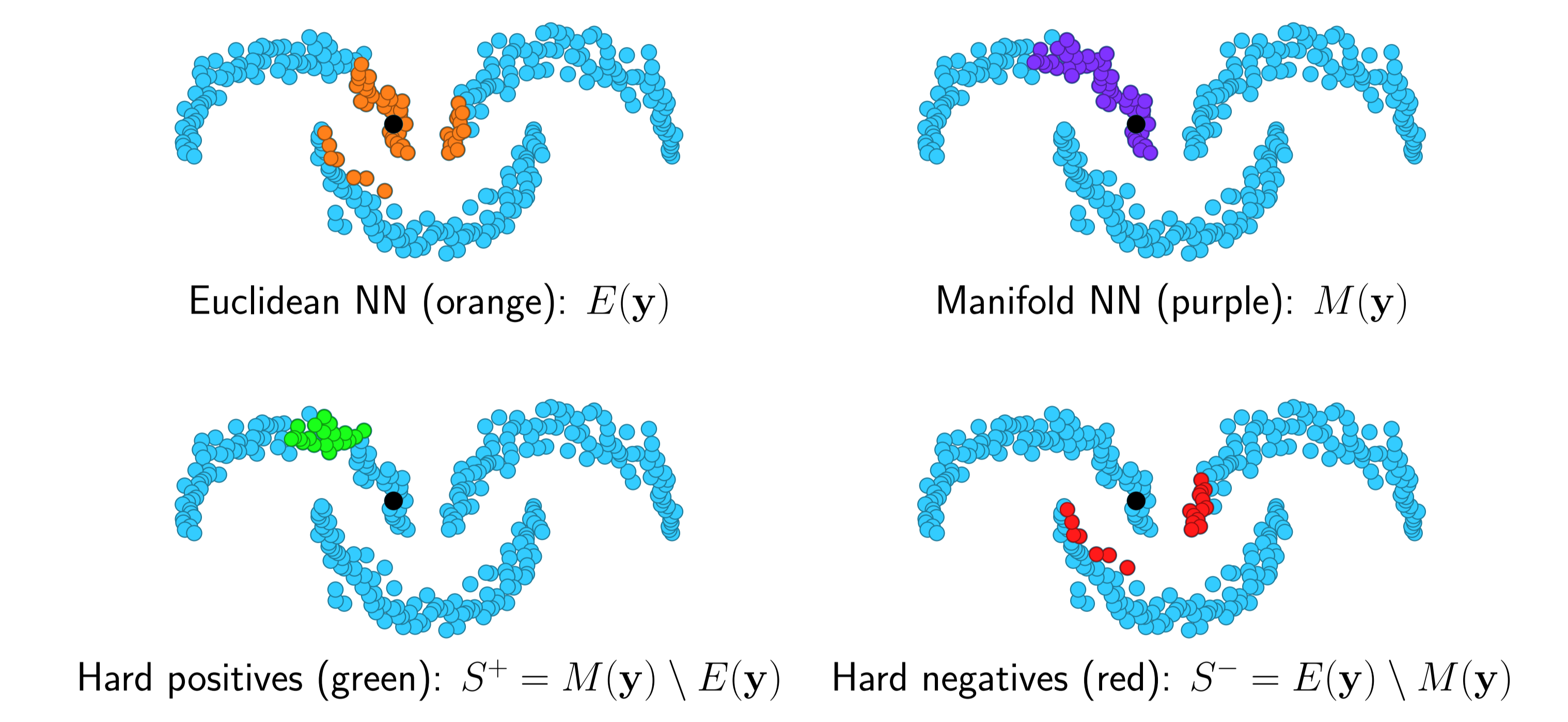


Goal: unsupervised mining of training samples



Learn descriptors that perform as manifold search



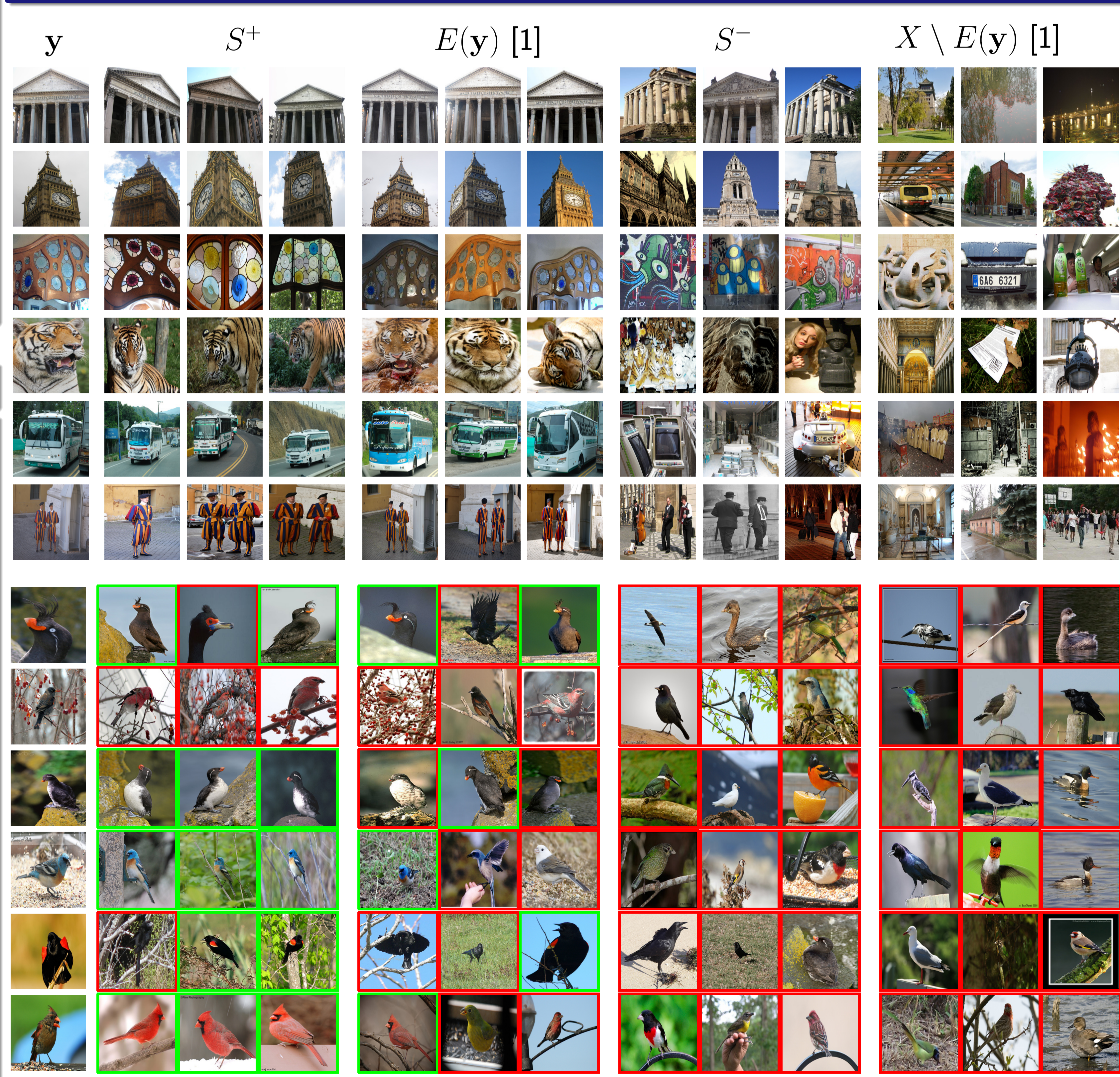
Mining on Manifolds (MoM): Approach

1. Input: unordered collection of n images
 2. Construct affinity matrix $A = (a_{ij}) \in \mathbb{R}^{n \times n}$
 3. Compute stationary prob. distribution π of random walk on A .
 4. Anchor selection: local maxima of π on A .
 5. For each anchor y
 - Top-k manifold ($M(y)$) and Euclidean ($E(y)$) neighbors.
 - Choose positive images:
$$S^+(y) = \{x \in X : x \in M(y) \setminus E(y)\}$$
 - Choose negative images:
$$S^-(y) = \{x \in X : x \in E(y) \setminus M(y)\}.$$
- see poster 2778 for manifold search, *a.k.a diffusion*

Anchor images



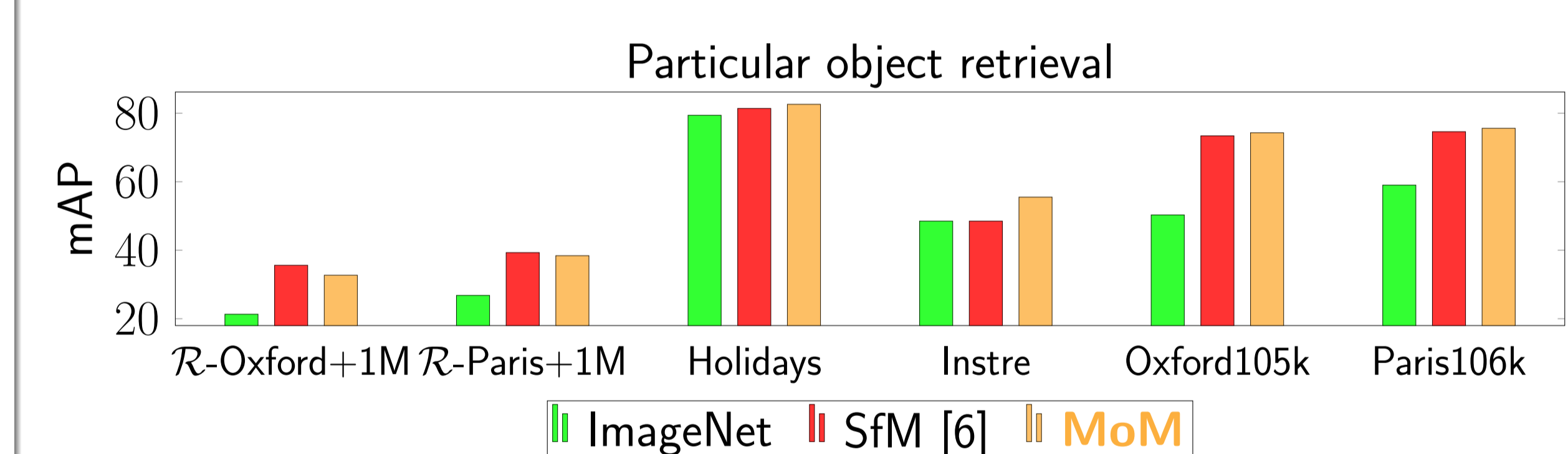
Positive and negative images



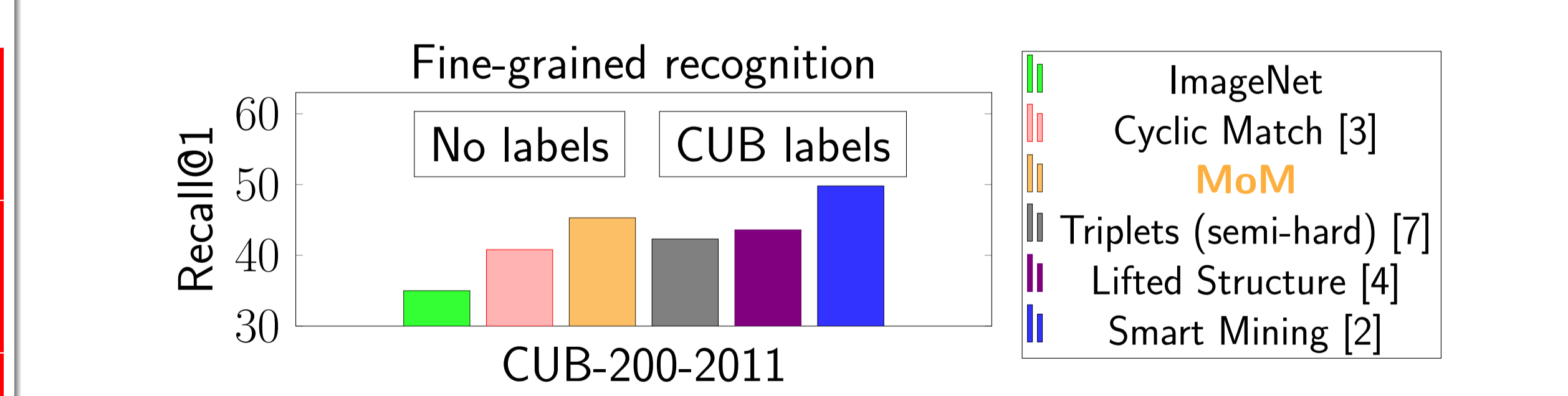
Applications

- ### Particular object retrieval
- Training set: 1M unlabeled Flickr images
 - Extract R-MAC descriptors with pre-trained network
 - Mine 1k anchors
 - Mine positive and negative pools per anchor (50 images per pool)
 - Train MAC image descriptors as in Radenović *et al.* [6]
 - Test sets: Oxford, Paris, Holidays, and Instre datasets
- ### Fine-grained categorization
- Training set: images for 100 CUB200-2011 classes, as in [4] but unlabeled
 - Extract R-MAC descriptors with pre-trained network
 - Set each training image as anchor
 - Mine positive and negative pools per anchor (50 images per pool)
 - Train 64D image descriptors with triplet loss
 - Test set: remaining 100 CUB200-2011 classes, standard benchmark [4]

Experiments



See paper 2730 [5] for \mathcal{R} -Oxford and \mathcal{R} -Paris benchmarks.



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