

Motivation

- ▶ **Problem:** Few-shot learning by using unlabelled data
- ▶ Limited labeled data make the problem fundamentally hard
- ▶ Available unlabeled data that can be used to improve accuracy performance
- ▶ **Solution:** Incorporate multiple ideas to design a novel algorithm
- ▶ Exploit the manifold structure of the data to classify the unlabelled data
- ▶ Select the most likely correctly classified predictions to augment labelled dataset and iteratively classify all available unlabeled data

Problem definition

Pre-training:

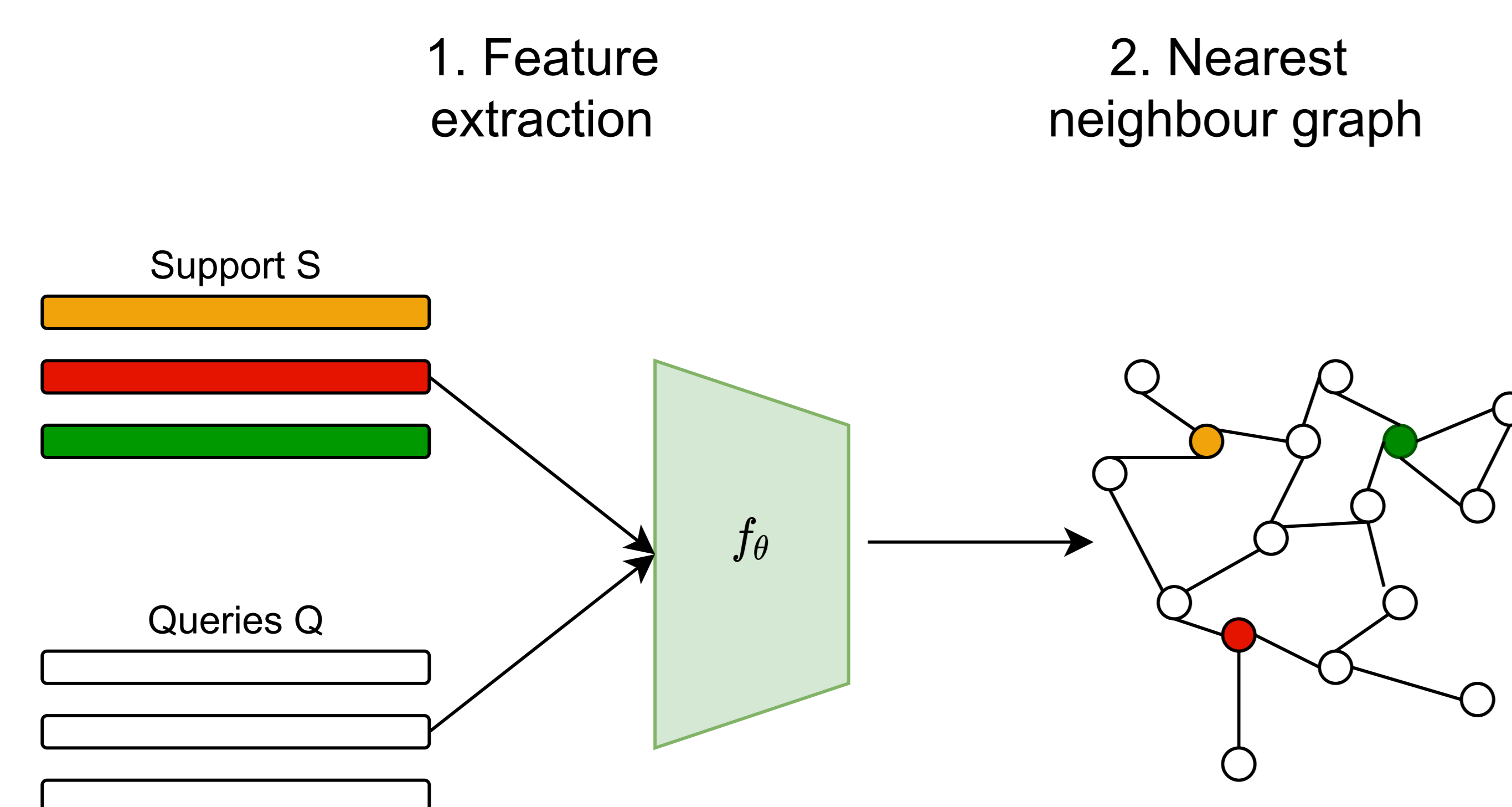
- ▶ We use publicly available pre-trained networks from published works
- ▶ Base class dataset: $D_{\text{base}} := \{(x_i, y_i)\}_{i=1}^I$ where $y_i \in C_{\text{base}}$
- ▶ Embedding network $f_\theta : \mathcal{X} \rightarrow \mathbb{R}^d$ is trained on D_{base}

Inference stage

- ▶ We focus on transductive and semi-supervised few-shot learning
- ▶ Novel class dataset D_{novel} with C_{novel} disjoint from C_{base}
- ▶ Assume access to f_θ , a support set, S , a query set, Q and in the semi-supervised setting also an unlabelled set, U

Nearest neighbour graph

- ▶ Embed all examples from S and Q into feature vectors and ℓ_1 -normalize them, where T is the total amount of examples both labelled and unlabelled
- ▶ Construct a k -nearest neighbour graph using all the features from S and Q

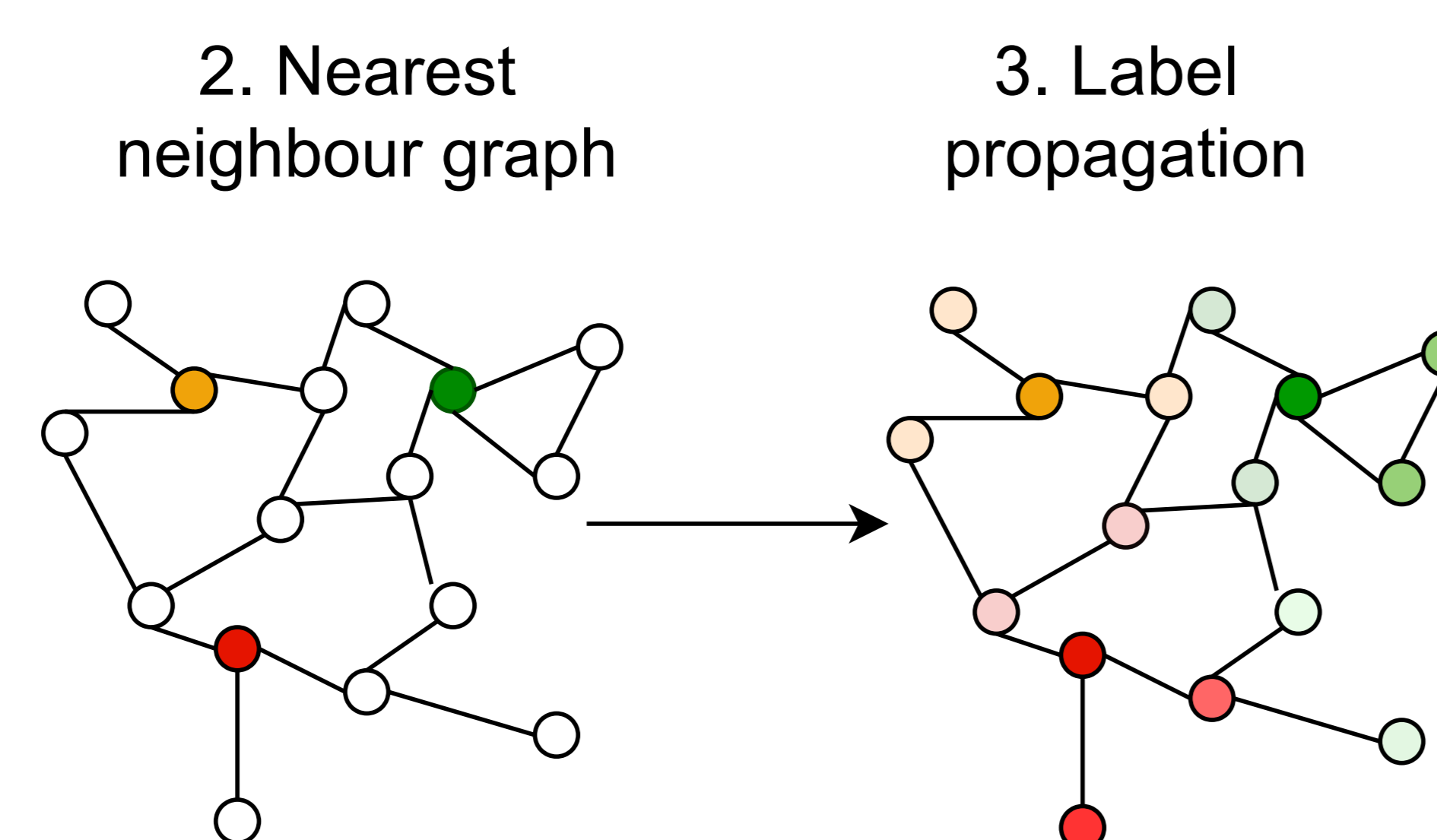


Label propagation

- ▶ Define the *label matrix* Y
- ▶ Label propagation to obtain a class probability distribution for every query

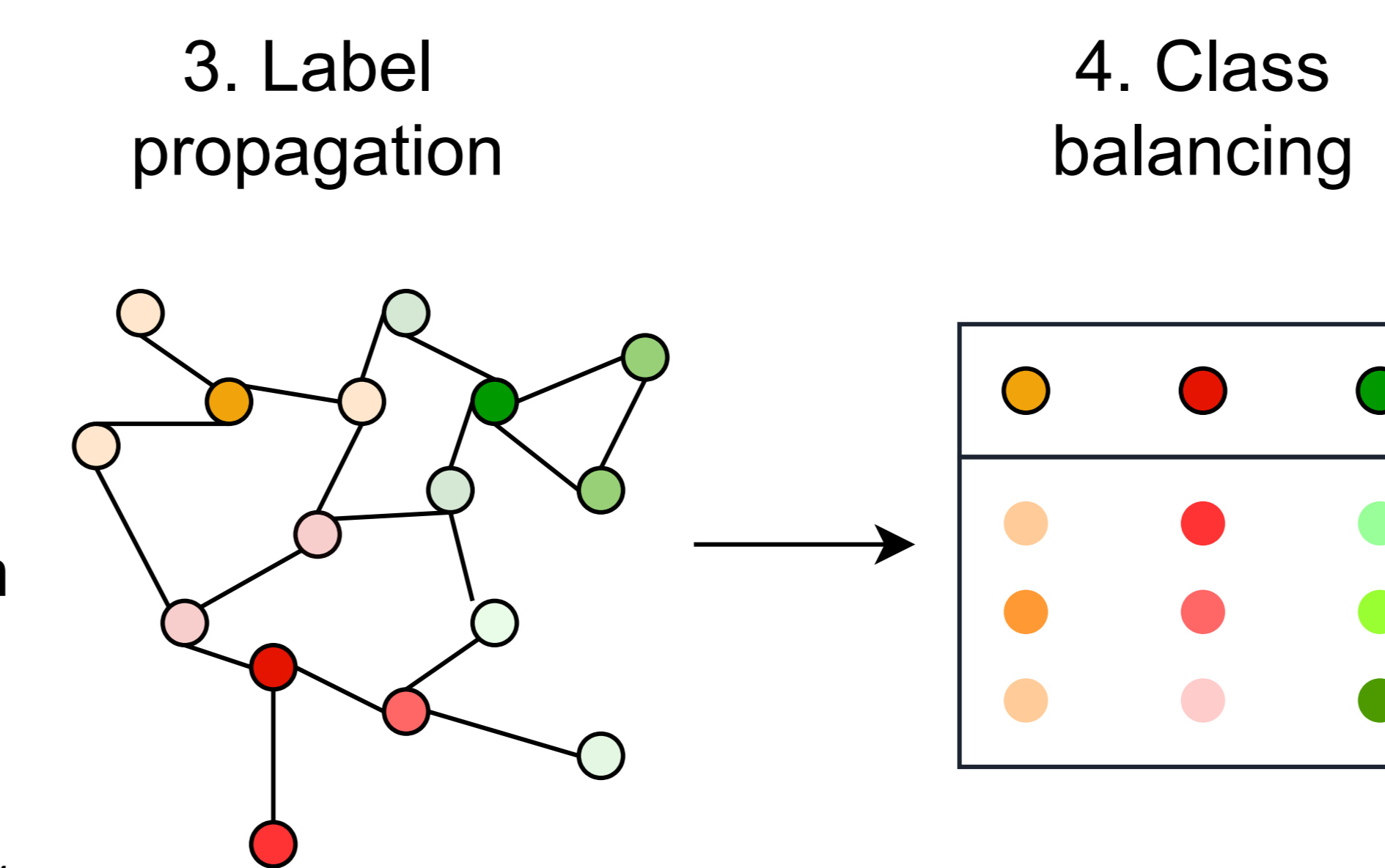
$$Z := (I - \alpha W)^{-1} Y, \quad (1)$$

where $\alpha \in [0, 1)$ is a hyperparameter, N is the number of classes and W is the adjacency matrix obtained from the construction of the nearest neighbour graph



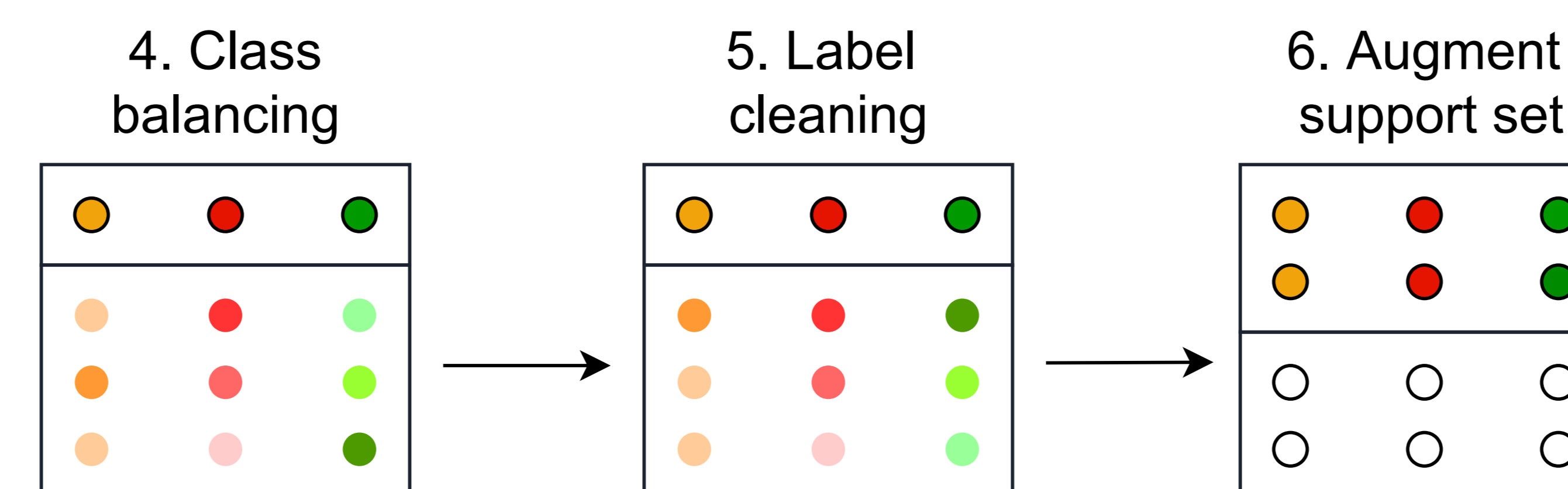
Class balancing

- ▶ Use the output matrix from the label propagation part
- ▶ We incorporate prior information in the class balancing regime by setting a row-wise sum \mathbf{p} and a column-wise sum \mathbf{q} as restrictions
- ▶ We search for a *transport plan* through the use of Sinkhorn-Knopp algorithm [2], i.e., iteratively normalizing rows and columns to the respective \mathbf{q} and \mathbf{q} until convergence



Label cleaning

- ▶ In order to identify the most likely correctly classified labels, we interpret the problem as *learning with noisy labels*
- ▶ We train an N -way linear classifier with large learning rate on both labeled and pseudo-labeled data
- ▶ For every class, we select the 3 pseudo-labels with the lowest loss value and treat them as labeled examples
- ▶ Iterate the procedure until all queries are classified



Implementation details

- ▶ We use PyTorch, FAISS and scikit-learn

Ablation study

Label propagation

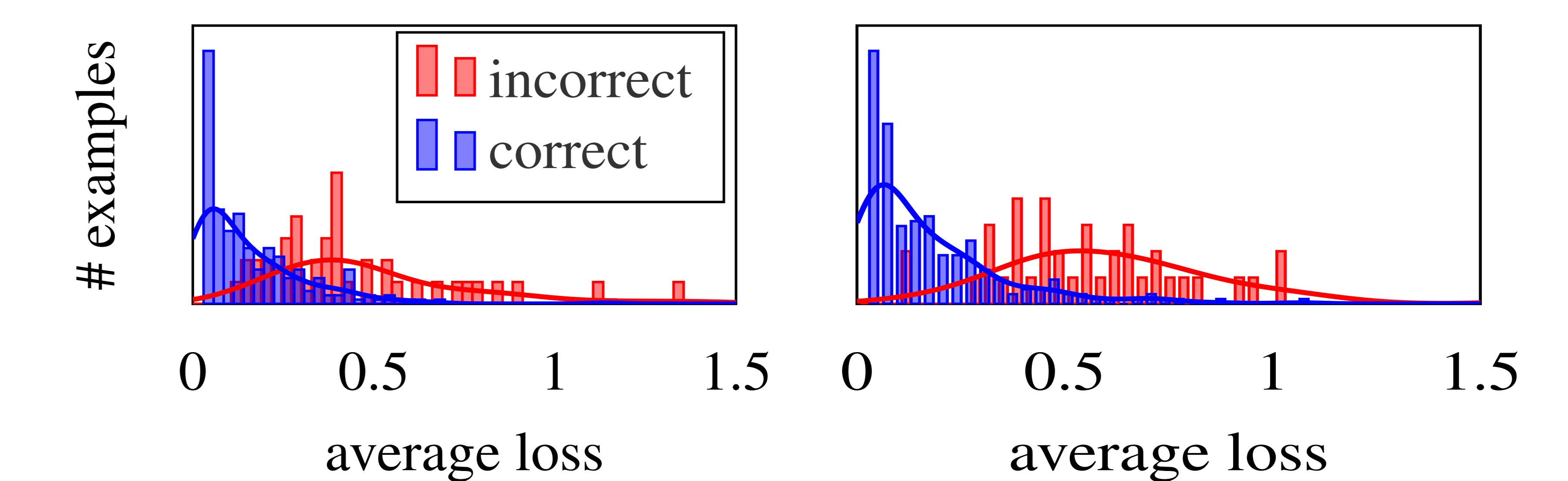
INFERENCE	RESNET-12A		WRN-28-10	
	1-shot	5-shot	1-shot	5-shot
Inductive classifier	56.30 \pm 0.62	75.59 \pm 0.47	68.17 \pm 0.60	84.33 \pm 0.43
Label Propagation	61.09 \pm 0.70	75.32 \pm 0.50	74.24 \pm 0.68	84.09 \pm 0.42

Class balancing

BALANCING NETWORK	NETWORK	miniIMAGENET		tieredIMAGENET	
		1-shot	5-shot	1-shot	5-shot
None	WRN-28-10	78.06 \pm 0.82	87.80 \pm 0.42	86.04 \pm 0.73	90.74 \pm 0.46
True	WRN-28-10	82.68 \pm 0.82	89.07 \pm 0.41	89.17 \pm 0.70	92.67 \pm 0.44

Ablation study

Label cleaning



Iterative procedure

INFERENCE	RESNET-12A		WRN-28-10	
	1-shot	5-shot	1-shot	5-shot
Non-iterative	65.04 \pm 0.75	76.82 \pm 0.50	79.42 \pm 0.69	85.34 \pm 0.43
iterative (iLPC)	69.79 \pm 0.99	79.82 \pm 0.55	83.05 \pm 0.79	88.82 \pm 0.42

State of the art comparisons

Transductive few-shot learning:

METHOD	NETWORK	miniIMAGENET		tieredIMAGENET		CIFAR-FS	
		1-shot	5-shot	1-shot	5-shot	1-shot	5-shot
LR+ICI [3]*	ResNet-12A	66.85 \pm 0.92	78.89 \pm 0.55	82.40 \pm 0.84	88.80 \pm 0.50	75.36 \pm 0.97	84.57 \pm 0.57
iLPC (ours)	ResNet-12A	69.79 \pm 0.99	79.82 \pm 0.55	83.49 \pm 0.88	89.48 \pm 0.47	89.00 \pm 0.70	92.74 \pm 0.35
PT+MAP [1]*	WRN-28-10	82.88 \pm 0.73	88.78 \pm 0.40	88.15 \pm 0.71	92.32 \pm 0.40	86.91 \pm 0.72	90.50 \pm 0.49
LR+ICI [3]*	WRN-28-10	80.61 \pm 0.80	87.93 \pm 0.44	86.79 \pm 0.76	91.73 \pm 0.40	84.88 \pm 0.79	89.75 \pm 0.48
iLPC (ours)	WRN-28-10	83.05 \pm 0.79	88.82 \pm 0.42	88.50 \pm 0.75	92.46 \pm 0.42	86.51 \pm 0.75	90.60 \pm 0.48

Transductive inference, comparison with LR+ICI [3] and PT+MAP [1]. *: our reproduction with official code on our datasets.

METHOD	NETWORK	miniIMAGENET		tieredIMAGENET		CIFAR-FS	
		1-shot	5-shot	1-shot	5-shot	1-shot	5-shot
LR+ICI [3]*	WRN-28-10	82.38 \pm 0.86	88.78 \pm 0.39	88.59 \pm 0.74	92.11 \pm 0.39	86.39 \pm 0.79	90.02 \pm 0.49
PT+MAP [1]*	WRN-28-10	83.79 \pm 0.71	88.94 \pm 0.33	88.87 \pm 0.64	92.01 \pm 0.36	87.63 \pm 0.66	90.15 \pm 0.46
iLPC (ours)	WRN-28-10	85.98 \pm 0.74	90.54 \pm 0.31	90.02 \pm 0.70	92.94 \pm 0.37	88.54 \pm 0.68	90.92 \pm 0.46

Transductive inference, 50 queries per class. *: our reproduction with official code on our datasets.

Semi-supervised few-shot learning:

METHOD	NETWORK SPLIT	miniIMAGENET		tieredIMAGENET		CIFAR-FS	
		1-shot	5-shot	1-shot	5-shot	1-shot	5-shot
LR+ICI [3]*	ResNet-12A 30/50	67.57 \pm 0.97	79.07 \pm 0.56	83.32 \pm 0.87	89.06 \pm 0.51	75.99 \pm 0.98	84.01 \pm 0.62
iLPC (ours)	ResNet-12A 30/50	70.99 \pm 0.91	81.06 \pm 0.49	85.04 \pm 0.79	89.63 \pm 0.47	78.57 \pm 0.80	85.84 \pm 0.56
LR+ICI [3]*	WRN-28-10 30/50	81.31 \pm 0.84	88.53 \pm 0.43	88.48 \pm 0.67	92.03 \pm 0.43	86.03 \pm 0.77	89.57 \pm 0.53
PT+MAP [1]†	WRN-28-10 30/50	83.14 \pm 0.72	88.95 \pm 0.38	89.16 \pm 0.61	92.30 \pm 0.39	87.05 \pm 0.69	89.98 \pm 0.49
iLPC (ours)	WRN-28-10 30/50	83.58 \pm 0.79	89.68 \pm 0.37	89.35 \pm 0.68	92.61 \pm 0.39	87.03 \pm 0.72	90.34 \pm 0.50

Semi-supervised few-shot learning, comparison with [3, 1]. *: our reproduction with official code on our datasets. †: our adaptation to semi-supervised, based on official code.

[1] Y. Hu, V. Gripon, and S. Pateux. Leveraging the feature distribution in transfer-based few-shot learning. *arXiv preprint arXiv:2006.03806*, 2020.

[2] P. A. Knight. The Sinkhorn-Knopp algorithm: convergence and applications. *SIAM Journal on Matrix Analysis and Applications*, 2008.

[3] Y. Wang, C. Xu, C. Liu, L. Zhang, and Y. Fu. Instance credibility inference for few-shot learning. *CVPR*, 2020.