

## Background

- ▶ **Transductive few-shot learning:** Labeled support examples and unlabeled queries are all available at test time.
- ▶ Main lines of research include class centroid approaches and data manifold approaches.
- ▶ Transductive few-shot learning benchmarks use perfectly class-balanced tasks.
- ▶ **Problem:** Several methods exploit this bias by encouraging class-balanced predictions.
- ▶ We investigate the more realistic imbalanced transductive few-shot learning setting where the number of queries per class is different.
- ▶ **Contributions:** Propose a novel algorithm that combines the merits of both class centroid and data manifold approaches named (*AM*).
- ▶ New state of the art performance on the imbalanced transductive few-shot setting.
- ▶ On par or even outperform many state of the art methods in the standard balanced transductive few-shot setting.

## Problem definition

### Pre-training:

- ▶ We use publicly available pre-trained networks from published works.
- ▶ Base class dataset:  $D_{\text{base}} := \{(x_i, y_i)\}_{i=1}^I$  where  $y_i \in C_{\text{base}}$ .
- ▶ Network  $f_\theta : \mathcal{X} \rightarrow \mathbb{R}^d$  is trained on  $D_{\text{base}}$ .

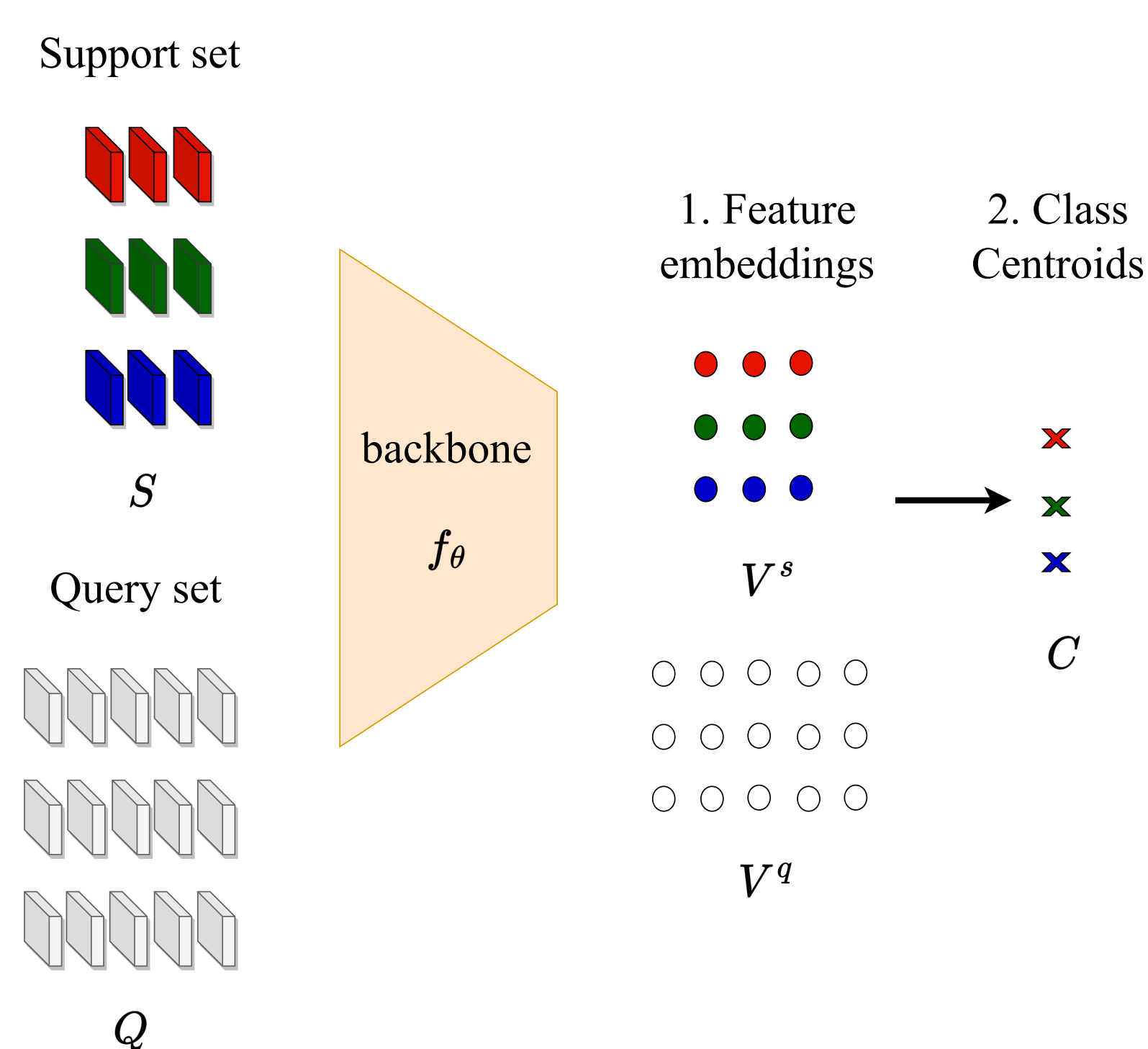
### Inference stage

- ▶ Novel class dataset  $D_{\text{novel}}$  with  $C_{\text{novel}}$  disjoint from  $C_{\text{base}}$ .
- ▶ Assume access to  $f_\theta$ , a support set,  $S$ , a query set,  $Q$ .
- ▶ We focus on imbalanced transductive few-shot learning.

## Manifold Centroids

- ▶ Embed all examples from  $S$  and  $Q$  into feature vectors and  $\ell_1$ -normalize them.
- ▶ Calculate the manifold class centroids using the labeled support vectors of every class. For class  $j$  the manifold centroid is:

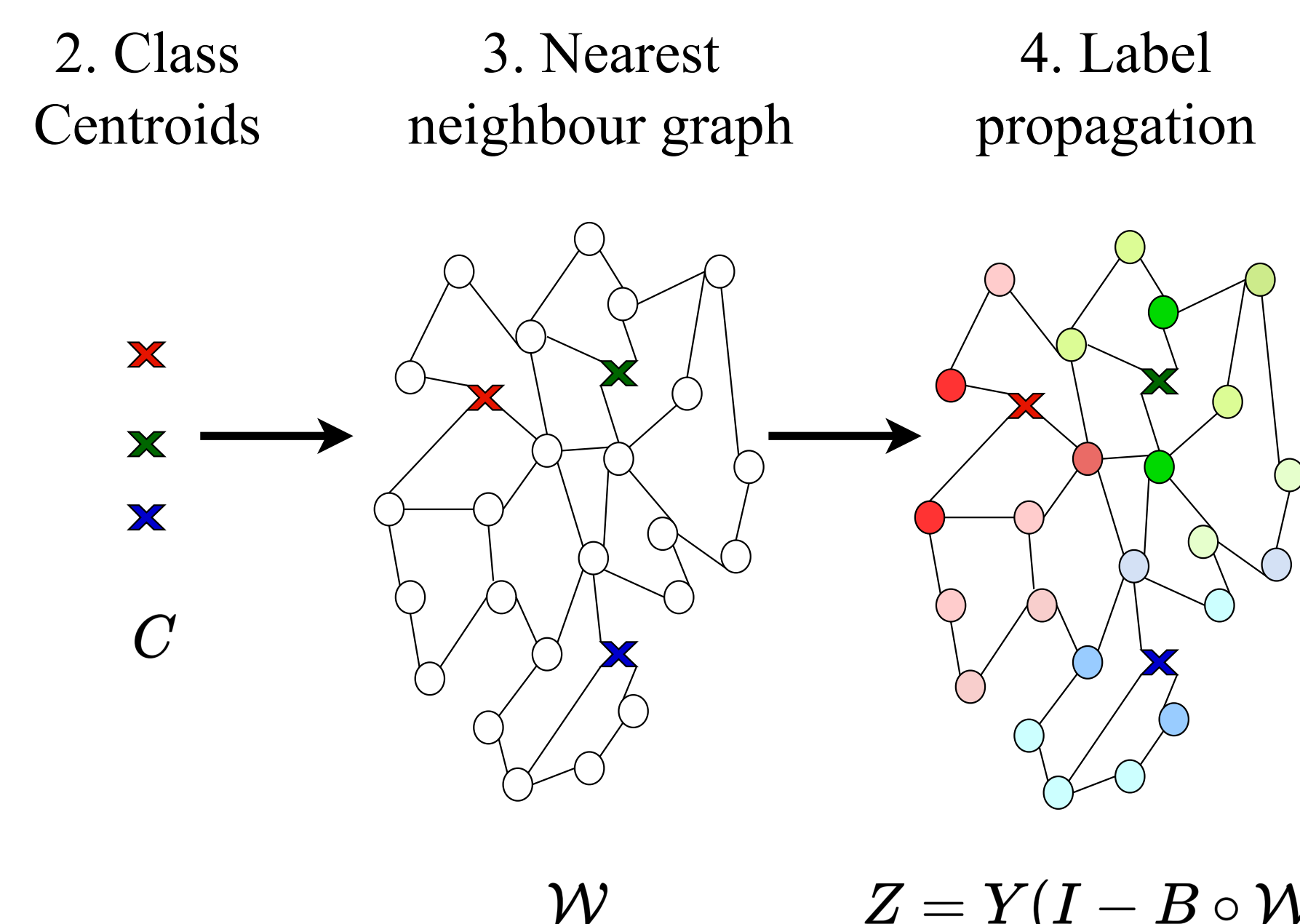
$$c_j = \frac{1}{K} \sum_{v_i^s \in \mathcal{V}^s} y_{ji}^s v_i^s \quad (1)$$



## Label propagation

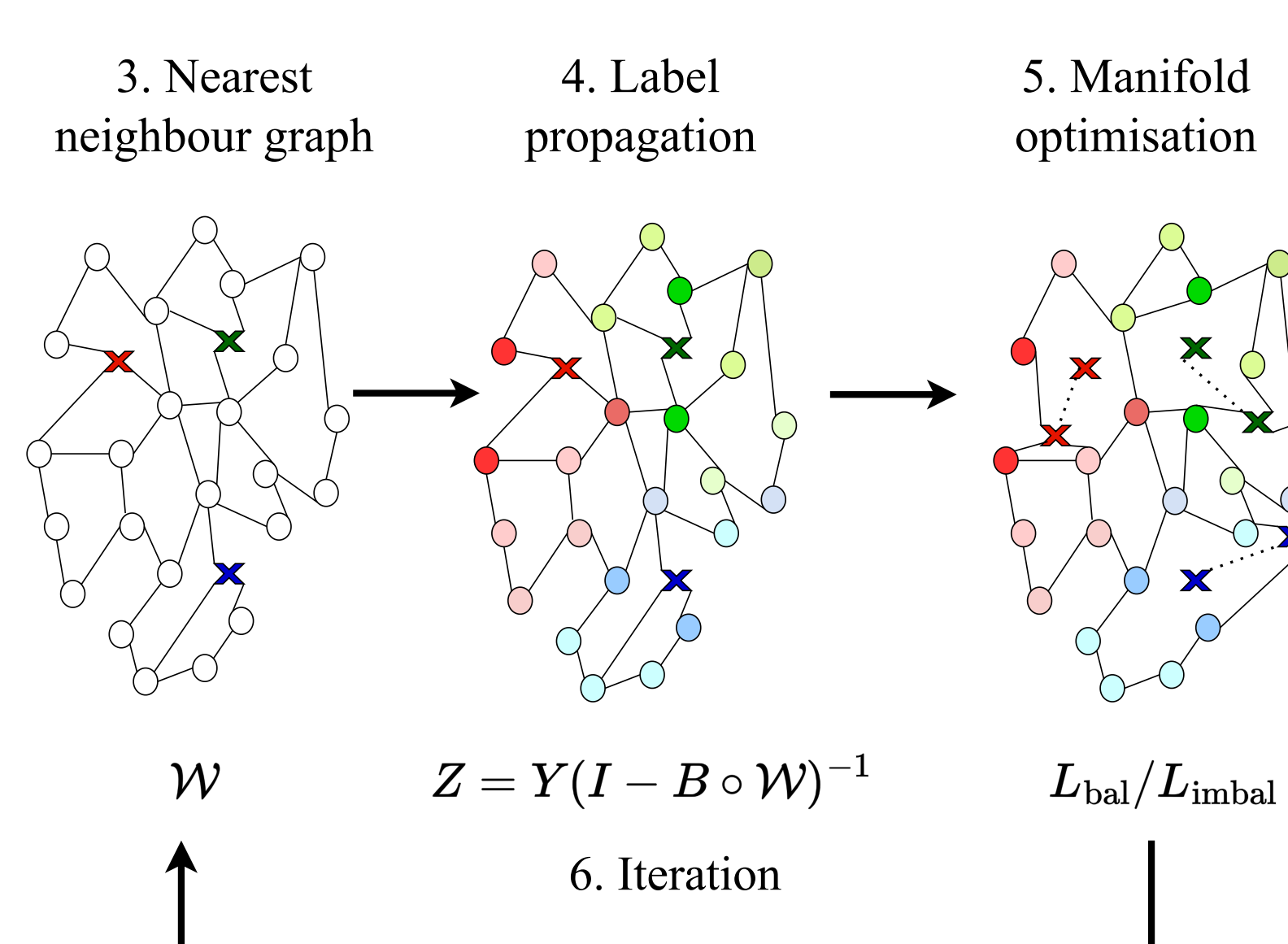
- ▶ Construct  $k$ -nearest neighbour graph, and obtain its adjacency matrix  $\mathcal{W}$ .
- ▶ Define the *label matrix*  $Y$ .
- ▶ Label propagation to obtain a class probability distribution for every query

$$Z := (I - \alpha \mathcal{W})^{-1} Y. \quad (2)$$



## Manifold Adaptation

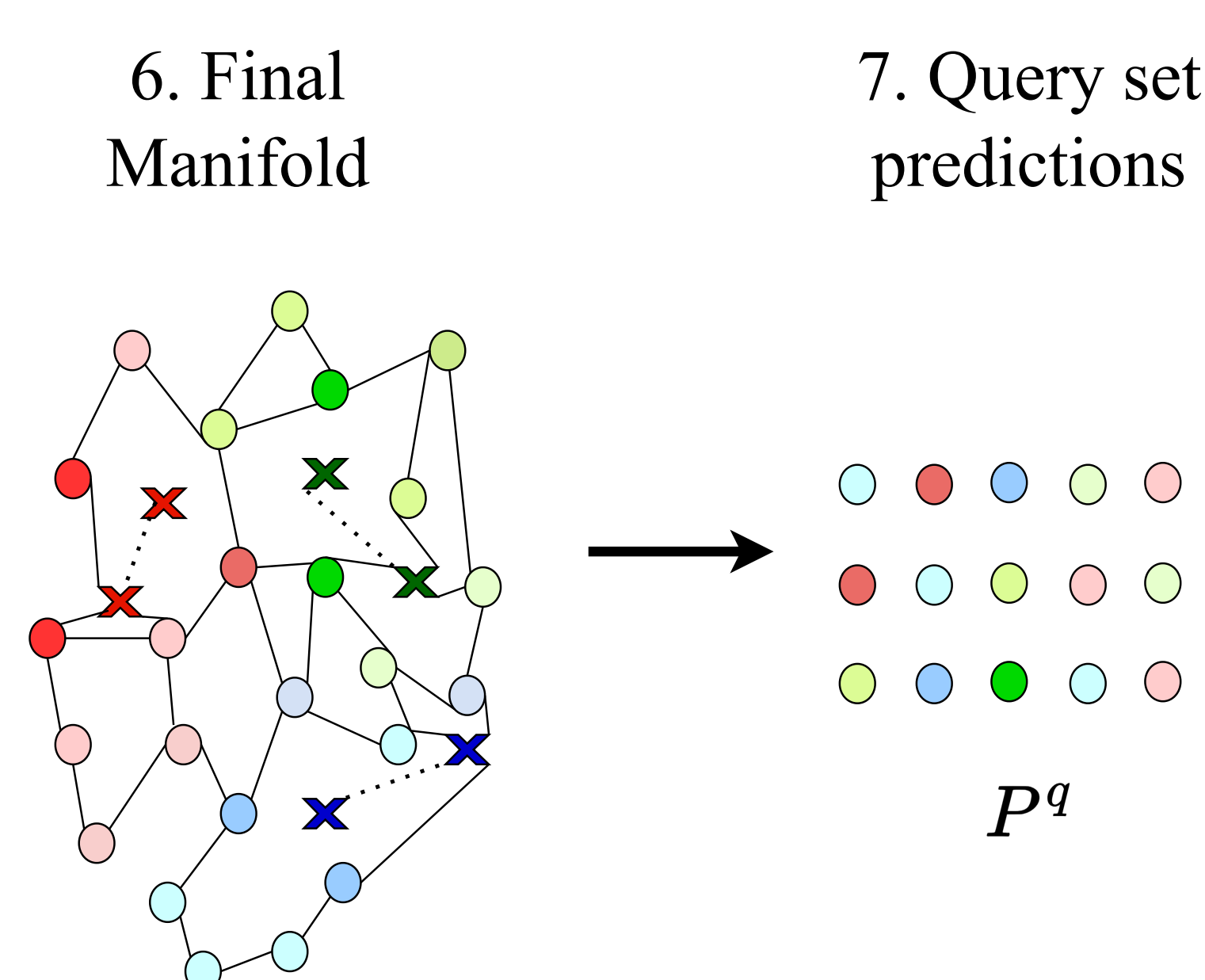
- ▶ Iteratively adapt the manifold centroids along with the manifold parameters using either the balanced or imbalanced loss function proposed by [1].



## Query set predictions

- ▶ Exploit the final Manifold to make predictions about the queries in the query set  $Q$ .
- ▶ Every query is classified to the class with the highest manifold similarity.

$$\hat{y}_i^q = \arg \max_j p_{ji}^q \quad (3)$$



## Implementation details

- ▶ Our Implementation is based on PyTorch.

## Ablation study

Table: Ablation study of algorithmic components of both balanced and imbalanced versions of our method AM on *minImageNet*.  $NN_k$ :  $k$ -nearest neighbour graph; otherwise, complete graph.  $C$ : learnable class centroids.  $G$ : learnable pairwise scaling factors  $G$ .  $B$ : learnable adjacency matrix  $B$ . PLC: feature pre-processing.

COMPONENTS	IMBALANCED				BALANCED			
	RESNET-18	WRN-28-10	RESNET-18	WRN-28-10				
$NN_k$	1-shot	5-shot	1-shot	5-shot	1-shot	5-shot	1-shot	5-shot
✓	60.21±0.27	74.24±0.21	63.34±0.27	76.19±0.21	59.09±0.21	71.54±0.19	62.38±0.21	73.46±0.19
✓	63.95±0.27	81.15±0.17	67.14±0.27	83.40±0.16	63.82±0.22	80.47±0.15	67.22±0.21	82.58±0.16
✓ ✓	68.57±0.28	82.69±0.16	71.22±0.26	84.74±0.16	73.43±0.23	84.37±0.14	75.94±0.22	86.55±0.13
✓ ✓ ✓	70.16±0.29	82.62±0.17	72.89±0.28	84.89±0.16	75.59±0.27	84.80±0.15	78.72±0.25	87.11±0.13
✓ ✓ ✓ ✓	69.11±0.29	82.97±0.16	71.64±0.28	85.16±0.15	74.85±0.25	84.66±0.14	77.70±0.23	86.91±0.13
✓ ✓ ✓ ✓ ✓	<b>70.24</b> ±0.29	82.71±0.17	<b>73.22</b> ±0.29	85.00±0.16	76.06±0.28	84.82±0.15	79.37±0.26	87.12±0.13
✓ ✓ ✓ ✓ ✓ ✓	69.97±0.29	<b>83.31</b> ±0.17	71.98±0.29	<b>85.66</b> ±0.15	<b>77.35</b> ±0.27	<b>85.47</b> ±0.14	<b>80.99</b> ±0.28	<b>87.86</b> ±0.13

## State of the art comparisons

### Imbalanced transductive:

Table: The results are reported from  $\alpha$ -TIM. Our reproduction of the imbalanced ProtoLP used the official code.

METHOD	<i>minImageNet</i>		<i>tieredImageNet</i>	
	1-shot	5-shot	1-shot	5-shot
RESNET-18				
PT-MAP	60.10	67.10	64.10	70.00
LaplacianShot	65.40	81.60	72.30	85.70
BD-CSPN	67.00	80.20	74.10	84.80
ProtoLP	65.42	78.48	71.12	82.51
TIM	67.30	79.80	74.10	84.10
$\alpha$ -TIM	67.40	82.50	74.40	86.60
$\alpha$ -TIM <sub>PLC</sub>	63.38	82.80	70.17	86.82
$\alpha$ -AM	<b>70.24</b>	82.71	<b>77.28</b>	86.97
$\alpha$ -AM <sub>PLC</sub>	69.97	<b>83.31</b>	76.44	<b>87.19</b>

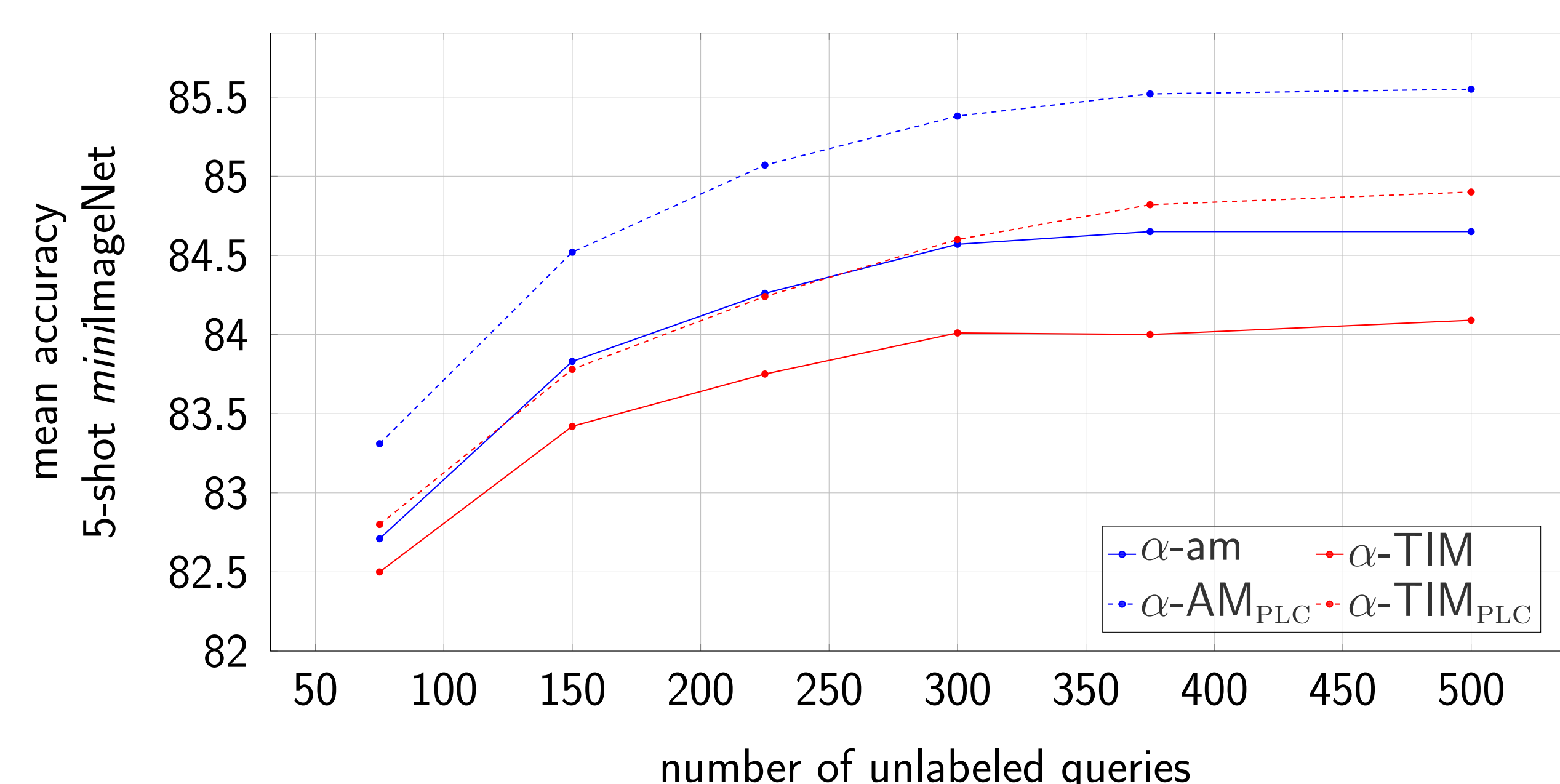
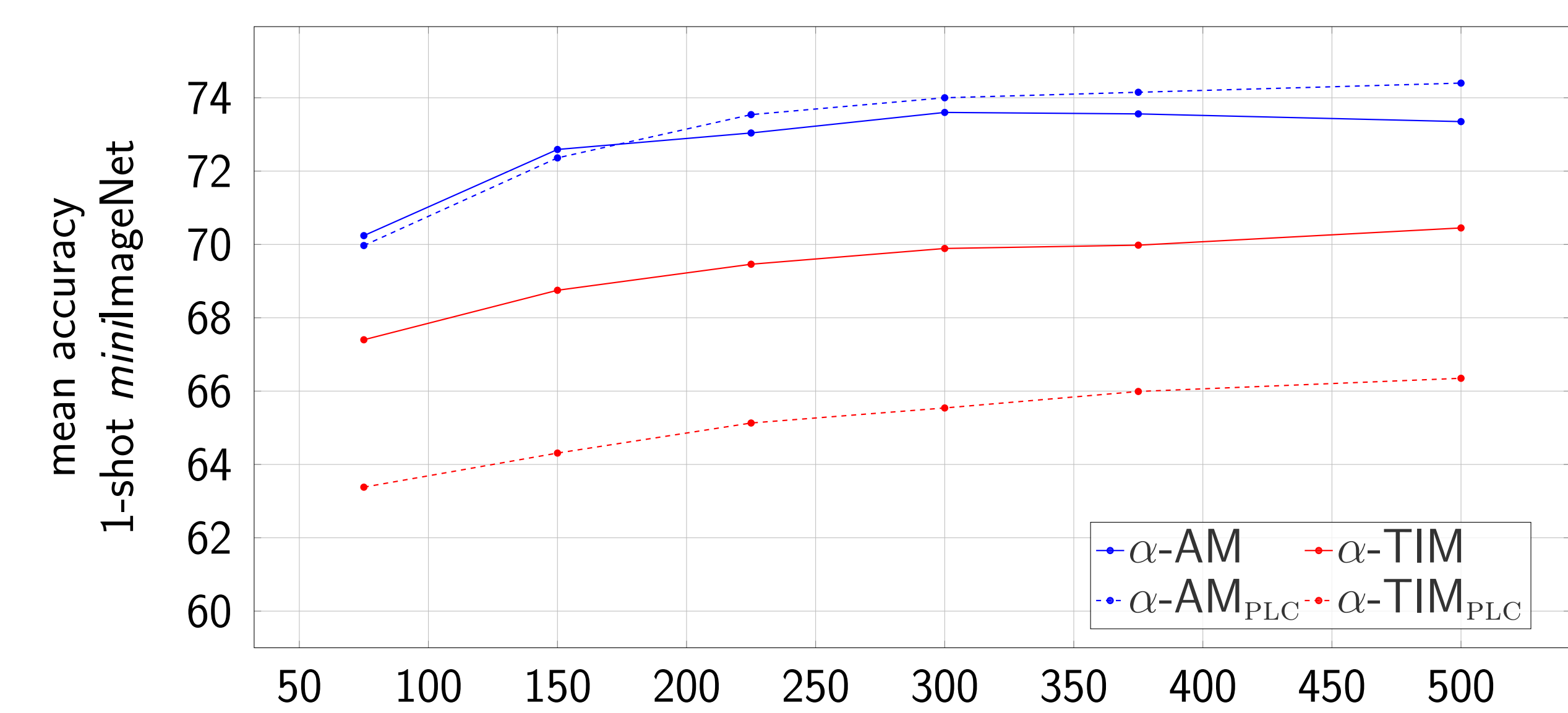
### Balanced transductive:

Table: All results were reproduced using the official code provided by  $\alpha$ -TIM. †: Our reproduction using the official code of protoLP.

METHOD	<i>minImageNet</i>		<i>tieredImageNet</i>	
	1-shot	5-shot	1-shot	5-shot
RESNET-18				
LaplacianShot	70.24	82.10	77.28	86.22
BD-CSPN	69.36	82.06	76.36	86.18
PT-MAP	76.88	85.18	82.89	88.64
protoLP†	76.96	84.90	83.06	88.55
TIM	73.81	84.91	80.13	88.61
TIM <sub>PLC</sub>	69.33	84.53	76.36	88.33
AM	76.06	84.82	82.42	88.61
AM <sub>PLC</sub>	<b>77.35</b>	<b>85.47</b>	<b>83.40</b>	<b>89.07</b>

## Using more unlabeled examples

Effect of number of unlabeled queries  $M$  on  $\alpha$ -LPC and  $\alpha$ -TIM using ResNet-18.



- ▶ The performance gap tends to increase as the number of unlabeled queries increase.
- ▶  $\alpha$ -AM Exploits the data manifold through the  $k$ -nearest neighbour graph while  $\alpha$ -TIM works in Euclidean space.